

Turing machines (continued)

Ashley Montanaro

ashley@cs.bris.ac.uk

Department of Computer Science, University of Bristol Bristol, UK

28 March 2014

Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Slide 1/28

Introduction

 We have seen an introduction to Turing machines and how they are defined.

Today: More about what they can do, and some other models which are equivalent to the Turing machine.



Slide 2/28

We can distinguish several different levels of formality when describing a Turing machine:



Slide 3/28

We can distinguish several different levels of formality when describing a Turing machine:

A formal description is the complete details of the states and transition function of the machine, specified via a transition diagram or a formal mathematical description.



We can distinguish several different levels of formality when describing a Turing machine:

- A formal description is the complete details of the states and transition function of the machine, specified via a transition diagram or a formal mathematical description.
- An implementation description is a higher-level description where the operation of the machine is described in English text. However, enough details are provided to be able to derive the formal description with no additional ideas.



We can distinguish several different levels of formality when describing a Turing machine:

- A formal description is the complete details of the states and transition function of the machine, specified via a transition diagram or a formal mathematical description.
- An implementation description is a higher-level description where the operation of the machine is described in English text. However, enough details are provided to be able to derive the formal description with no additional ideas.
- A high-level description describes the operation of the machine informally without mentioning the details of how it operates on the tape.



We can distinguish several different levels of formality when describing a Turing machine:

- A formal description is the complete details of the states and transition function of the machine, specified via a transition diagram or a formal mathematical description.
- An implementation description is a higher-level description where the operation of the machine is described in English text. However, enough details are provided to be able to derive the formal description with no additional ideas.
- A high-level description describes the operation of the machine informally without mentioning the details of how it operates on the tape.

For the remainder of the unit, we will use implementation or high-level descriptions of Turing machines.

Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



We can distinguish several different levels of formality when describing a Turing machine:

- A formal description is the complete details of the states and transition function of the machine, specified via a transition diagram or a formal mathematical description.
- An implementation description is a higher-level description where the operation of the machine is described in English text. However, enough details are provided to be able to derive the formal description with no additional ideas.
- A high-level description describes the operation of the machine informally without mentioning the details of how it operates on the tape.

For the remainder of the unit, we will use implementation or high-level descriptions of Turing machines.

Unless otherwise specified, if you are asked to describe a Turing machine, the implementation description is the right level to pick.

Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Encodings

We will often want to encode the objects on which a Turing machine operates.

- ► Given an object O, we write its representation as a string of symbols in some alphabet as (O).
- Each object has many different representations; we just pick a "reasonable" one.



Encodings

We will often want to encode the objects on which a Turing machine operates.

- ► Given an object O, we write its representation as a string of symbols in some alphabet as (O).
- Each object has many different representations; we just pick a "reasonable" one.

Some examples:

▶ $n \in \mathbb{N}$: we can write *n* as a binary string, e.g. $\langle 5 \rangle = 101$.



Encodings

We will often want to encode the objects on which a Turing machine operates.

- ► Given an object O, we write its representation as a string of symbols in some alphabet as (O).
- Each object has many different representations; we just pick a "reasonable" one.

Some examples:

- ▶ $n \in \mathbb{N}$: we can write *n* as a binary string, e.g. $\langle 5 \rangle = 101$.
- If G is a graph: we could write its adjacency matrix in binary, with commas between the rows, e.g. for



$$\langle {\it G}
angle =$$
 010,101,000

Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Computing using a Turing machine

Turing machines can be used to solve more than decision problems.

- We can generalise the notion of Turing machines slightly by allowing the machine to output data.
- ► We can introduce a state q_{halt} such that, if the machine reaches state q_{halt}, it stops and outputs the contents of its tape.





Computing using a Turing machine

Turing machines can be used to solve more than decision problems.

- We can generalise the notion of Turing machines slightly by allowing the machine to output data.
- ► We can introduce a state q_{halt} such that, if the machine reaches state q_{halt}, it stops and outputs the contents of its tape.



This allows us to implement general algorithms on a Turing machine.

