Anomalous fluctuations in one dimensional interacting systems

Joint with Júlia Komjáthy and Timo Seppäläinen

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University of Bristol

Bristol, 29 November, 2013.

The models

Asymmetric simple exclusion process Zero range Bricklayers

Hydrodynamics

Characteristics

Tool: the second class particle

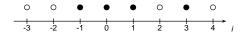
Single Many second class particles

Results

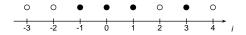
Normal fluctuations Abnormal fluctuations

Proof

Upper bound Lower bound Microscopic concavity/convexity



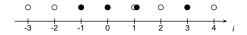
Bernoulli(ϱ) distribution; $\omega_i = 0$ or 1.



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Particles try to jump

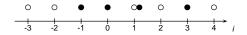
to the right with rate p, to the left with rate q = 1 - p < p.



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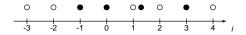
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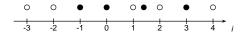
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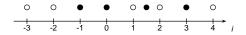
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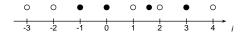
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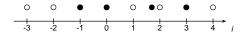
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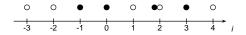
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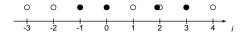
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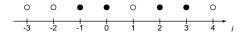
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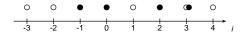
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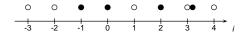
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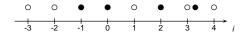
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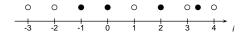
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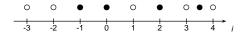
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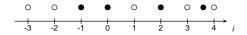
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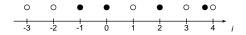
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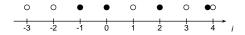
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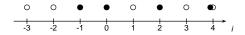
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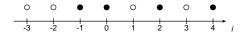
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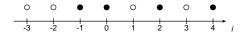
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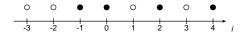
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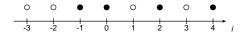
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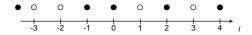
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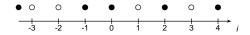
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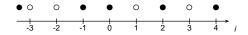
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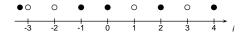
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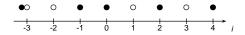
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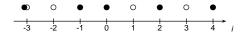
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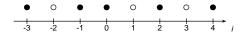
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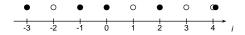
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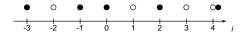
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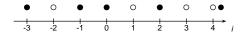
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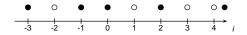
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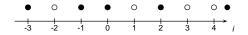
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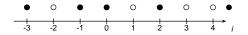
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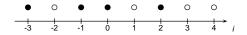
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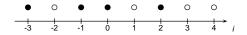
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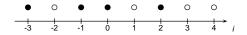
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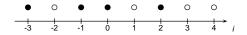
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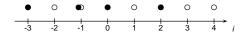
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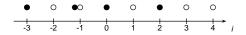
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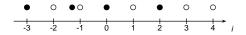
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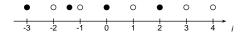
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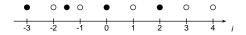
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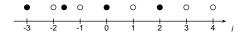
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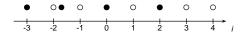
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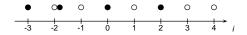
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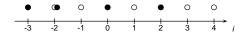
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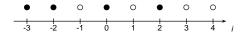
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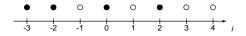
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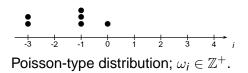
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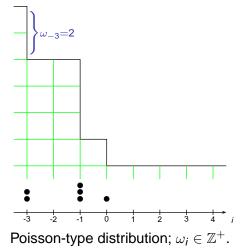
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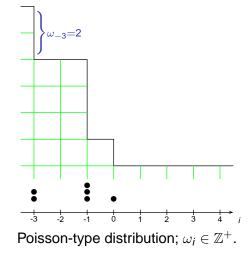
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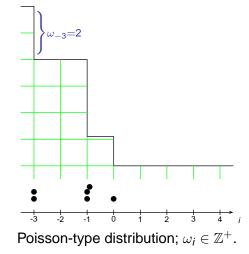
The jump is suppressed if the destination site is occupied by another particle.

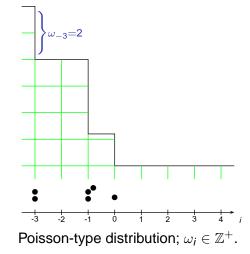
The Bernoulli(ϱ) distribution is time-stationary for any ($0 \le \varrho \le 1$). Any translation-invariant stationary distribution is a mixture of Bernoullis.

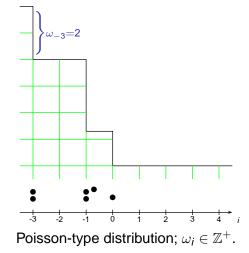


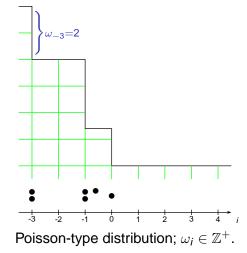


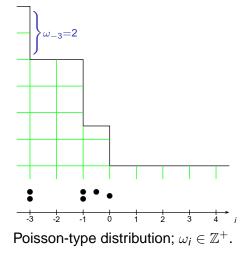


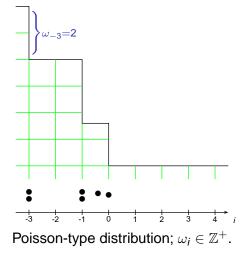


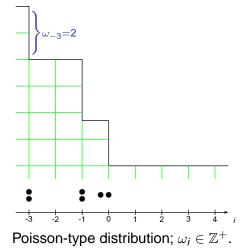


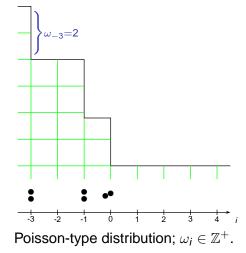


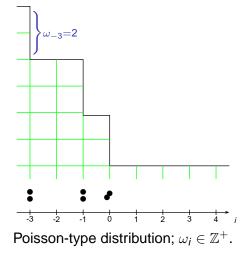


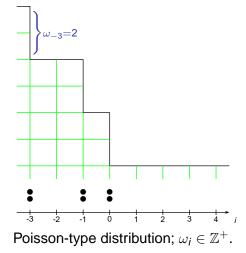


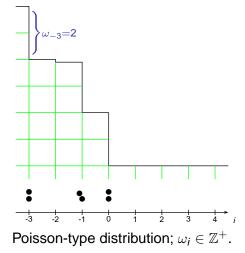






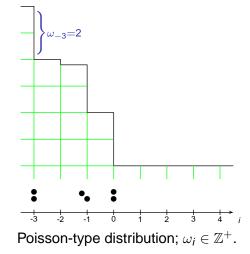


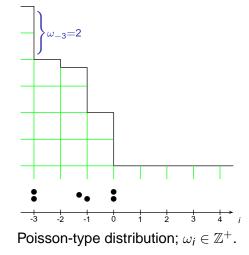


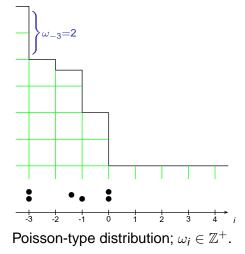


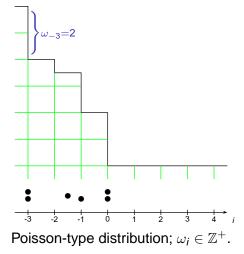
AZRP ABLP

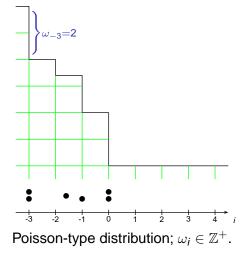
The asymmetric zero range process

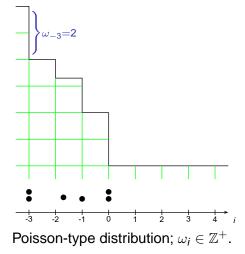


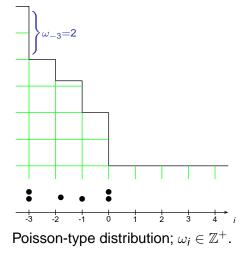


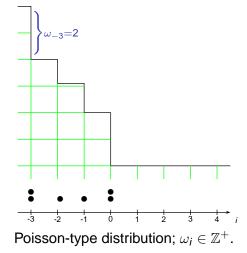


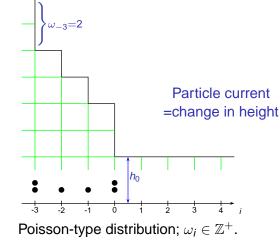


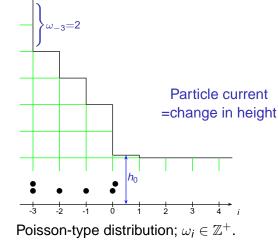


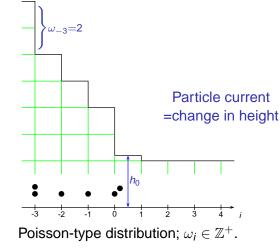


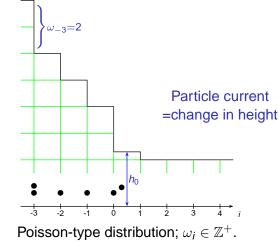


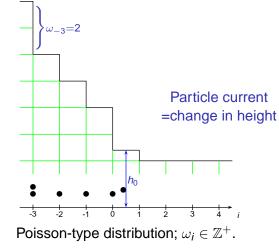


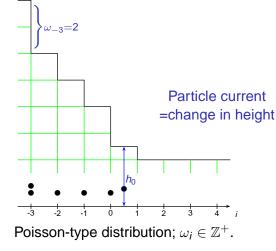


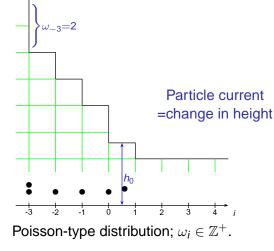


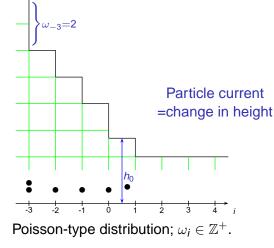


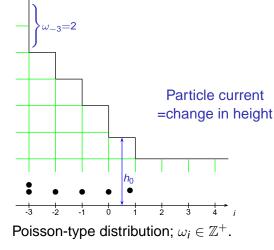


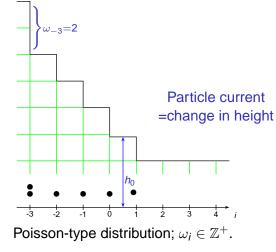


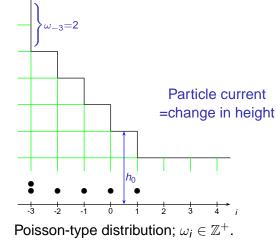


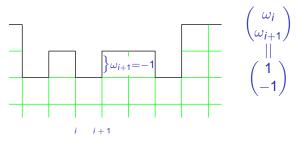




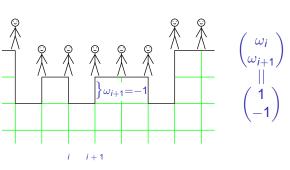






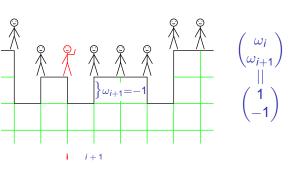


Poisson-type distribution; $\omega_i \in \mathbb{Z}$.



