

# Problem Sheet on Convex Optimisation

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1. Show that the following functions are convex:

(a)  $f(x) = |x|, x \in \mathbb{R}$ .

(b)  $f(x) = x \log x, x \in (0, \infty)$ . Logarithms are natural unless otherwise specified.

(c)  $f(x) = x^2 y^2, (x, y) \in \mathbb{R}^2$ .

(d)  $f(\mathbf{x}) = \|\mathbf{A}\mathbf{x} - \mathbf{b}\|^2, \mathbf{x} \in \mathbb{R}^n$ , where  $\mathbf{A}$  is an  $m \times n$  matrix,  $\mathbf{b} \in \mathbb{R}^m$ , and  $\|\cdot\|$  denotes the Euclidean norm of a vector. In order to show that  $f$  is convex, you may need to show that a certain matrix is positive semi-definite.

(e)  $f(x) = \begin{cases} x, & x > 0, \\ y, & x = 0, \\ +\infty, & x < 0, \end{cases}$  where  $y \geq 0$  is arbitrary.

2. (a) Let  $\mathbb{S}$  denote the set of all real symmetric  $n \times n$  matrices. Show that  $\mathbb{S}$  is a convex subset of  $\mathbb{R}^{n \times n}$ .

(b) Recall that all eigenvalues of a symmetric matrix are real. Hence, they can be ordered from largest to smallest. Let  $\lambda_{\max}(A)$  denote the largest eigenvalue of the real symmetric matrix  $A$ . Let  $f : \mathbb{S} \rightarrow \mathbb{R}$  be defined by  $f(A) = \lambda_{\max}(A)$ . Show that  $f$  is a convex function.

*Hint.* Use the Rayleigh-Ritz formula, which states that

$$\lambda_{\max}(A) = \max_{\mathbf{x} \neq \mathbf{0}} \frac{\mathbf{x}^T \mathbf{A} \mathbf{x}}{\mathbf{x}^T \mathbf{x}} = \max_{\|\mathbf{x}\|=1} \mathbf{x}^T \mathbf{A} \mathbf{x}.$$

3. Let  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  be a convex function, and let  $C$  be a convex subset of  $\mathbb{R}$ . Define  $g : \mathbb{R} \rightarrow \mathbb{R}$  by

$$g(x) = \min_{y \in C} f(x, y).$$

Show that  $g$  is a convex function.

*Hint.* Start from the definition of convexity. Pick  $x_0$  and  $x_1$  in  $\mathbb{R}$ ,  $\alpha \in [0, 1]$  and define  $x_\alpha = (1 - \alpha)x_0 + \alpha x_1$ . Suppose that the minimum in the definition of  $g(x_0)$  (respectively  $g(x_1), g(x_\alpha)$ ) is attained at  $y_0 \in C$  (respectively at  $y_1, y^\alpha$ ). The use of the superscript for  $y^\alpha$  is to make it clear that no assumption is made about the value of  $y^\alpha$ , beyond that it is in  $C$ ; specifically,  $y^\alpha$  need not be equal to  $y_\alpha = (1 - \alpha)y_0 + \alpha y_1$ .

4. (a) The linear regression problem in statistics has data in the form of an  $n \times p$  matrix  $X$  of  $n$  observations of  $p$  independent variables, and a  $n \times 1$  matrix (i.e. a column vector of length  $n$ )  $\mathbf{y}$  of observations of a single dependent variable. The objective is to find a  $p$ -vector of coefficients  $\beta$  so as to solve the following least-squares problem:

$$\min_{\beta \in \mathbb{R}^p} f(\beta) := \|X\beta - \mathbf{y}\|^2,$$

where, as usual,  $\|\mathbf{z}\|$  denotes the Euclidean norm of the vector  $\mathbf{z}$ ; recall that  $\|\mathbf{z}\|^2 = \mathbf{z}^T \mathbf{z}$ .

- i. Show that  $f : \mathbb{R} \rightarrow \mathbb{R}$  is a convex function. You may need to show that a certain matrix is positive semi-definite.
  - ii. Use the first order sufficient condition for unconstrained optimisation to find the optimal  $\beta$ . You may assume that the matrix  $X^T X$  is full rank (hence invertible).
- (b) Linear regression works well in practice when the number of observations  $n$  is much bigger than the number of variables  $p$ . In many “Big Data” problems, this is not the case. Often  $p$  is close to  $n$  in size, which can result in overfitting (finding spurious statistically significant dependencies just be chance), or  $p$  can even be bigger than  $n$ , in which case the least squares problem doesn’t have a unique solution for  $\beta$ . One approach to dealing with such problems is to assume that  $\beta$  is sparse, i.e., that it has few non-zero coefficients. Often, there is good intuitive justification for this assumption. This motivates us to try and solve the least squares problem with a sparsity constraint (constraint on the number of non-zero elements in  $\beta$ ). However, this problem is non-convex and, consequently, intractable. Instead, a common approach is to consider a “convex relaxation” of this problem.

LASSO, or  $\ell_1$ -penalised least squares, seeks to solve the following modification of the least-squares optimisation problem:

$$\min_{\beta \in \mathbb{R}^p} g(\beta) := \|X\beta - \mathbf{y}\|^2 + \lambda \|\beta\|_1, \quad \text{where } \|\beta\|_1 := \sum_{i=1}^p |\beta_i| \text{ and } \lambda > 0.$$

The quantity  $\|\beta\|_1$  is called the  $\ell_1$  norm of  $\beta$ , and is simple the sum of the absolute values of its co-ordinates. The constant  $\lambda > 0$  is the penalty on the  $\ell_1$  norm, and trades off between how accurately we want to fit the data (the first term in  $g$ ), and how much we penalise large values of  $\beta$ , as measured by its  $\ell_1$  norm.

Show that  $g$  is a convex function. You may use answers to previous questions to save yourself some work.

5. A quadratic programming (QP) problem involves the minimisation of a quadratic function subject to linear constraints. The general form is:

$$\min_{\mathbf{x} \in \mathbb{R}^n} \frac{1}{2} \mathbf{x}^T Q \mathbf{x} + \mathbf{c}^T \mathbf{x} \text{ subject to } A \mathbf{x} \leq \mathbf{b}.$$

Here,  $Q$  is a real symmetric  $n \times n$  matrix,  $\mathbf{c} \in \mathbb{R}^n$ ,  $A \in \mathbb{R}^{m \times n}$  and  $\mathbf{b} \in \mathbb{R}^m$ ; inequalities between vectors are to be interpreted to hold for each coordinate.

- (a) Suppose  $Q$  is positive semi-definite. Then show that the QP is a convex optimisation problem, i.e., that the objective function is convex, and that the set of  $\mathbf{x} \in \mathbb{R}^n$  satisfying the constraints is a convex set.
- (b) Write down the Lagrangian for the problem, and formulate the dual problem.
- (c) Write down the KKT conditions for optimality.
- (d) Starting from an initial value  $\mathbf{x}^0$  for the unconstrained version of the above problem, compute the value  $\mathbf{x}^1$  you would obtain after one iteration of gradient descent with exact line search.

Do the same for one step of the Newton method, assuming  $Q$  is positive definite, and hence invertible.

What is the exact solution to the minimisation problem in this case (still unconstrained)?