- ► A Turing machine can be seen as computing a mathematical function *f*(*x*) of its input *x*.
- If a function can be computed by a Turing machine, we call it computable.

Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Slide 5/28

The Church-Turing thesis

We have seen that Turing machines are more powerful than PDAs. How much more powerful?



Slide 6/28

The Church-Turing thesis

We have seen that Turing machines are more powerful than PDAs. How much more powerful?

Church-Turing thesis

Everything which can be computed can be computed by a Turing machine.



The Church-Turing thesis

We have seen that Turing machines are more powerful than PDAs. How much more powerful?

Church-Turing thesis

Everything which can be computed can be computed by a Turing machine.

- This claim can be interpreted as saying that the Turing machine formalises our intuitive notion of what an algorithm is.
- ▶ NB: the Church-Turing thesis is unproven!
- It is a claim about physical reality: that anything we can compute in our physical universe can be computed by a Turing machine.



So why study Turing machines?



Pic: abstrusegoose.com

Because they give us a formal basis for understanding computation.

Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Slide 7/28

Evidence for the Church-Turing thesis

One way in which we can strengthen our intuition that the C-T thesis is true: Consider computational models which are apparently stronger than TMs, and show that they can be simulated by TMs.



Slide 8/28

Evidence for the Church-Turing thesis

- One way in which we can strengthen our intuition that the C-T thesis is true: Consider computational models which are apparently stronger than TMs, and show that they can be simulated by TMs.
- ► The first of these models: the multitape Turing machine.



Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Slide 8/28

Multitape Turing machines

A *k*-tape Turing machine *M* is defined as follows.

- M has access to k tapes, each with its own head for reading and writing.
- The input is initially placed at the left end of tape 1; the other tapes are blank.
- The transition function is now of the form

$$\delta: \boldsymbol{Q} \times \boldsymbol{\Gamma}^{k} \to \boldsymbol{Q} \times \boldsymbol{\Gamma}^{k} \times \{\boldsymbol{L}, \boldsymbol{R}\}^{k},$$

so all *k* tapes can be written, and all *k* heads can be moved, simultaneously.

▶ Note that the state of *M* is shared across all of the tapes.

Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Slide 9/28

Multitape Turing machines

We show that a k-tape Turing machine can be simulated by a 1-tape Turing machine.

Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Slide 10/28

Multitape Turing machines

We show that a k-tape Turing machine can be simulated by a 1-tape Turing machine. The basic idea:



is mapped to



Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Slide 10/28

Assume the input is a string $w_1 w_2 \dots w_n$.

1. To start with, *S* puts its tape into the format corresponding to a concatenation of all *k* tapes of *M*, i.e.:

$$\# \widehat{W_1} W_2 \dots W_n \# \widehat{ } \# \widehat{ } \# \widehat{ } \# \dots \#$$



Slide 11/28

Assume the input is a string $w_1 w_2 \dots w_n$.

1. To start with, *S* puts its tape into the format corresponding to a concatenation of all *k* tapes of *M*, i.e.:

$$\#\widehat{W_1}W_2\ldots W_n\#\widehat{}_{}^{}\#\widehat{}_{}^{}\#\ldots \#$$

2. To simulate a move of *M*, *S* scans the tape from the first # to the (k + 1)'st #, to determine what the symbols are under the heads.



Assume the input is a string $w_1 w_2 \dots w_n$.

1. To start with, *S* puts its tape into the format corresponding to a concatenation of all *k* tapes of *M*, i.e.:

 $\#\widehat{W_1}W_2\ldots W_n\#\widehat{}_{}^{}\#\widehat{}_{}^{}\#\ldots \#$

- 2. To simulate a move of *M*, *S* scans the tape from the first # to the (k + 1)'st #, to determine what the symbols are under the heads.
- 3. *S* then passes back through the tape to update it according to *M*'s transition function operating on these symbols.



Assume the input is a string $w_1 w_2 \dots w_n$.