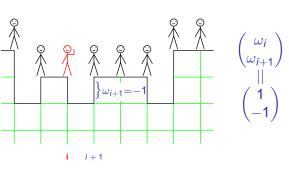
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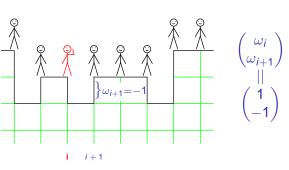
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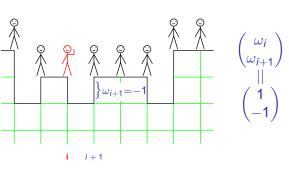
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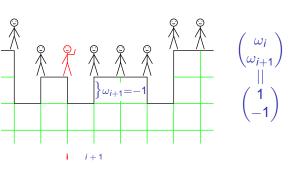
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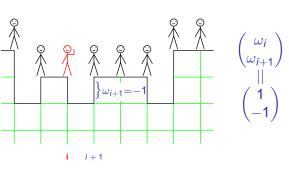
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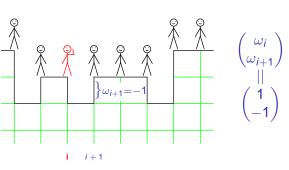
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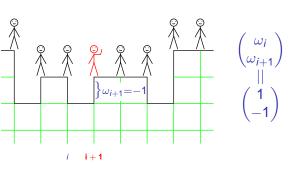
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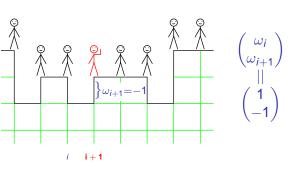
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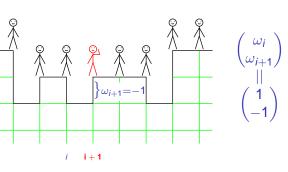
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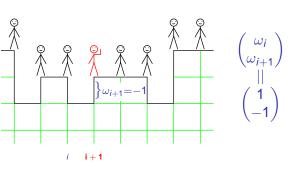
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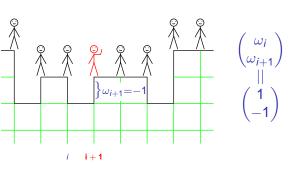
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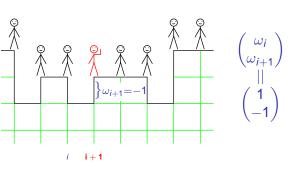
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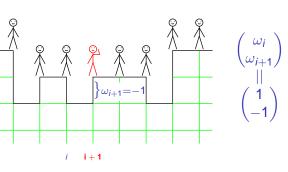
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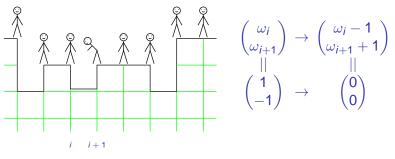
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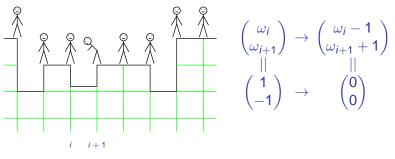
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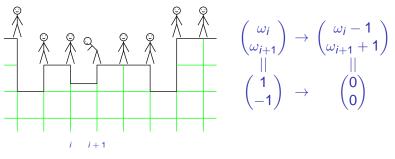
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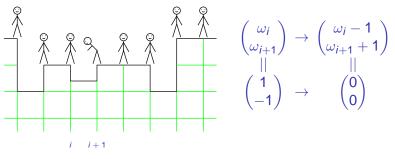
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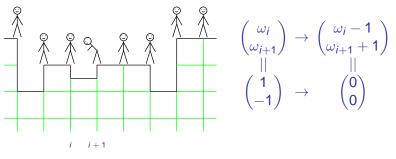
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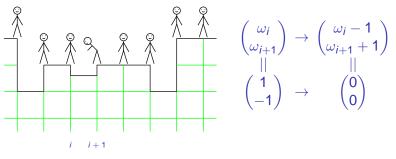
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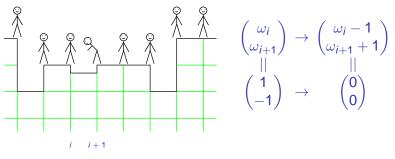
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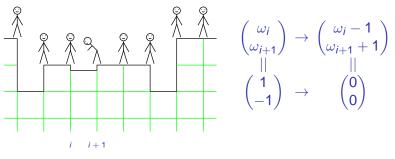
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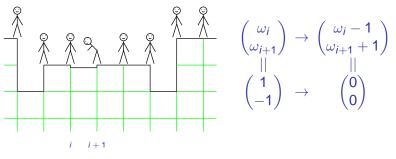
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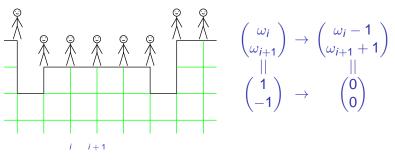
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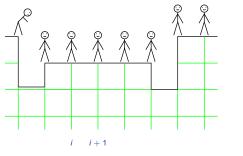
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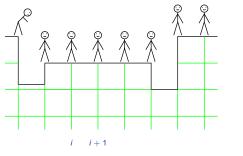
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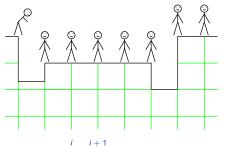
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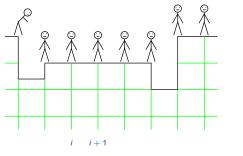
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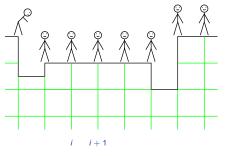
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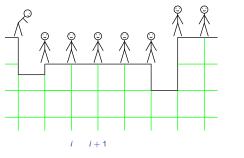
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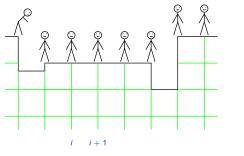
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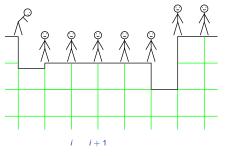
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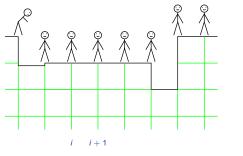
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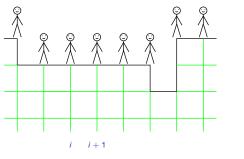
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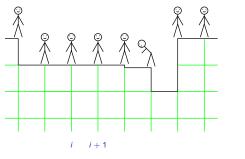
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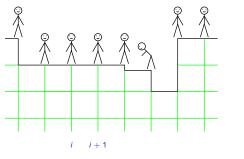
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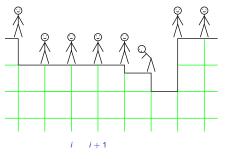
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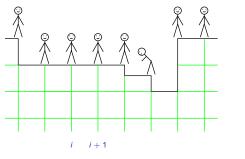
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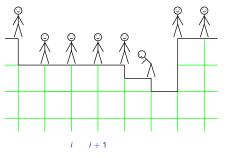
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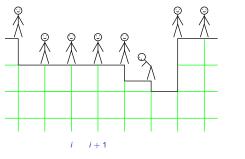
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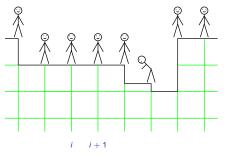
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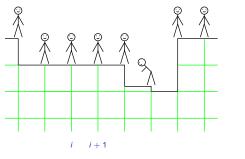
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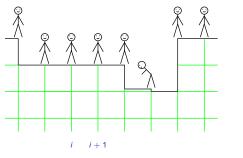
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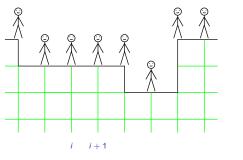
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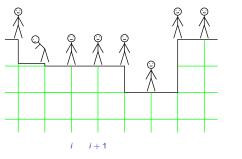
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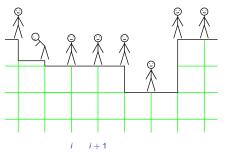
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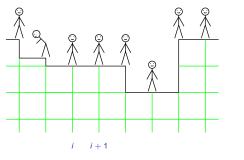
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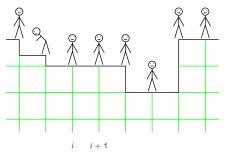
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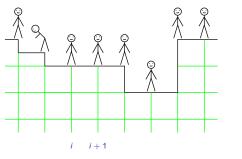
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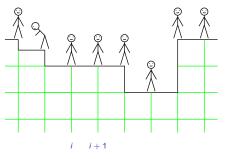
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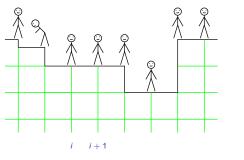
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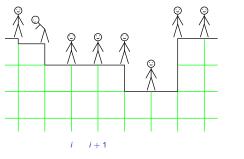
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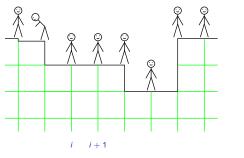
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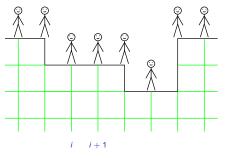
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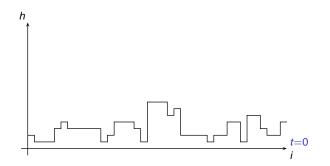
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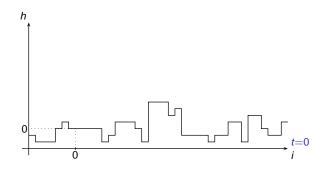
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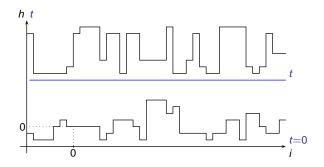
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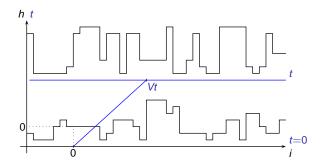
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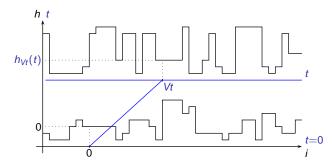
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- they satisfy some regularity conditions to make sure the dynamics exists.











 $h_{Vt}(t)$ = height as seen by a moving observer of velocity V. = net number of particles passing the window $s \mapsto Vs$.

(Remember: particle current=change in height.)

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► The characteristics is a path X(T) where *e*(T, X(T)) is constant.

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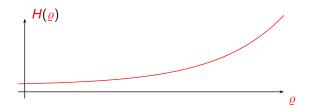
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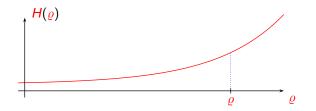
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Convex flux (some cases of AZRP, ABLP):



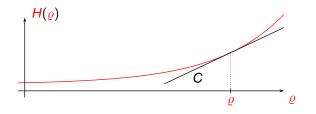
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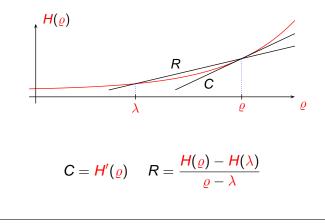
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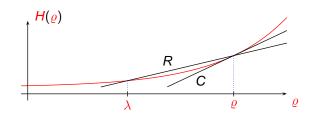
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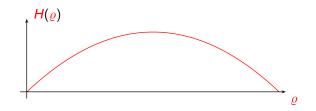
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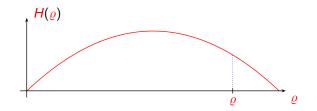
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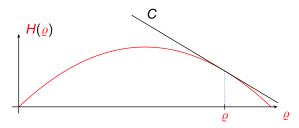
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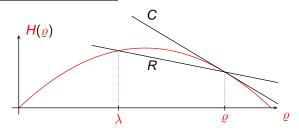


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Characteristics (very briefly)

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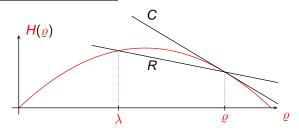
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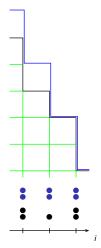


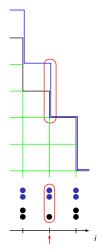
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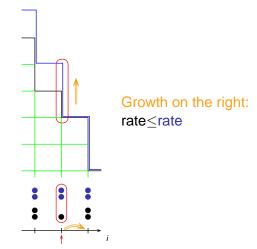
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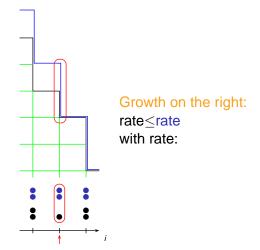
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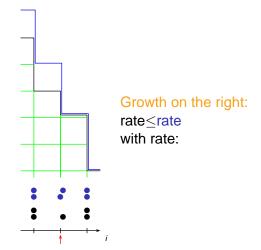
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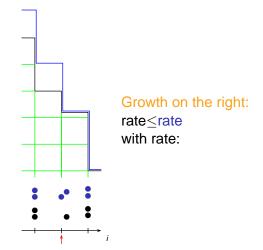


