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5 November 2013

Ashley Montanaro ashley@cs.bris.ac.uk COMS21103: All-pairs shortest paths



Slide 1/22

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Today: algorithms for general graphs with better runtimes than this.

- The Floyd-Warshall algorithm: time $O(V^3)$.
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Assume for simplicity that the input graph has no negative-weight cycles.

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In the Floyd-Warshall algorithm, we assume we are given access to a graph G with n vertices as a n × n adjacency matrix W. The weights of the edges in G are represented as follows:

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We use the optimal substructure property of shortest paths (the triangle inequality) to write down a dynamic programming recurrence.



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- ▶ If there is no shortest path from *i* to *j* of this form, then $d_{ii}^{(k)} = \infty$.



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- ▶ If there is no shortest path from *i* to *j* of this form, then $d_{ii}^{(k)} = \infty$.
- In the case $k = 0, d_{ii}^{(0)} = W_{ij}$.
- On the other hand, for k = n, $d_{ij}^{(n)} = \delta(i, j)$.



Let *p* be a shortest (i.e. minimum-weight) path from *i* to *j* with all intermediate vertices in the set $\{1, ..., k\}$.

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Let *p* be a shortest (i.e. minimum-weight) path from *i* to *j* with all intermediate vertices in the set $\{1, ..., k\}$. Then observe that:

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We therefore have the following recurrence for $d_{ii}^{(k)}$:

$$d_{ij}^{(k)} = \begin{cases} W_{ij} & \text{if } k = 0\\ \min\left\{d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)}\right\} & \text{if } k \ge 1. \end{cases}$$

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The Floyd-Warshall algorithm

Based on the above recurrence, we can give the following bottom-up algorithm for computing $d_{ii}^{(n)}$ for all pairs *i*, *j*.

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Based on the above recurrence, we can give the following bottom-up algorithm for computing $d_{ii}^{(n)}$ for all pairs *i*, *j*.

FloydWarshall(W)

1. $d^{(0)} \leftarrow W$ 2. for k = 1 to n3. for i = 1 to n4. for j = 1 to n5. $d^{(k)}_{ij} \leftarrow \min(d^{(k-1)}_{ij}, d^{(k-1)}_{ik} + d^{(k-1)}_{kj})$ 6. return $d^{(n)}$.



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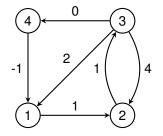
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- 1. $d^{(0)} \leftarrow W$ 2. for k = 1 to n3. for i = 1 to n4. for j = 1 to n5. $d_{ij}^{(k)} \leftarrow \min(d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)})$ 6. return $d^{(n)}$.
 - The time complexity is clearly $O(n^3)$ and the algorithm is very simple.
 - Correctness follows from the argument on the previous slide.

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Consider the following graph and its corresponding adjacency matrix:



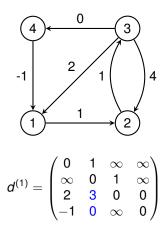
(0	1	∞	∞
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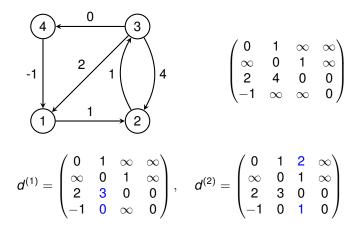
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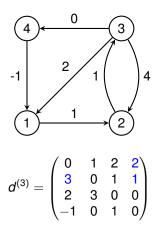
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Consider the following graph and its corresponding adjacency matrix:



 $\begin{pmatrix} \mathbf{0} & \mathbf{1} & \infty & \infty \\ \infty & \mathbf{0} & \mathbf{1} & \infty \\ \mathbf{2} & \mathbf{4} & \mathbf{0} & \mathbf{0} \\ -\mathbf{1} & \infty & \infty & \mathbf{0} \end{pmatrix}$

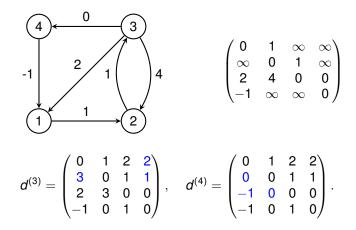
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- ▶ We can do this in a similar way to computing the distance matrix. We define a sequence of matrices $\Pi^{(0)}, \ldots, \Pi^{(n)}$ such that $\Pi_{ij}^{(k)}$ is the predecessor of *j* in a shortest path from *i* to *j* only using vertices in the set $\{1, \ldots, k\}$.