1. To start with, *S* puts its tape into the format corresponding to a concatenation of all *k* tapes of *M*, i.e.:

 $\# \widehat{W_1} W_2 \dots W_n \# \widehat{ } \# \widehat{ } \# \dots \#$

- 2. To simulate a move of *M*, *S* scans the tape from the first # to the (k + 1)'st #, to determine what the symbols are under the heads.
- 3. *S* then passes back through the tape to update it according to *M*'s transition function operating on these symbols.
- 4. At some point *S* may move one of the *k* virtual heads rightwards onto a #. This implies that *M* has moved that physical head onto a blank square of the tape. In this situation, *S* shifts everything to the right of that cell one position to the right, and then writes a _ symbol onto that tape cell.

Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Slide 11/28

Other equivalent models

There are also machines which may seem weaker (or very different), but which turn out to be equivalent to Turing machines.

First, a pushdown automaton with two stacks:



Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Slide 12/28

Other equivalent models

There are also machines which may seem weaker (or very different), but which turn out to be equivalent to Turing machines.

First, a pushdown automaton with two stacks:



- The basic idea is that one stack represents the tape extending to the left, the other the tape extending to the right (including the cell under the head).
- The PDA begins by reading in the input into the second stack. Then it simulates the operation of a Turing machine using the stacks.



The state of the PDA after it has first read in the input looks like



Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Slide 13/28

The state of the PDA after it has first read in the input looks like



The PDA repeatedly pops the top symbol from the first stack and pushes it onto the second stack. The resulting state is



This corresponds to the starting configuration of a Turing machine.

Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Slide 13/28

- The PDA can look at the top element of the second stack to determine which operations to perform.
- So if (for example) the current state of the Turing machine wants to replace the current symbol with c and move to the right, the new configuration of the PDA would be



Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Slide 14/28

- The PDA can look at the top element of the second stack to determine which operations to perform.
- So if (for example) the current state of the Turing machine wants to replace the current symbol with c and move to the right, the new configuration of the PDA would be



The PDA then continues to simulate the Turing machine in this way until it accepts or rejects.

Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Slide 14/28

Consider the following, very simple model of a "real" computer:

- We have a small, fixed number of registers, each containing an integer (which can be arbitrarily large).
- ► We have an instruction set containing only the instructions
 - ▶ INC *r*: increment register *r*
 - DEC r: decrement register r (never going below 0)
 - ► JZ r, k: if r = 0, jump to instruction k, otherwise continue.



Consider the following, very simple model of a "real" computer:

- We have a small, fixed number of registers, each containing an integer (which can be arbitrarily large).
- ► We have an instruction set containing only the instructions
 - ► INC *r*: increment register *r*
 - DEC r: decrement register r (never going below 0)
 - ► JZ r, k: if r = 0, jump to instruction k, otherwise continue.
- If we have a register Z always set to 0, we can define GOTO k as shorthand for JZ Z, k.



Consider the following, very simple model of a "real" computer:

- We have a small, fixed number of registers, each containing an integer (which can be arbitrarily large).
- We have an instruction set containing only the instructions
 - ▶ INC r: increment register r
 - DEC r: decrement register r (never going below 0)
 - ► JZ r, k: if r = 0, jump to instruction k, otherwise continue.
- If we have a register Z always set to 0, we can define GOTO k as shorthand for JZ Z, k.

An example program fragment on a counter machine:

```
1. DEC B
2. JZ B, 4
3. GOTO 1
4. ...
```



Consider the following, very simple model of a "real" computer:

- We have a small, fixed number of registers, each containing an integer (which can be arbitrarily large).
- We have an instruction set containing only the instructions
 - ► INC *r*: increment register *r*
 - DEC r: decrement register r (never going below 0)
 - ► JZ r, k: if r = 0, jump to instruction k, otherwise continue.
- If we have a register Z always set to 0, we can define GOTO k as shorthand for JZ Z, k.

An example program fragment on a counter machine:

```
1. DEC B
2. JZ B, 4
3. GOTO 1
4. ...
```

The above code zeroes register B before continuing (call this "ZERO B").

Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



What does the following code do?

```
1. ZERO B
2. ZERO C
3. JZ A, 8
4. DEC A
5. TNC B
6. INC C
7. GOTO 3
8. JZ C, 12
9. INC A
10. DEC C
11. GOTO 8
12. ...
```



Slide 16/28

What does the following code do?

```
1. ZERO B
2. ZERO C
3. JZ A, 8
4. DEC A
5. TNC B
6. INC C
7. GOTO 3
8. JZ C, 12
9. INC A
10. DEC C
11. GOTO 8
12. ...
```

It copies register A to register B, using register C as temporary storage.

Ashley Montanaro
COMS11700: Turing machines



Slide 16/28

Our simulation will be based around having three registers:

- H stores the tape symbol under the head;
- L stores the tape to the left of the head;
- **R** stores the tape to the right of the head (up to the first blank symbol).



Our simulation will be based around having three registers:

- H stores the tape symbol under the head;
- L stores the tape to the left of the head;
- **R** stores the tape to the right of the head (up to the first blank symbol).

Assume the tape alphabet is $\{0, 1, _\}$. We store multiple tape symbols in one register by encoding them as an integer written in binary.

► If the tape to the right of the head is $r_0r_1 \dots r_{m-1}$ (going left to right), the integer in **R** is $\sum_{i=0}^{m-1} r_i 2^i$.



Our simulation will be based around having three registers:

- H stores the tape symbol under the head;
- L stores the tape to the left of the head;
- **R** stores the tape to the right of the head (up to the first blank symbol).

Assume the tape alphabet is $\{0, 1, _\}$. We store multiple tape symbols in one register by encoding them as an integer written in binary.

- ► If the tape to the right of the head is $r_0r_1 \dots r_{m-1}$ (going left to right), the integer in **R** is $\sum_{i=0}^{m-1} r_i 2^i$.
- Similarly, if the tape to the left of the head is ℓ₀ℓ₁...ℓ_{m-1} (going right to left), the integer in L is ∑_{i=0}^{m-1} ℓ_i2ⁱ.



Our simulation will be based around having three registers:

- H stores the tape symbol under the head;
- L stores the tape to the left of the head;
- **R** stores the tape to the right of the head (up to the first blank symbol).

Assume the tape alphabet is $\{0, 1, _\}$. We store multiple tape symbols in one register by encoding them as an integer written in binary.

- ► If the tape to the right of the head is $r_0r_1 \dots r_{m-1}$ (going left to right), the integer in **R** is $\sum_{i=0}^{m-1} r_i 2^i$.
- Similarly, if the tape to the left of the head is ℓ₀ℓ₁...ℓ_{m-1} (going right to left), the integer in L is ∑_{i=0}^{m-1} ℓ_i2ⁱ.

Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Slide 17/28

Our simulation will be based around having three registers:

- H stores the tape symbol under the head;
- L stores the tape to the left of the head;
- **R** stores the tape to the right of the head (up to the first blank symbol).

Assume the tape alphabet is $\{0, 1, _\}$. We store multiple tape symbols in one register by encoding them as an integer written in binary.

- ► If the tape to the right of the head is $r_0r_1 \dots r_{m-1}$ (going left to right), the integer in **R** is $\sum_{i=0}^{m-1} r_i 2^i$.
- Similarly, if the tape to the left of the head is ℓ₀ℓ₁...ℓ_{m-1} (going right to left), the integer in L is ∑_{i=0}^{m-1} ℓ_i2ⁱ.

e.g.:
$$0 \ 1 \ 1 \ 0 \ 0 \ 1 \ - \ S \ \cdots$$
 $H=1, L=1, R=4.$



Slide 17/28

- We start the simulation by having the register H contain the first symbol on the tape, and R contain the rest of the input.
- Then the simulation proceeds similarly to the two-stack PDA, where we think of L as containing the first stack and R the second stack.



Slide 18/28

- We start the simulation by having the register H contain the first symbol on the tape, and R contain the rest of the input.
- Then the simulation proceeds similarly to the two-stack PDA, where we think of L as containing the first stack and R the second stack.