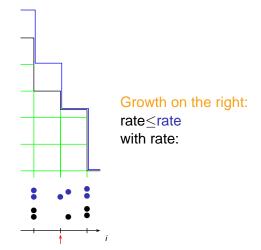


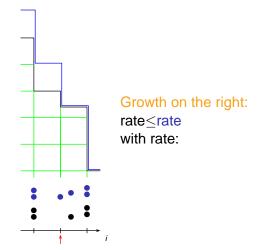


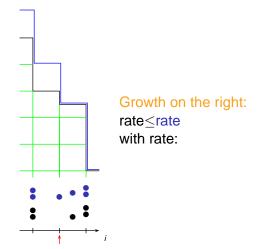


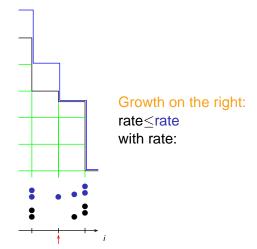


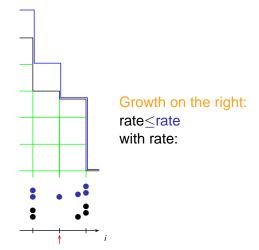


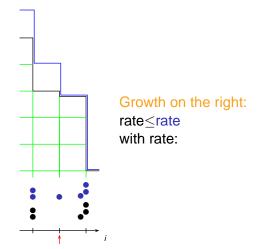


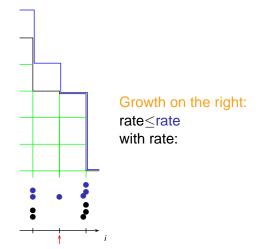


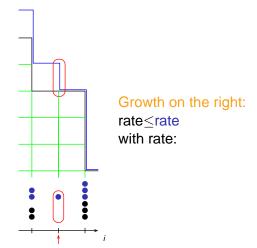


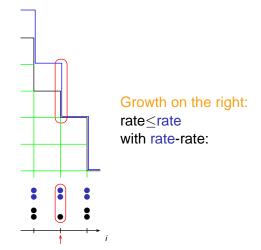


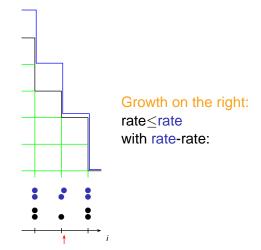


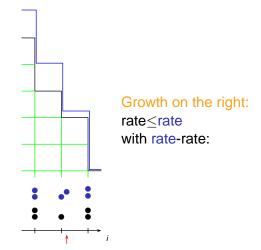


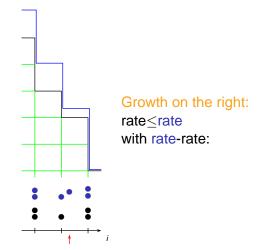


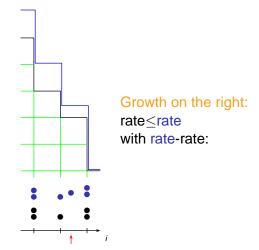


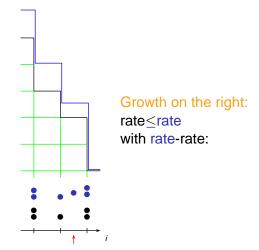


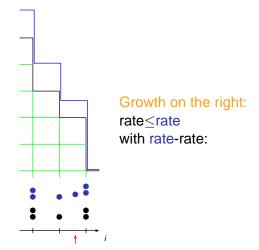


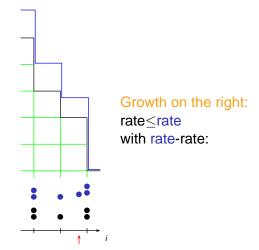


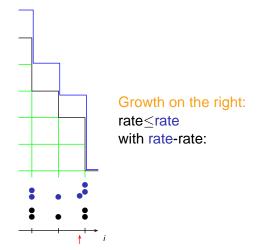


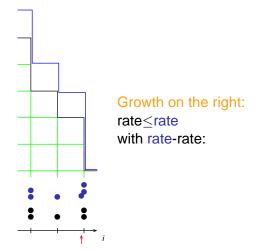


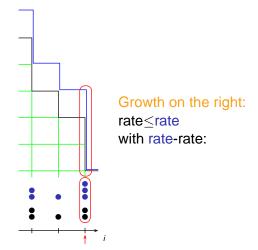


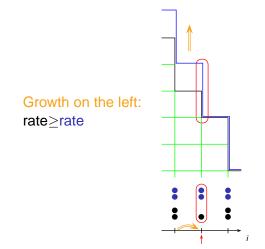


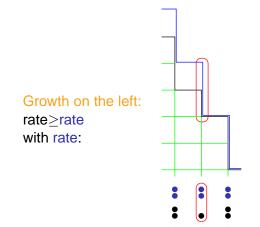


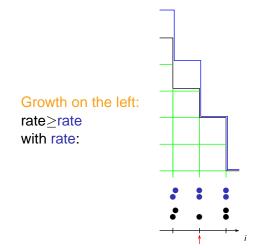


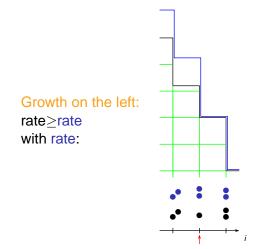


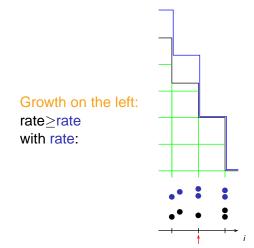


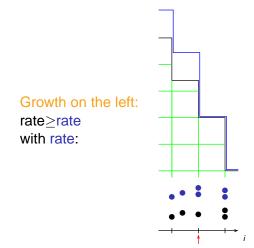


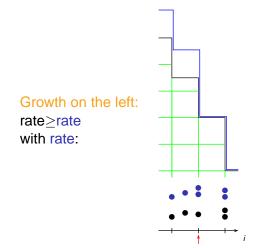


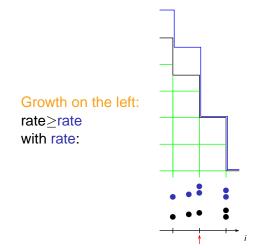


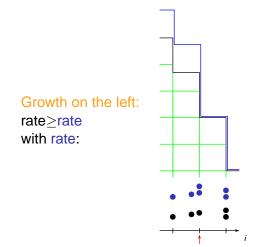


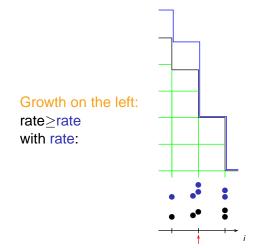


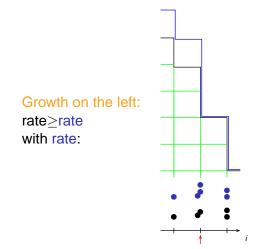


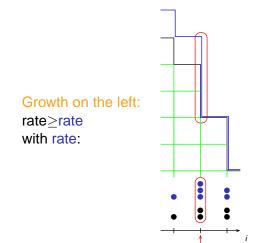






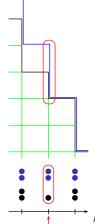


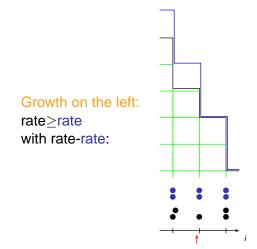


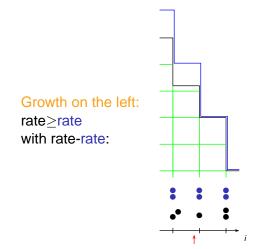


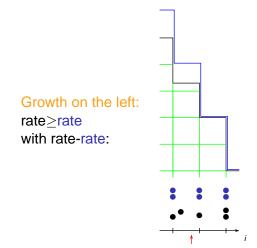
States ω and ω only differ at one site.

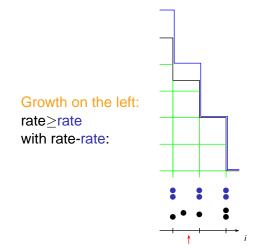
Growth on the left: rate > rate with rate-rate:

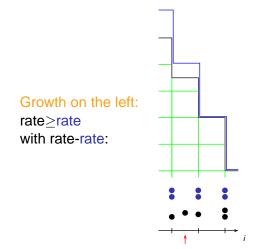


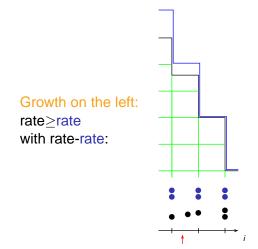


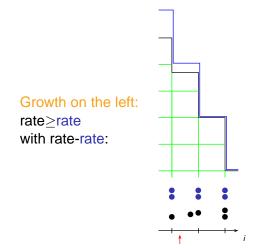


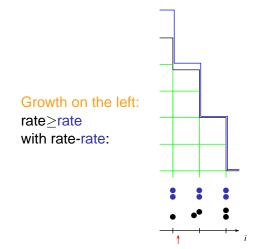


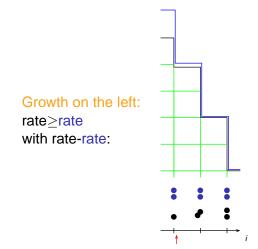


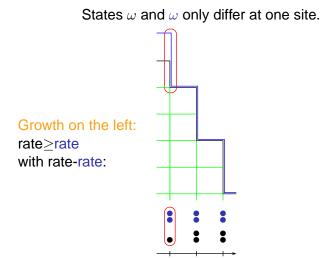


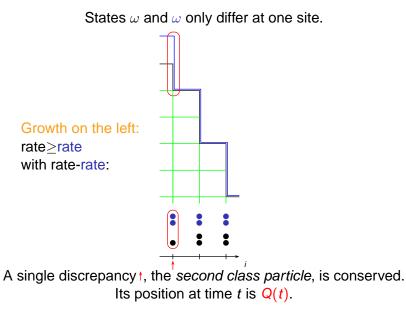












Theorem (B. - Seppäläinen; also ideas from B. Tóth, H. Spohn and M. Prähofer)

Started from (almost) equilibrium,

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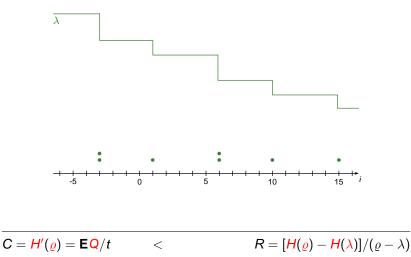
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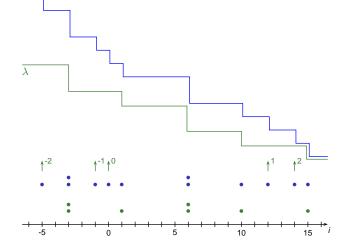
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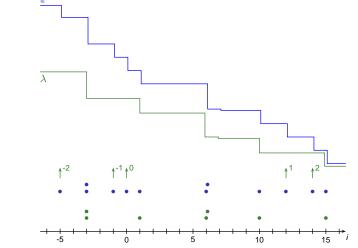




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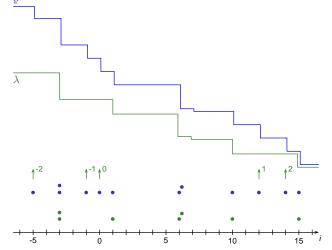


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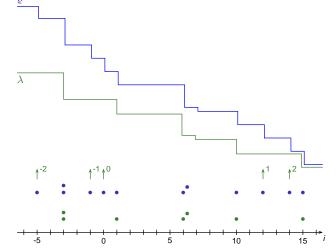
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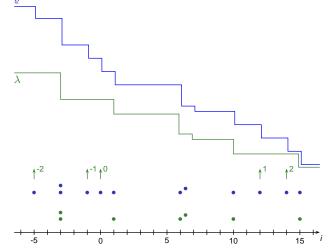


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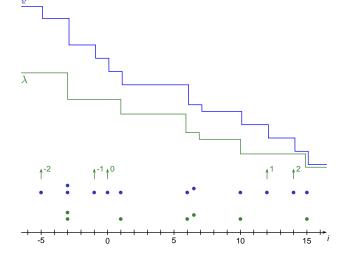
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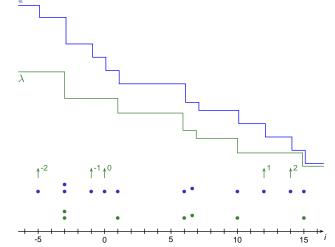


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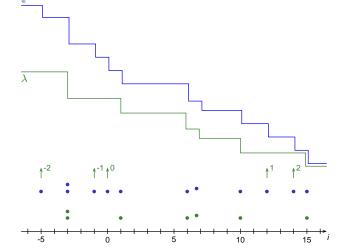










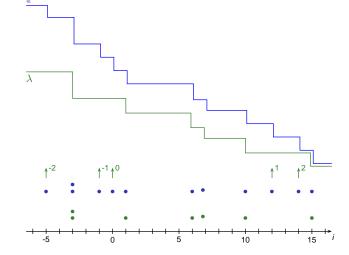


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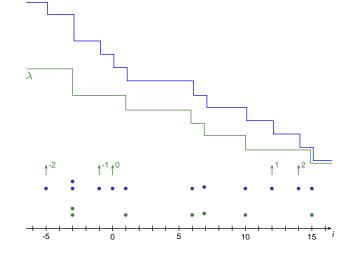








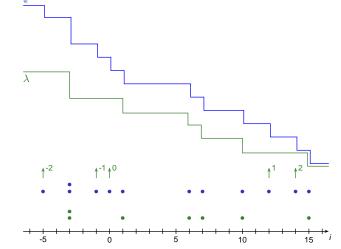
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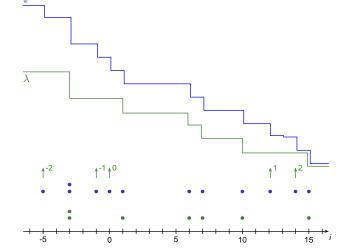






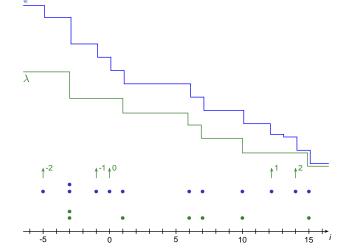






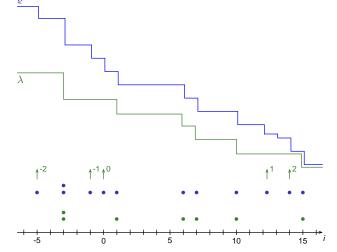






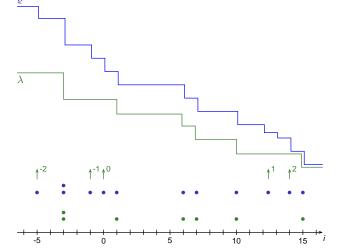
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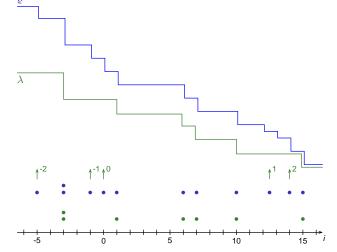