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- Then, for k = 0,

$$\Pi_{ij}^{(0)} = \begin{cases} \text{nil} & \text{if } i = j \text{ or } W_{ij} = \infty \\ i & \text{if } i \neq j \text{ and } W_{ij} \neq \infty. \end{cases}$$



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For $k \ge 1$, we have essentially the same recurrence as for $d^{(k)}$. Formally,

$$\Pi_{ij}^{(k)} = \begin{cases} \Pi_{ij}^{(k-1)} & \text{if } d_{ij}^{(k-1)} \leq d_{ik}^{(k-1)} + d_{kj}^{(k-1)} \\ \Pi_{kj}^{(k-1)} & \text{otherwise.} \end{cases}$$

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The Floyd-Warshall algorithm with predecessors

FloydWarshall(W)

1.
$$d^{(0)} \leftarrow W$$

2. for $k = 1$ to n
3. for $i = 1$ to n
4. for $j = 1$ to n
5. if $d_{ij}^{(k-1)} \leq d_{ik}^{(k-1)} + d_{kj}^{(k-1)}$
6. $d_{ij}^{(k)} \leftarrow d_{ij}^{(k-1)}$
7. $\Pi_{ij}^{(k)} \leftarrow \Pi_{ij}^{(k-1)}$
8. else
9. $d_{ij}^{(k)} \leftarrow d_{ik}^{(k-1)} + d_{kj}^{(k-1)}$
10. $\Pi_{ij}^{(k)} \leftarrow \Pi_{kj}^{(k-1)}$

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Johnson's algorithm

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- Johnson's algorithm uses Dijkstra's algorithm to solve the all-pairs shortest paths problem for graphs which may have negative-weight edges. It is based around the idea of first reweighting G so that all the weights are non-negative, then using Dijkstra.



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- ► For sparse graphs, its complexity $O(VE + V^2 \log V)$ (the same as Dijkstra) is faster than the Floyd-Warshall algorithm.



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- Johnson's algorithm uses Dijkstra's algorithm to solve the all-pairs shortest paths problem for graphs which may have negative-weight edges. It is based around the idea of first reweighting G so that all the weights are non-negative, then using Dijkstra.
- ► For sparse graphs, its complexity $O(VE + V^2 \log V)$ (the same as Dijkstra) is faster than the Floyd-Warshall algorithm.
- We assume that we are given G as an adjacency list, and have access to a weight function w(u, v) which tells us the weight of the edge u → v.

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For any edge $u \rightarrow v$, define

$$\widehat{w}(u,v) := w(u,v) + h(u) - h(v),$$

where *h* is an arbitrary function mapping vertices to real numbers. Then any path $p = v_0, \ldots, v_k$ is a shortest path from v_0 to v_k with respect to the weight function \hat{w} if and only if it is a shortest path with respect to the weight function *w*.



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Proof

The total weights of p under \hat{w} and w are closely related:

$$\sum_{i=1}^{k} \widehat{w}(v_{i-1}, v_i) = \sum_{i=1}^{k} w(v_{i-1}, v_i) + h(v_{i-1}) - h(v_i)$$

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$$= h(v_0) - h(v_k) + \sum_{i=1}^{k} w(v_{i-1}, v_i)$$

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Negative-weight cycles

Claim

A graph has a negative-weight cycle under weight function \hat{w} if and only if if has one under weight function w.

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• Let $c = v_0, \ldots, v_k$, where $v_0 = v_k$, be any cycle.

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Given a graph G, to define our new weight function, we add a new vertex s which has an edge of weight 0 to all other vertices in G.



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- We then define $h(v) = \delta(s, v)$ for all vertices v in G.



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- ▶ So, if we reweight according to the function *h*,

$$\widehat{w}(u,v) = w(u,v) + h(u) - h(v) \geq 0$$

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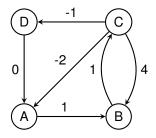
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► Then, if $\hat{\delta}(u, v)$ is the weight of a shortest path from *u* to *v* with weight function \hat{w} , $\delta(u, v) = \hat{\delta}(u, v) + h(v) - h(u)$.