A sketch of how this works:

- 1. We have different code for each possible state of the Turing machine.
- 2. We can check whether the symbol under the head is 0 or 1 using JZ.
- 3. Imagine it is 0 and in the current state we should write a 1 and move right (the other cases are similar). Then:
 - We multiply L by 2 and then add 1 to L;
 - We update H to contain the lowest bit of R;
 - We divide R by 2 (delete the lowest bit).

The multiplication and division operations can be performed using a sequence of increments and decrements (exercise!).

Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Extremely small counter machines

Using this basic idea, we can simulate a Turing machine using 5 registers (the H, L and R registers, the Z register and another "workspace" register).



Slide 19/28

Extremely small counter machines

- Using this basic idea, we can simulate a Turing machine using 5 registers (the H, L and R registers, the Z register and another "workspace" register).
- This can be reduced to 2 registers if a trick called Gödel encoding is used, where several integers z₁,..., z_k are encoded as a product of prime numbers raised to corresponding powers:

$$z_1, z_2, \ldots, z_k \mapsto 2^{z_1} 3^{z_2} 5^{z_3} \ldots$$



Slide 19/28

Extremely small counter machines

- Using this basic idea, we can simulate a Turing machine using 5 registers (the H, L and R registers, the Z register and another "workspace" register).
- This can be reduced to 2 registers if a trick called Gödel encoding is used, where several integers z₁,..., z_k are encoded as a product of prime numbers raised to corresponding powers:

$$z_1, z_2, \ldots, z_k \mapsto 2^{z_1} 3^{z_2} 5^{z_3} \ldots$$

Thus, assuming that the Church-Turing thesis is true, a computer with 2 registers and 3 instructions can compute everything which can be computed!

Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Just as we can have nondeterministic finite and pushdown automata, we can have nondeterministic Turing machines (NDTMs).

- > An NDTM can explore multiple computational paths simultaneously.
- It accepts if and only if at least one of the computational paths accepts.



Ashley Montanaro
COMS11700: Turing machines



Slide 20/28

 NDTMs are formally described in the same way as TMs, except that their transition function is of the form

 $\delta: \boldsymbol{Q} \times \boldsymbol{\Gamma} \to \mathcal{P}(\boldsymbol{Q} \times \boldsymbol{\Gamma} \times \{\boldsymbol{L}, \boldsymbol{R}\})$

- The right-hand side of this expression specifies the set of new configurations reachable from any given configuration. We think of this as exploring a tree of possible computation paths simultaneously.
- An NDTM accepts if any of the computation paths leads to the accepting state q_{accept}.



 NDTMs are formally described in the same way as TMs, except that their transition function is of the form

 $\delta: \boldsymbol{Q} \times \boldsymbol{\Gamma} \to \mathcal{P}(\boldsymbol{Q} \times \boldsymbol{\Gamma} \times \{\boldsymbol{L}, \boldsymbol{R}\})$

- The right-hand side of this expression specifies the set of new configurations reachable from any given configuration. We think of this as exploring a tree of possible computation paths simultaneously.
- An NDTM accepts if any of the computation paths leads to the accepting state q_{accept}.
- Unlike TMs, we do not believe we can really implement NDTMs physically.
- Nevertheless, they are a useful theoretical tool...



 NDTMs are formally described in the same way as TMs, except that their transition function is of the form

 $\delta: \boldsymbol{Q} \times \boldsymbol{\Gamma} \to \mathcal{P}(\boldsymbol{Q} \times \boldsymbol{\Gamma} \times \{\boldsymbol{L}, \boldsymbol{R}\})$

- The right-hand side of this expression specifies the set of new configurations reachable from any given configuration. We think of this as exploring a tree of possible computation paths simultaneously.
- An NDTM accepts if any of the computation paths leads to the accepting state q_{accept}.
- Unlike TMs, we do not believe we can really implement NDTMs physically.
- Nevertheless, they are a useful theoretical tool...