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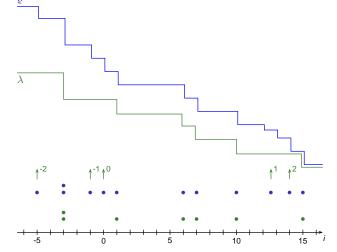




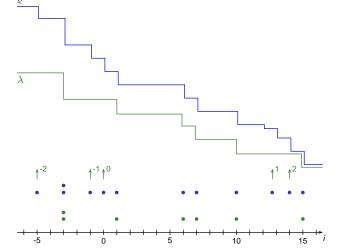




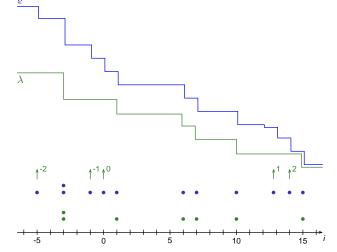






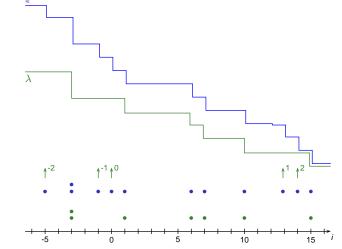












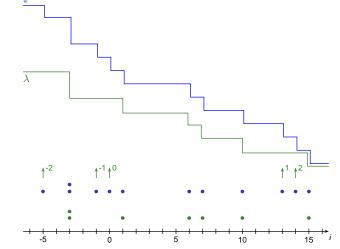
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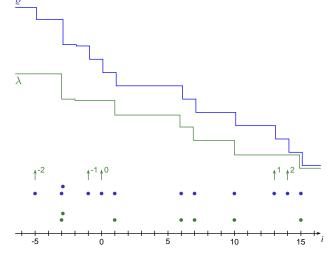




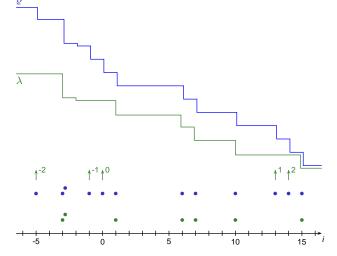


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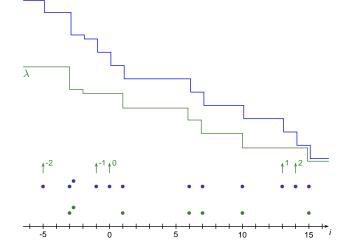
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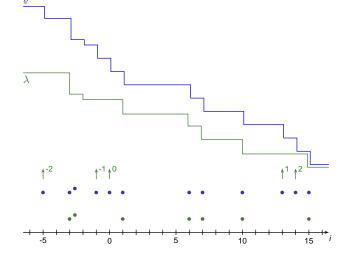
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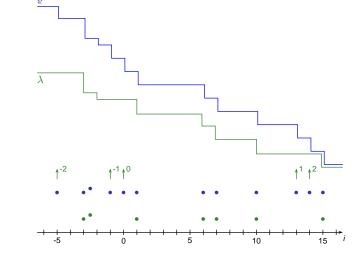






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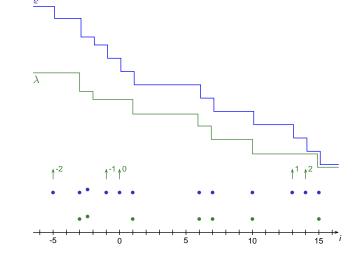




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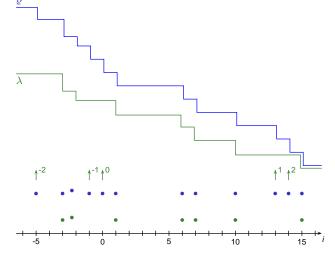




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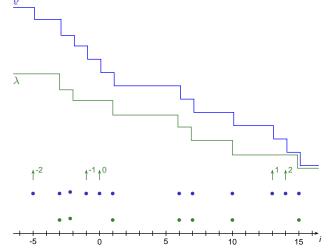
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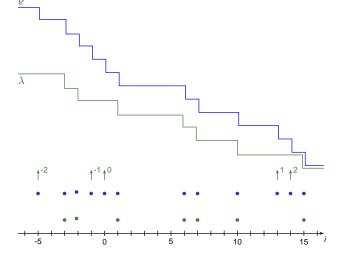


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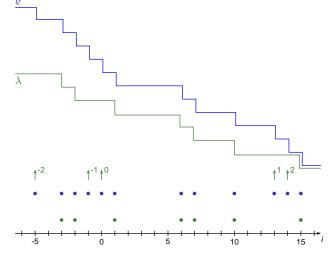
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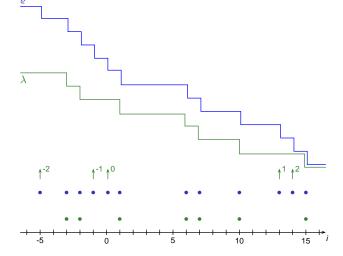


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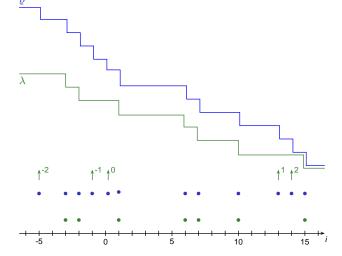
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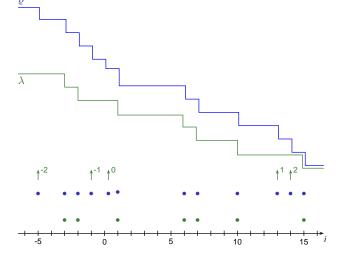


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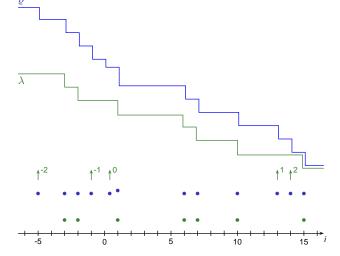
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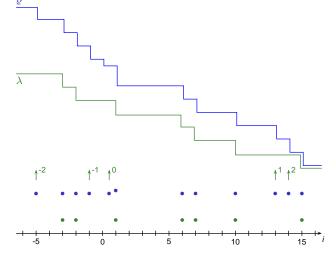
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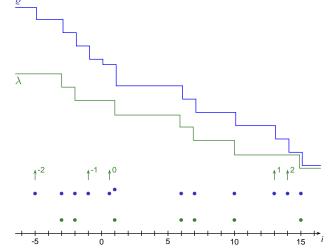
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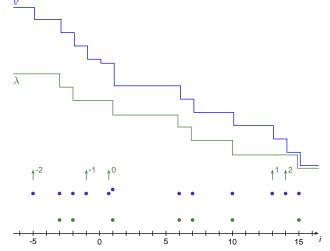
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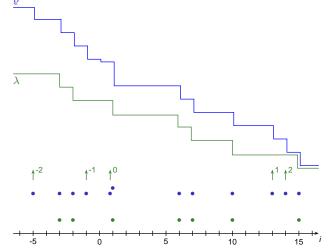


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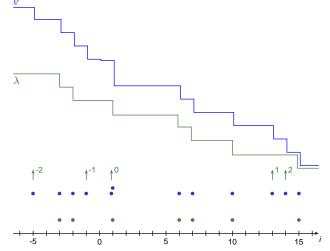


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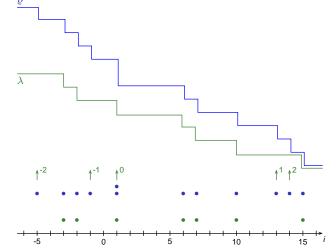
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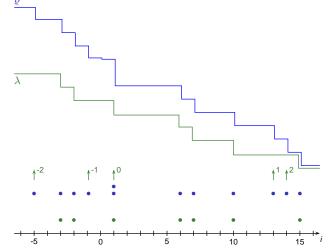
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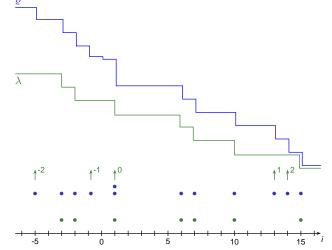
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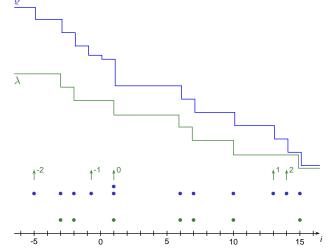
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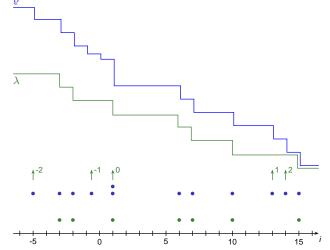
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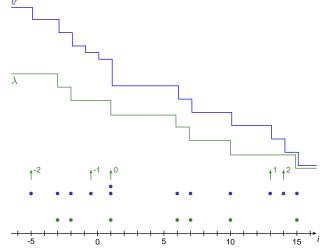
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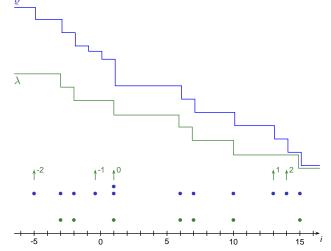


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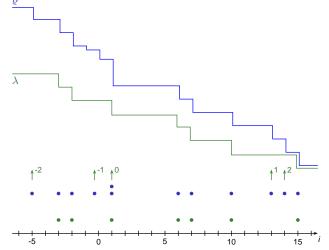
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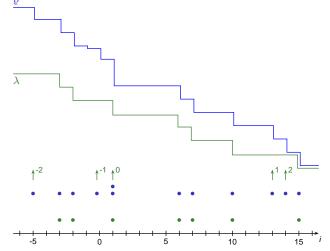




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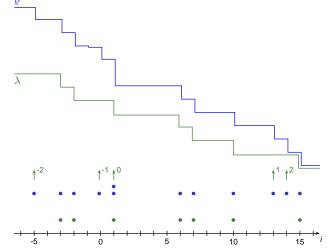


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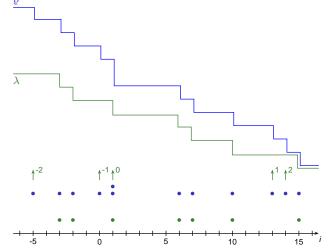


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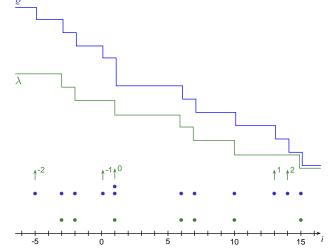
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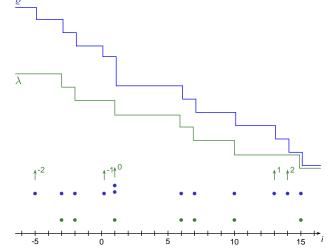
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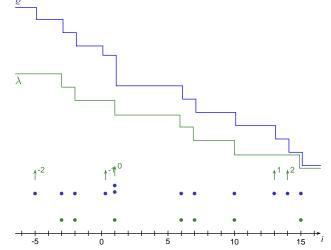
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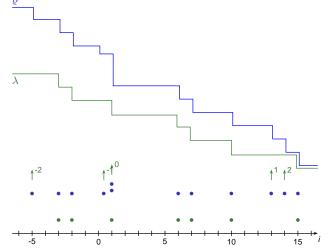
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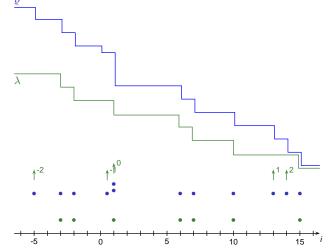


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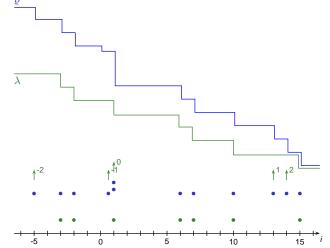


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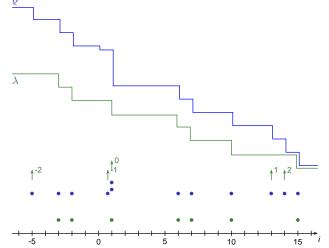
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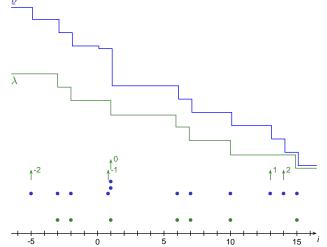


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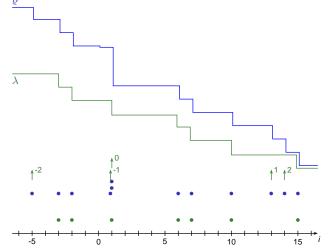
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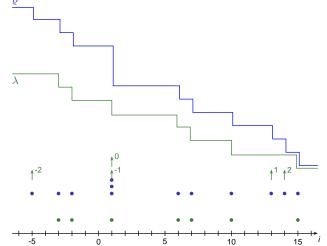