Imagine we want to reweight the following graph:

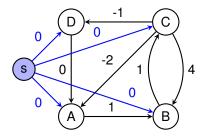


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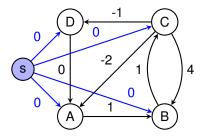


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Using Bellman-Ford, we compute

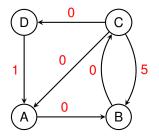
 $h(A) = -2, \quad h(B) = -1, \quad h(C) = 0, \quad h(D) = -1.$

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Reweighting according to *h* gives the following graph:

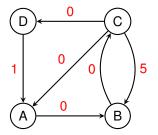


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Reweighting according to *h* gives the following graph:



► For each pair of vertices $u, v, \delta(u, v) = \hat{\delta}(u, v) + h(v) - h(u)$.

▶ For example, $\delta(C, A) = 0 - 2 - 0 = -2$ as expected.

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From the above discussion, we can write down the following algorithm.

Johnson(G)

1. form a new graph G' by adding s to G, as defined above

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From the above discussion, we can write down the following algorithm.

Johnson(G)

- 1. form a new graph G' by adding s to G, as defined above
- 2. compute $\delta(s, v)$ for all $v \in G$ using BellmanFord



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- 3. for each edge $u \rightarrow v$ in G

4.
$$\widehat{w}(u, v) \leftarrow w(u, v) + \delta(s, u) - \delta(s, v)$$

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$$\widehat{w}(u, v) \leftarrow w(u, v) + \delta(s, u) - \delta(s, v)$$

- 5. for each vertex $u \in G$
- 6. compute $\hat{\delta}(u, v)$ for all v using Dijkstra
- 7. for each vertex $v \in G$

8.
$$d_{uv} \leftarrow \widehat{\delta}(u, v) + \delta(s, v) - \delta(s, u)$$

9. return d

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 Both algorithms work for graphs which may have negative-weight edges.



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- The runtime of Johnson's algorithm is dominated by the complexity of running Dijkstra's algorithm once for each vertex, which is O(VE + V² log V) if implemented using a Fibonacci heap, and O(VE log V) if implemented using a binary heap.
- This can be significantly smaller than the runtime of the Floyd-Warshall algorithm if the input graph is sparse.



Shortest path algorithms: the summary

To compute single-source shortest paths in a directed graph G which is...

- unweighted: use breadth-first search in time O(V + E);
- ▶ weighted with non-negative weights: use Dijkstra's algorithm in time O(E + V log V);
- ▶ weighted with negative weights: use Bellman-Ford in time O(VE).



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- ▶ weighted with negative weights: use Bellman-Ford in time O(VE).

To compute all-pairs shortest paths in a directed graph G which is...

- unweighted: use breadth-first search from each vertex in time O(VE + V²);
- weighted with non-negative weights: use Dijkstra's algorithm from each vertex in time O(VE + V² log V);
- ► weighted with negative weights: use Johnson's algorithm in time O(VE + V² log V).



Further Reading

Introduction to Algorithms

T.H. Cormen, C.E. Leiserson, R.L. Rivest and C. Stein. MIT Press/McGraw-Hill, ISBN: 0-262-03293-7.

Chapter 25 – All-Pairs Shortest Paths

Algorithms lecture notes, University of Illinois Jeff Erickson

http://www.cs.uiuc.edu/~jeffe/teaching/algorithms/

Lecture 20 – All-pairs shortest paths



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Biographical notes

The Floyd-Warshall algorithm was invented independently by Floyd and Warshall (and also Bernard Roy).

Robert W. Floyd (1936-2001)

- American computer scientist who did major work on compilers and initiated the field of programming language semantics.
- He completed his first degree (in liberal arts) at the age of 17 and won the Turing Award in 1978.
- Had his middle name legally changed to "W".



Pic: IEEE



Biographical notes

Stephen Warshall (1935–2006)

- Another American computer scientist whose other work included operating systems and compiler design.
- Supposedly he and a colleague bet a bottle of rum on who could first prove correctness of his algorithm.
- Warshall found his proof overnight and won the bet (and the rum).

Donald B. Johnson (d. 1994)

 Yet another American computer scientist. Founded the computer science department at Dartmouth College and invented the *d*-ary heap.

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