Are NDTMs more powerful than TMs?

Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Theorem

Every NDTM has an equivalent TM.

Proof idea

- Given an NDTM N, we form a deterministic multitape TM D by trying all possible branches of its computation tree.
- ► *D* accepts if any of these branches accept. Otherwise, *D* runs forever.
- ► We explore this tree using breadth-first search.



Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



The simulation (sketch)



Our simulating TM will have three tapes:

- ► The input tape contains the original input to the NDTM *N*.
- ► The simulation tape contains the current contents of *N*'s tape.
- The address tape describes a sequence of states which can be reached by N.

Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Slide 23/28

The simulation (sketch)



The simulation proceeds as follows:

- 1. Initialise the simulation and address tapes to be empty.
- 2. Copy the input tape to the simulation tape.
- 3. Simulate some steps of *N* on the simulation tape, according to the address tape. Accept if *N* accepts.
- 4. Replace the address tape with the next valid identifier of a branch of *N*'s computation, and go to step (2).

Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



The Turing machine model is powerful enough to simulate itself.

- ► In other words, there exists a Turing machine *U* which can simulate the operation of any other Turing machine *M*, given a description of *M* as input.
- Intuitively, this is like having an interpreter for a programming language written in the language itself.
- ► We show this by sketching a 2-tape TM U which simulates the operation of any 1-tape TM M (as we have seen, U can then be converted to only use 1 tape).

Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Slide 25/28

1. The first tape of *U* stores a description $\langle M \rangle$ of *M* (for example, *M*'s transition function). The second tape will store *M*'s configuration at any point in the computation.



Slide 26/28

1. The first tape of *U* stores a description $\langle M \rangle$ of *M* (for example, *M*'s transition function). The second tape will store *M*'s configuration at any point in the computation.

2. At each step of the computation, *U* reads *M*'s transition function to decide what step to perform next and updates the configuration on the second tape appropriately.



1. The first tape of *U* stores a description $\langle M \rangle$ of *M* (for example, *M*'s transition function). The second tape will store *M*'s configuration at any point in the computation.

2. At each step of the computation, *U* reads *M*'s transition function to decide what step to perform next and updates the configuration on the second tape appropriately.

3. If the simulation of *M* enters the accept or reject state, *U* accepts or rejects (respectively).

Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Slide 26/28

The Church-Turing thesis states that everything which can be computed can be computed by a Turing machine.



Slide 27/28

- The Church-Turing thesis states that everything which can be computed can be computed by a Turing machine.
- Some evidence for this: Turing machines are equivalent to other models of computation such as multitape Turing machines, pushdown automata with two stacks and counter machines.



Slide 27/28

- The Church-Turing thesis states that everything which can be computed can be computed by a Turing machine.
- Some evidence for this: Turing machines are equivalent to other models of computation such as multitape Turing machines, pushdown automata with two stacks and counter machines.
- The nondeterministic Turing machine model is apparently more powerful but can also be simulated by a deterministic Turing machine.



- The Church-Turing thesis states that everything which can be computed can be computed by a Turing machine.
- Some evidence for this: Turing machines are equivalent to other models of computation such as multitape Turing machines, pushdown automata with two stacks and counter machines.
- The nondeterministic Turing machine model is apparently more powerful but can also be simulated by a deterministic Turing machine.
- There are universal Turing machines which can simulate any other Turing machine given as input.



- The Church-Turing thesis states that everything which can be computed can be computed by a Turing machine.
- Some evidence for this: Turing machines are equivalent to other models of computation such as multitape Turing machines, pushdown automata with two stacks and counter machines.
- The nondeterministic Turing machine model is apparently more powerful but can also be simulated by a deterministic Turing machine.
- There are universal Turing machines which can simulate any other Turing machine given as input.
- Further reading: Sipser §3.1-3.3, and Computation: Finite and Infinite Machines (Marvin L. Minsky, Prentice-Hall, 1967).

Ashley Montanaro ashley@cs.bris.ac.uk COMS11700: Turing machines



Slide 27/28