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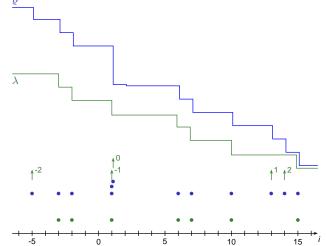
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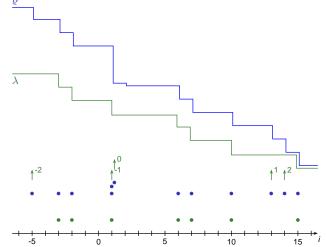
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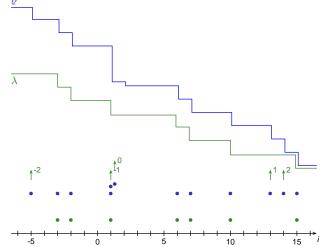


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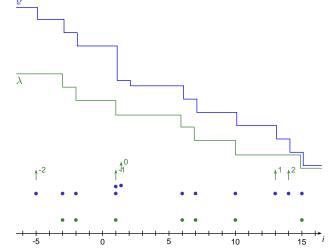


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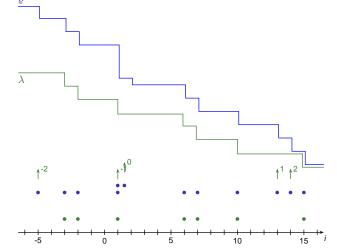


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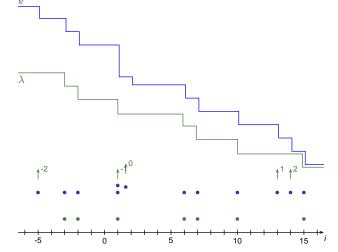


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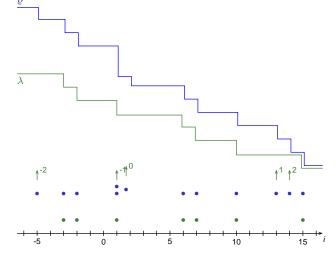




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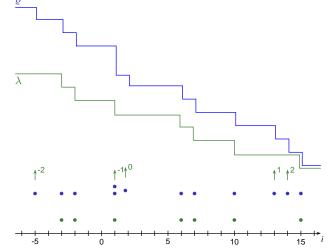


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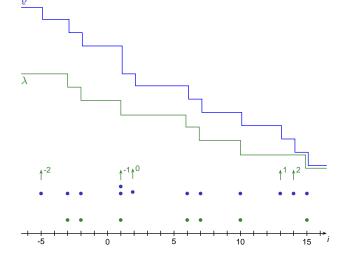


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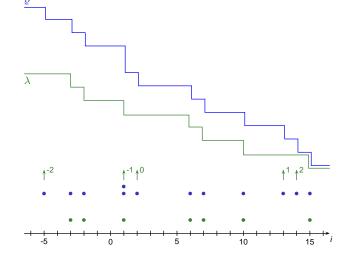
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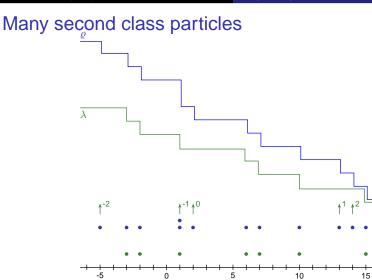
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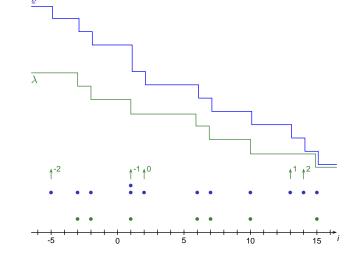
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Picture:

The position X(t) of \uparrow^0 follows the Rankine-Hugoniot speed *R*.



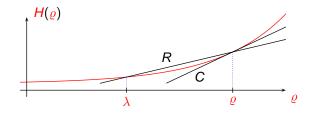


Picture:

The position X(t) of \uparrow^0 follows the Rankine-Hugoniot speed R.

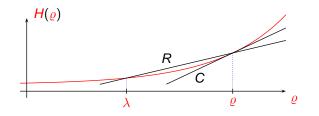
 $C = H'(\rho) = \mathbf{E}\mathbf{Q}/t$ < **E** $X/t = R = [H(\rho) - H(\lambda)]/(\rho - \lambda)$

Convex flux (some cases of AZRP, ABLP):



Recall
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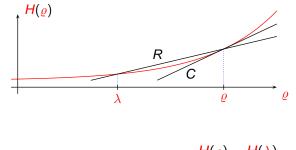
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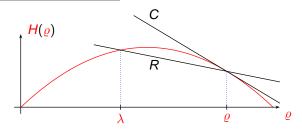
Do we have $Q(t) \stackrel{?}{\geq} X(t)$

Convex flux (some cases of AZRP, ABLP):



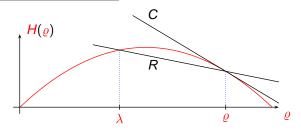
Recall $C = H'(\varrho) > R = \frac{H(\varrho) - H(\lambda)}{\varrho - \lambda}$ Do we have $Q(t) \stackrel{?}{\geq} X(t)$ - tight error

Concave flux (ASEP, AZRP):



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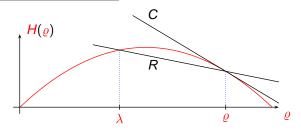
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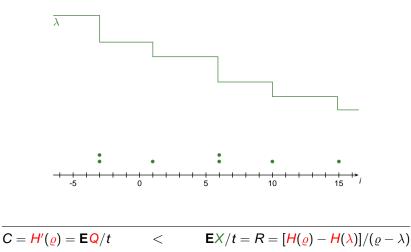
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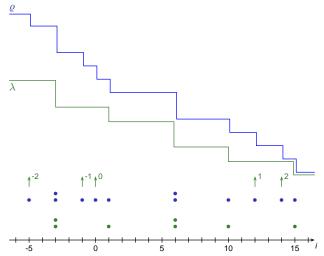
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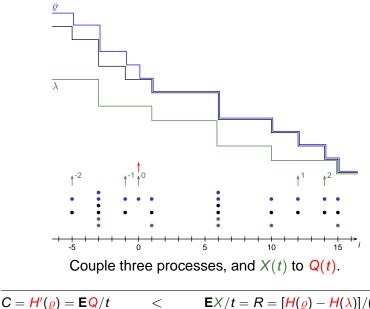


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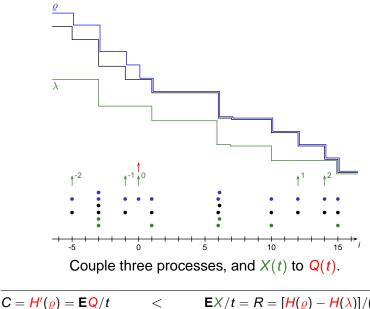
Do we have $Q(t) \stackrel{?}{\leq} X(t) + \text{tight error}$



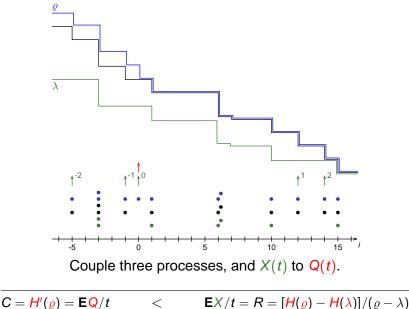


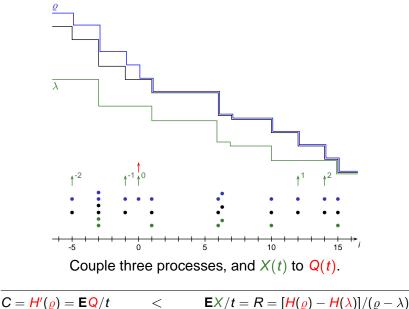


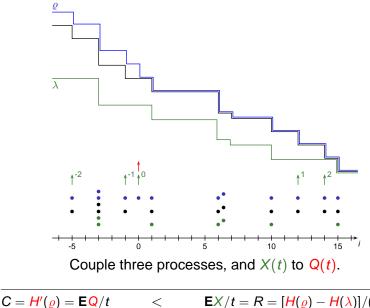
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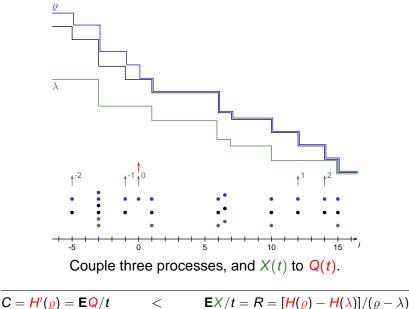
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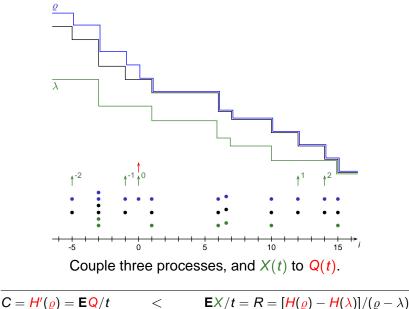


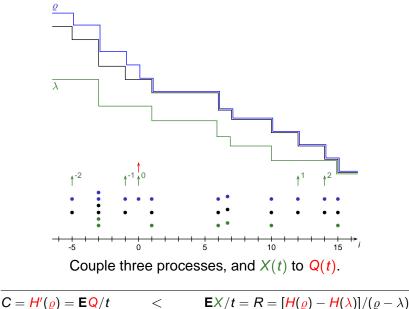


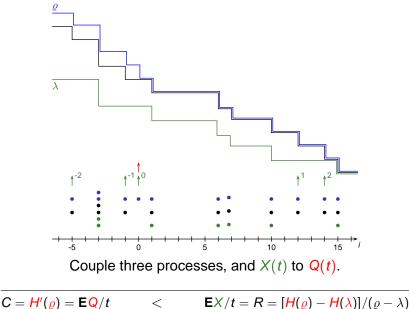


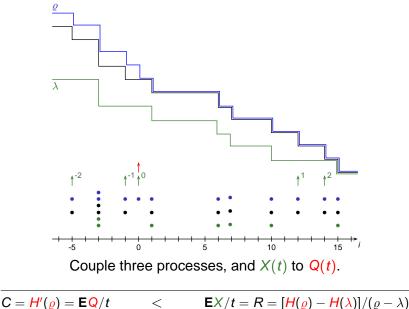
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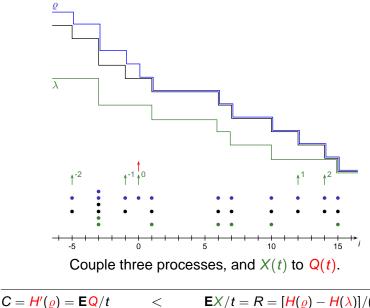


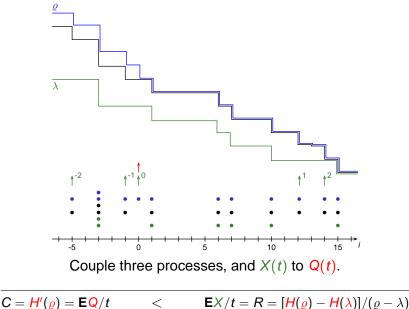


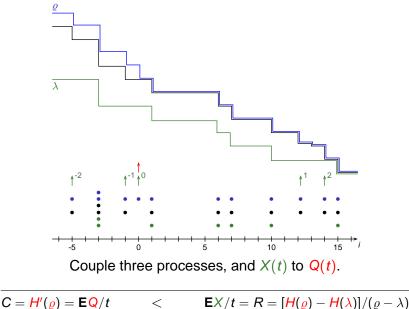


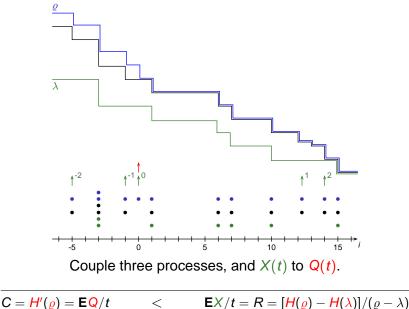


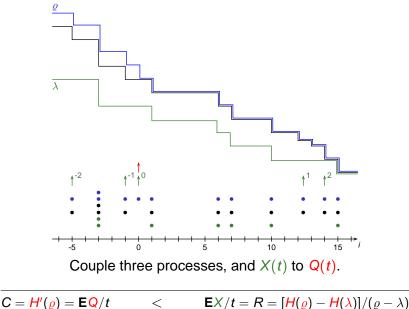


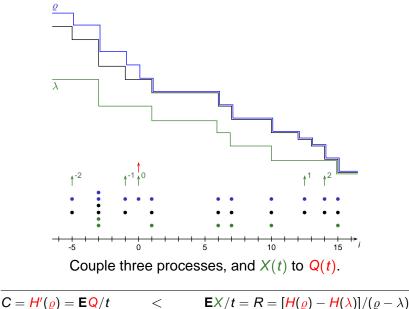


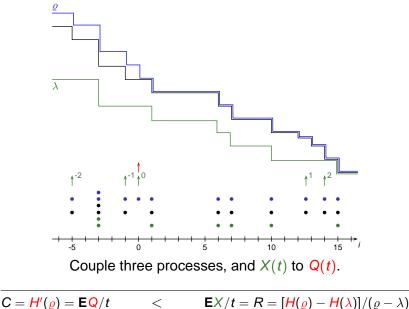


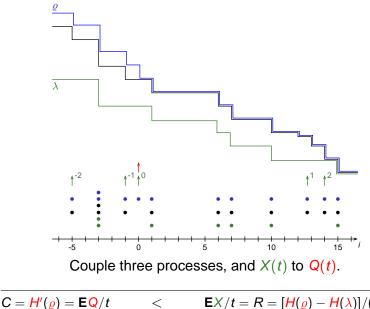


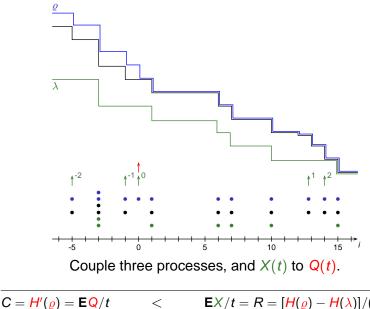


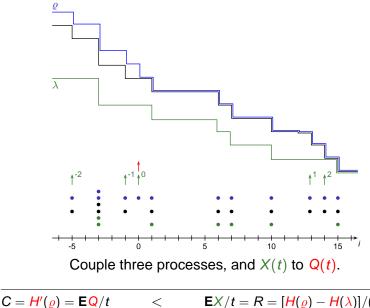


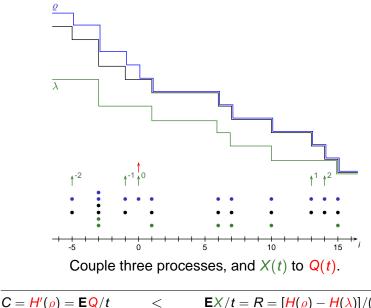


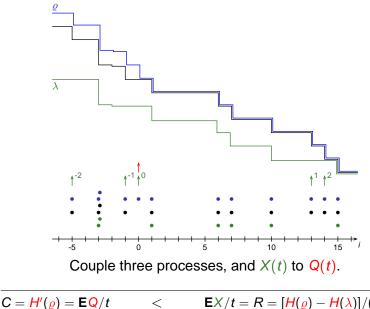


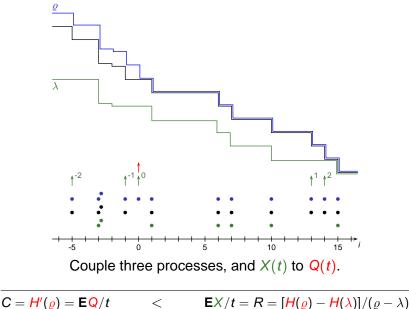


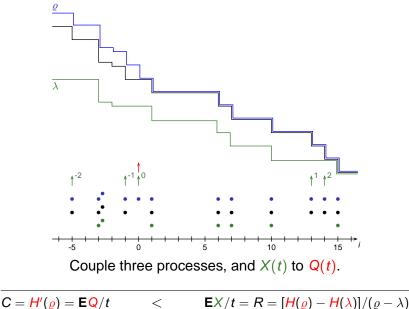


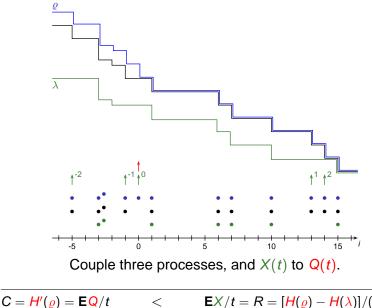


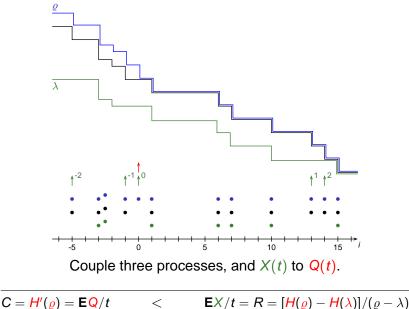


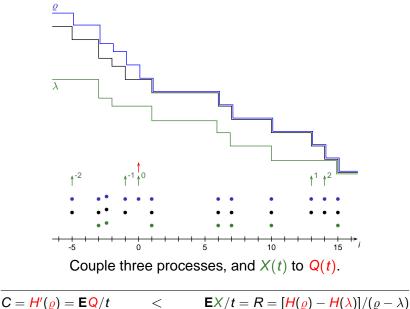


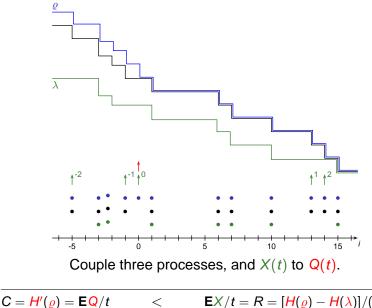


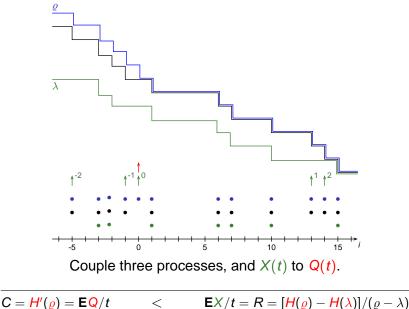


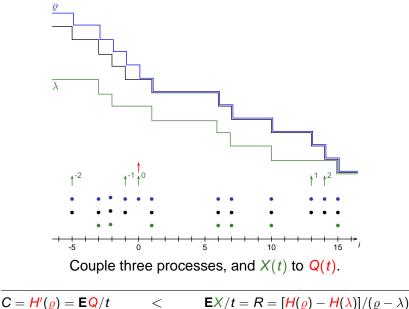


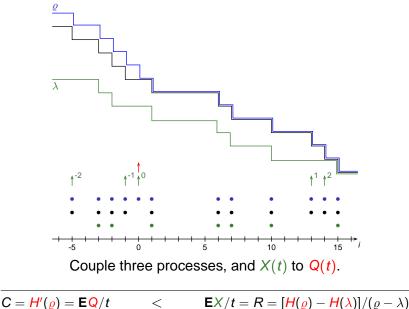


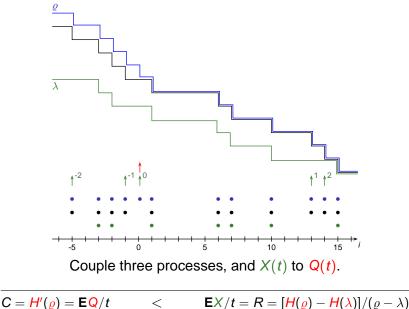


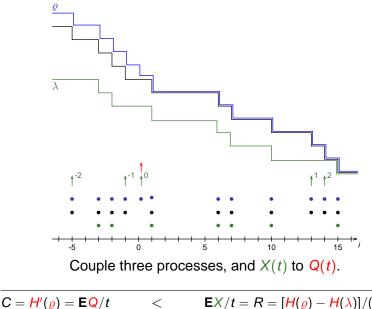


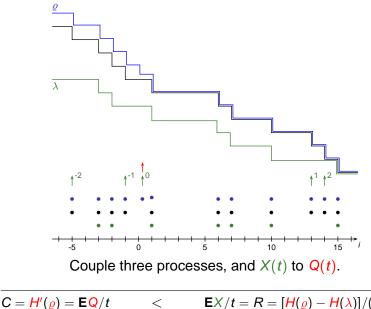


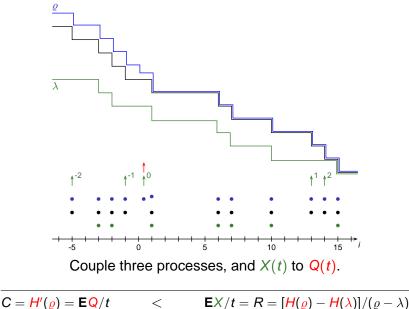


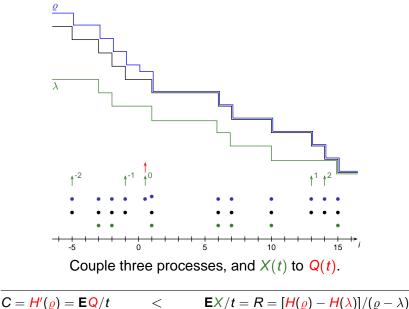


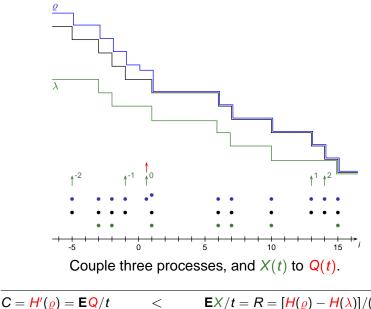


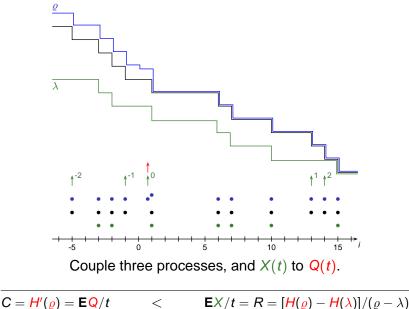


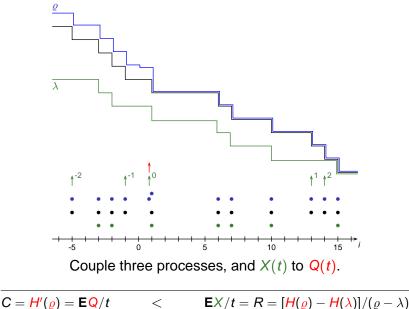


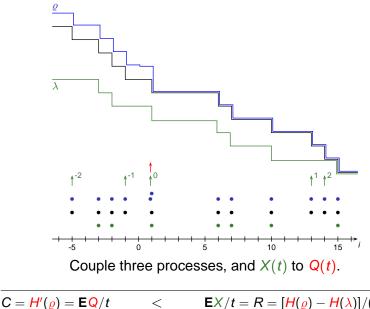


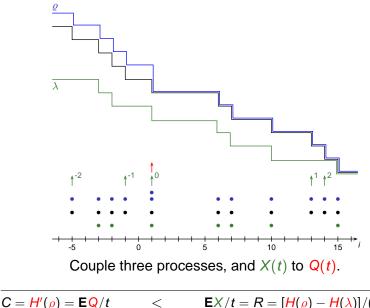


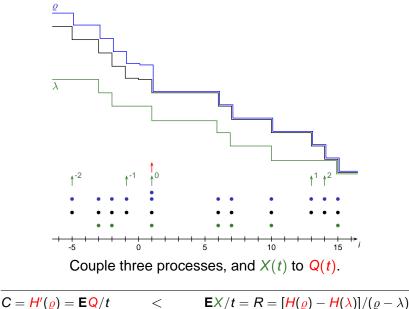


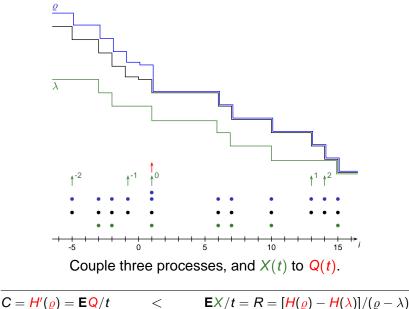


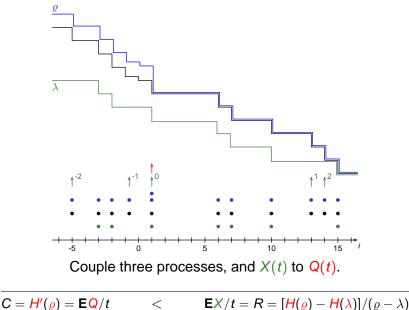


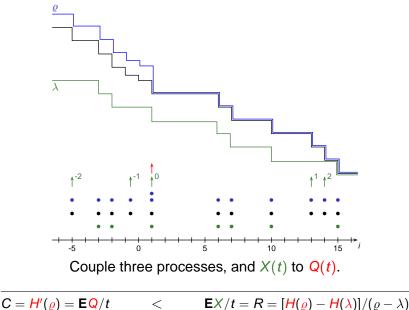


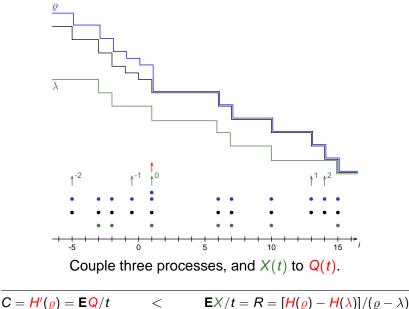


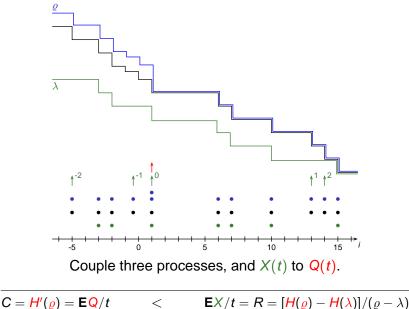


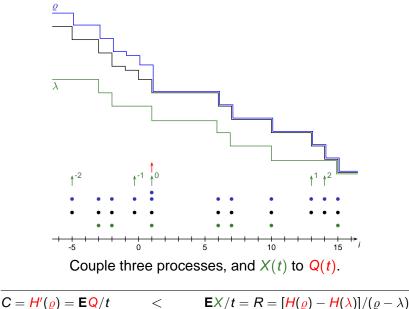


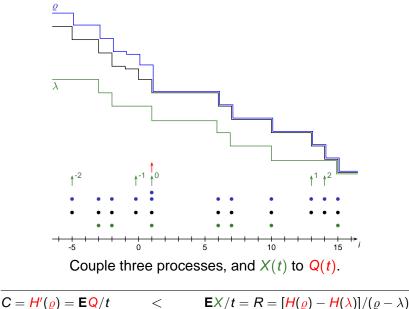


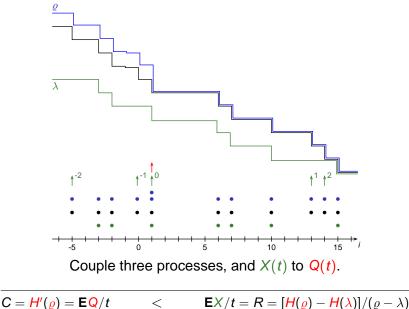


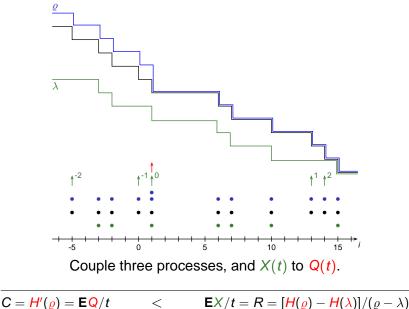


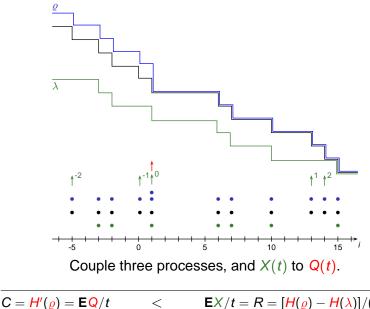


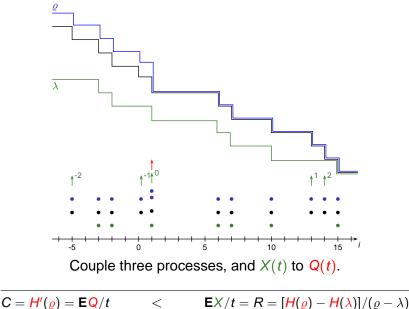


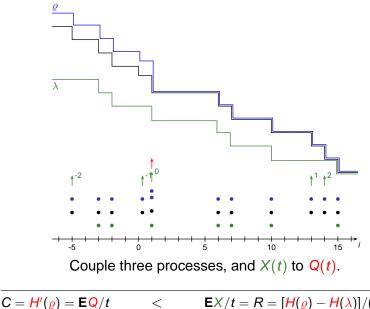


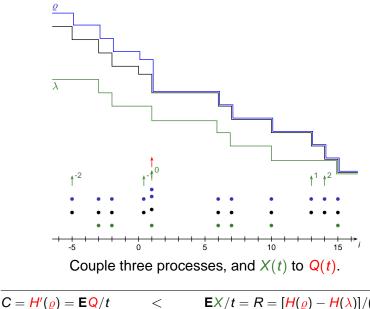


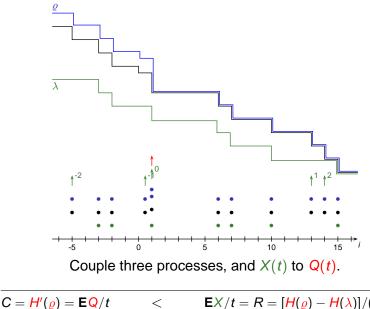


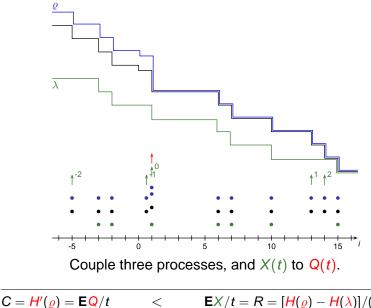


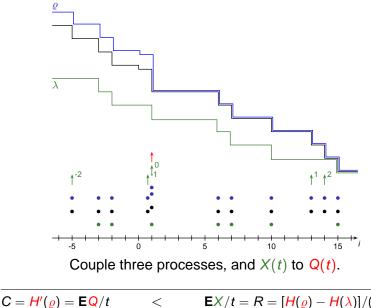


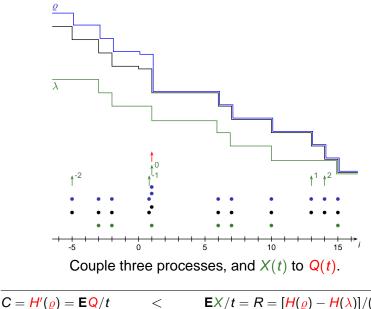


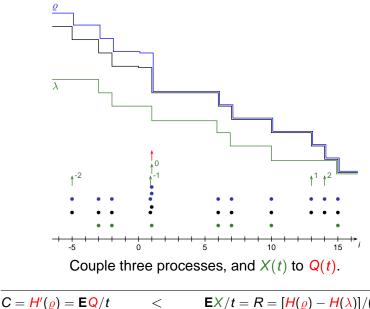


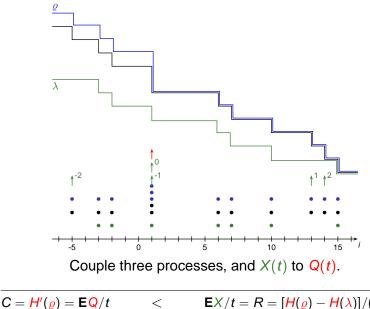


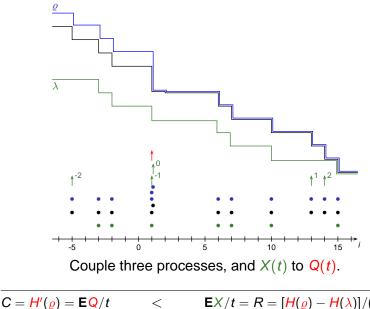


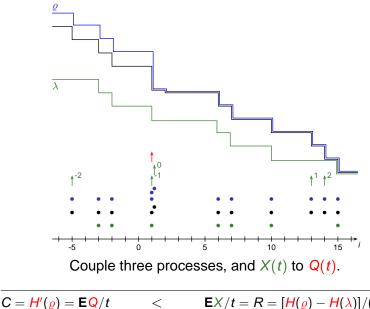


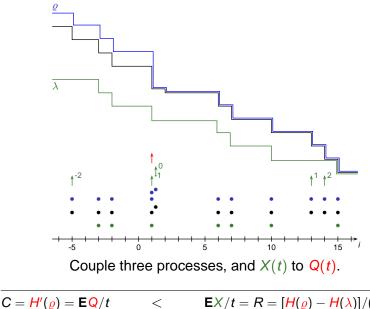


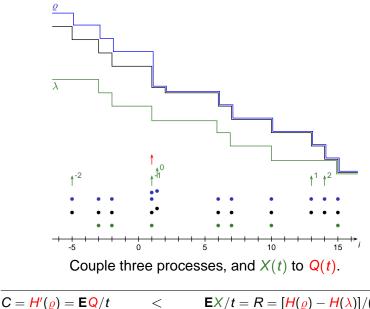


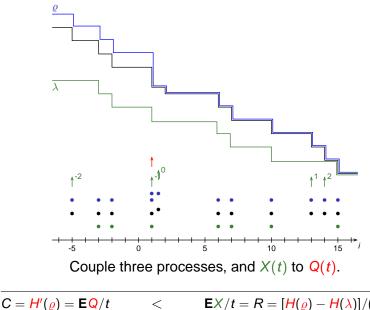


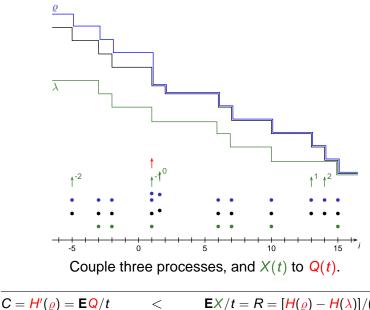


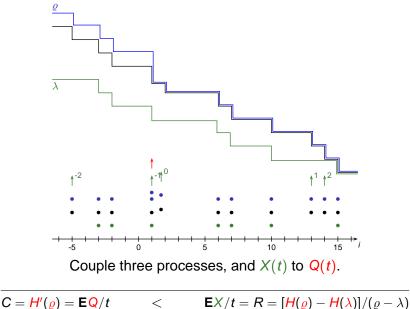


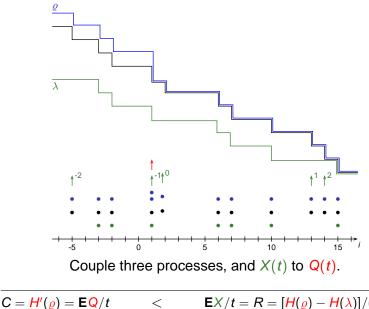


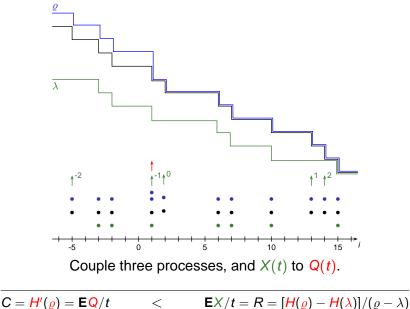


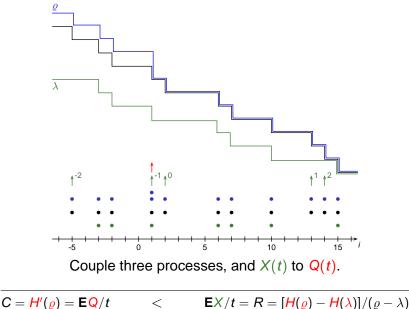












Microscopic convexity/concavity

We say that a model has the microscopic convexity property, if there is such a three-process coupling by which $Q(t) \ge X(t)$ -tight error can be achieved.

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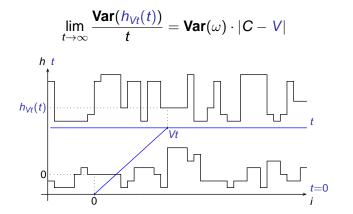
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Normal fluctuations:

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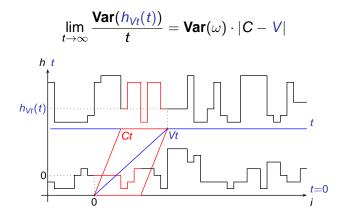
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Initial fluctuations are transported along the characteristics on this scale.

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$$0 < \liminf_{t \to \infty} \frac{\operatorname{Var}(h_{Ct}(t))}{t^{2/3}} \leq \limsup_{t \to \infty} \frac{\operatorname{Var}(h_{Ct}(t))}{t^{2/3}} < \infty.$$

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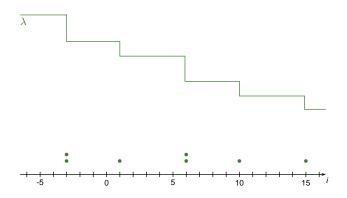
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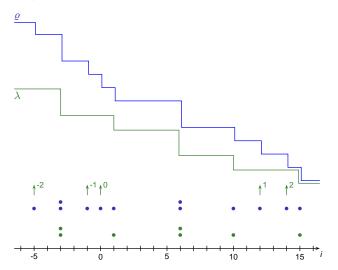
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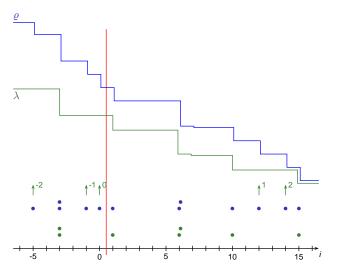
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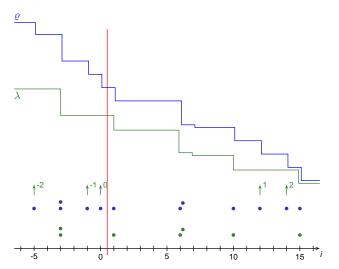
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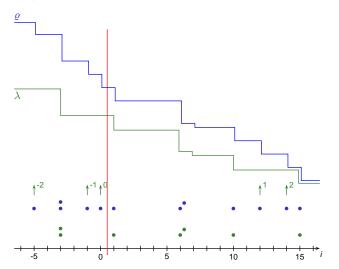
There is a huge literature now on limit distribution results, using combinatorial and asymptotic analytic tools.

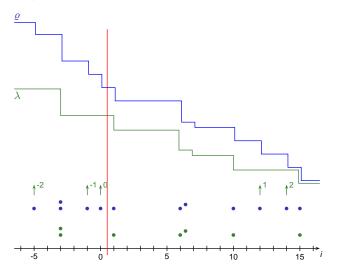


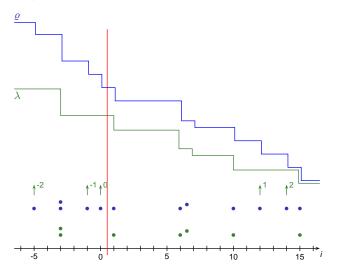


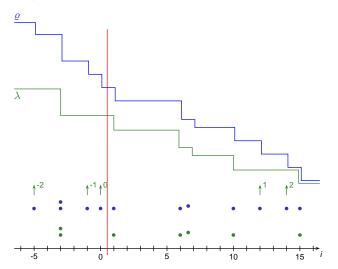


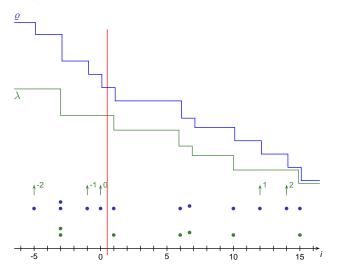


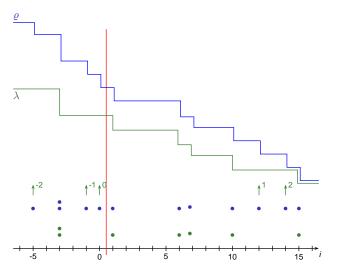


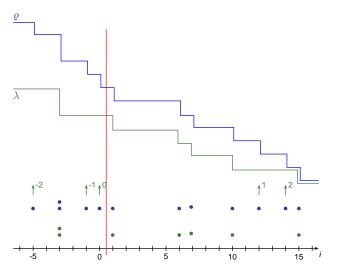


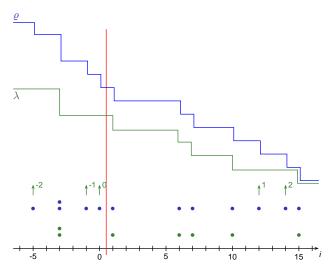


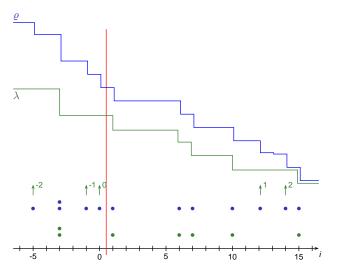


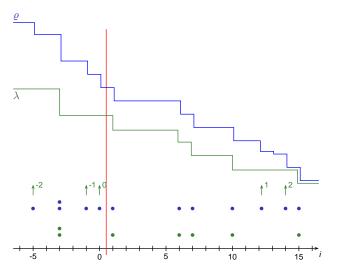


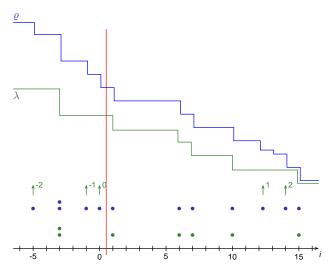


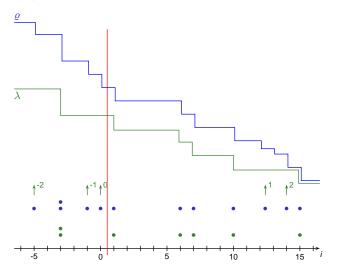


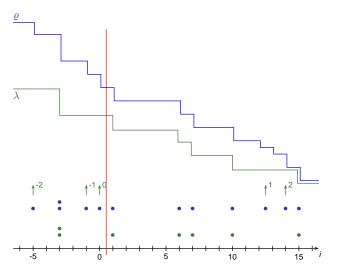


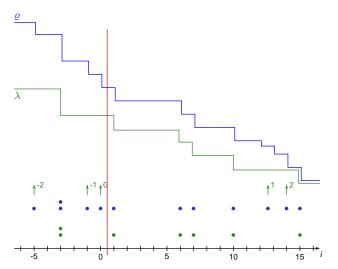


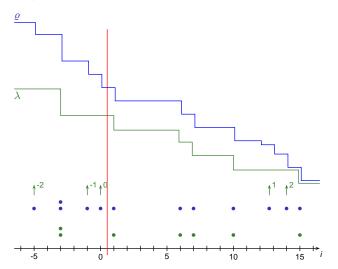


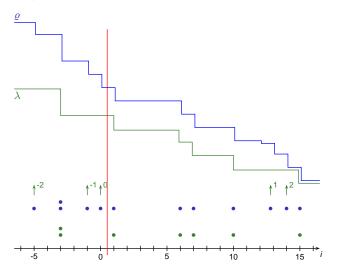


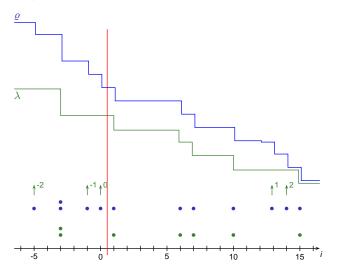


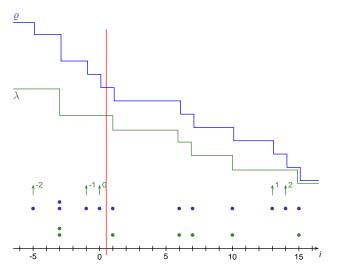


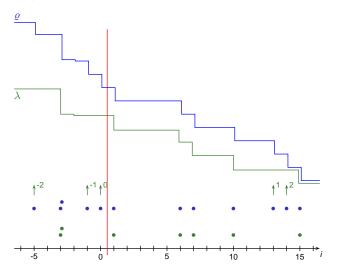


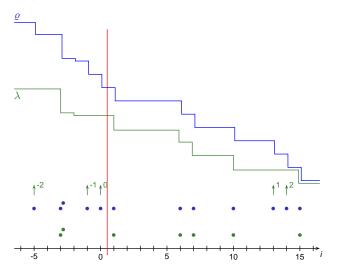


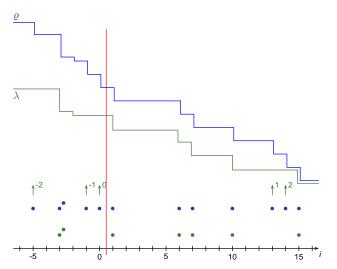


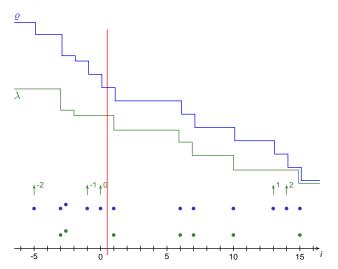


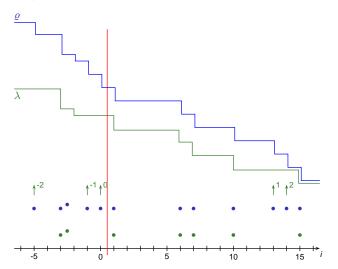


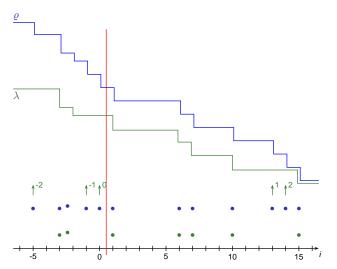


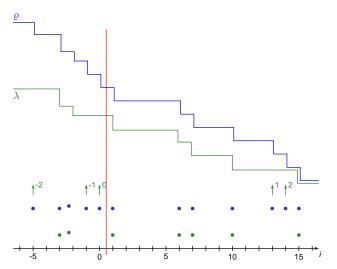


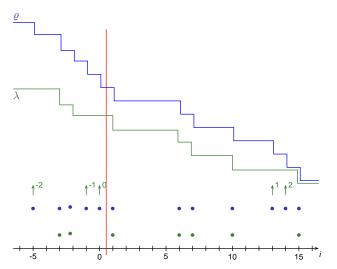


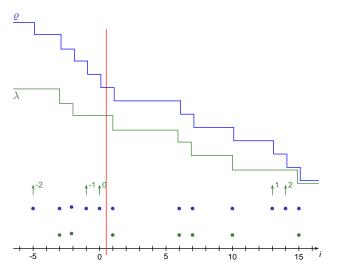


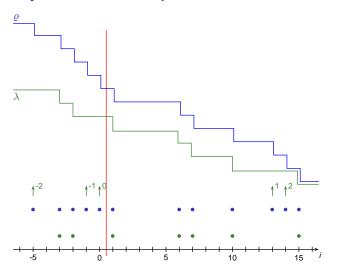


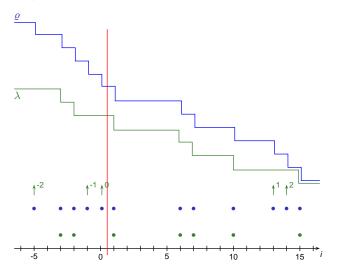


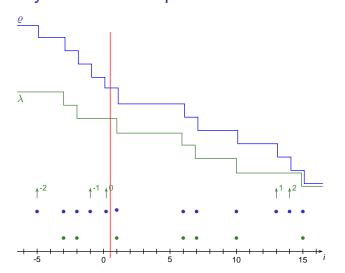


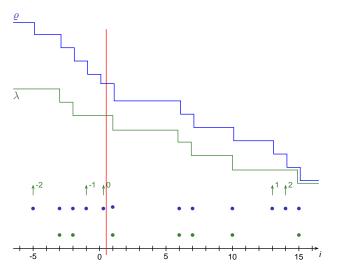


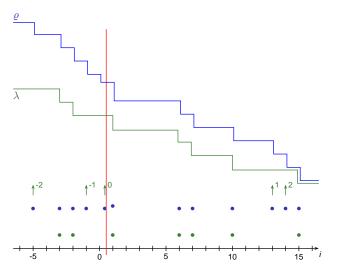


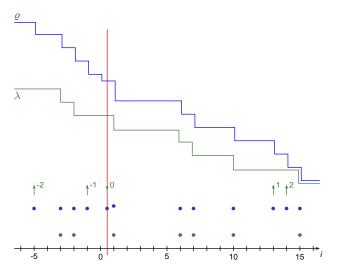


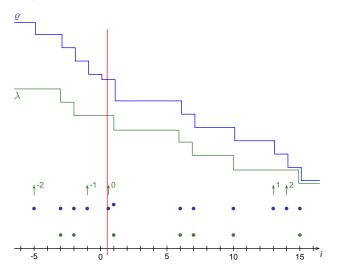


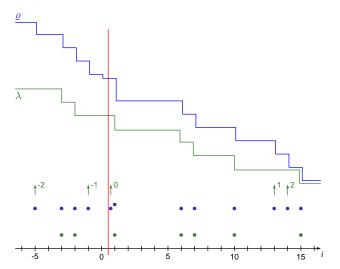


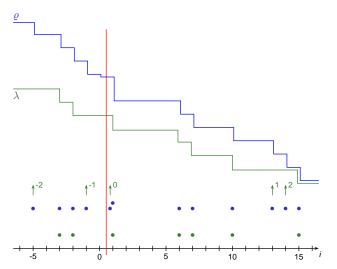


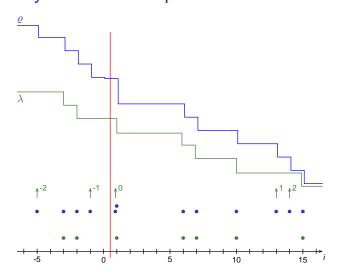


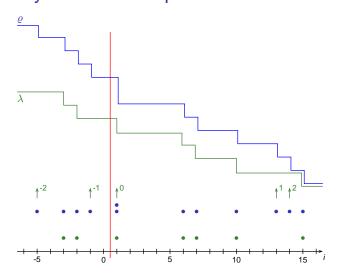


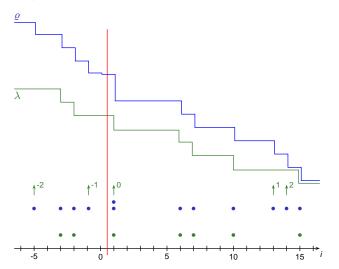


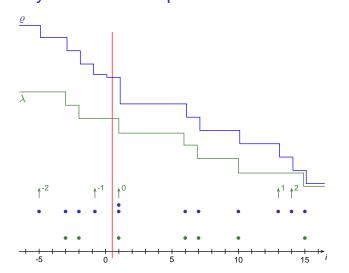


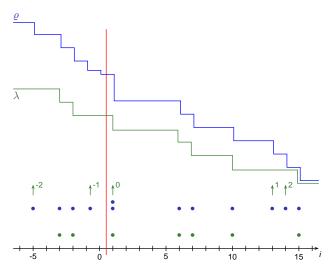


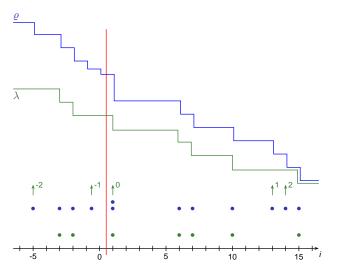


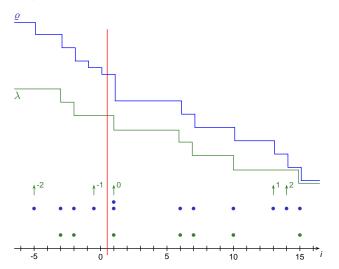


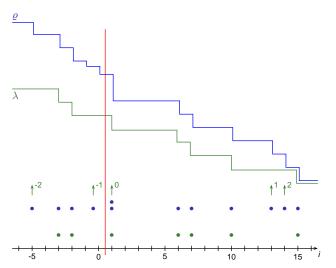


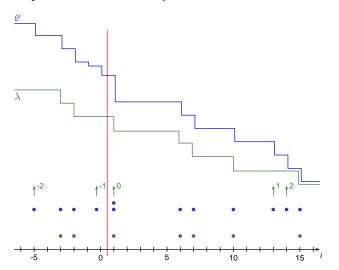


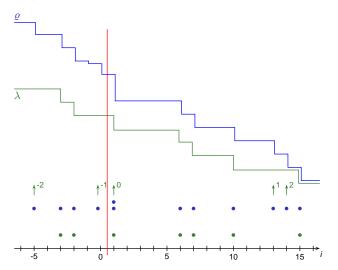


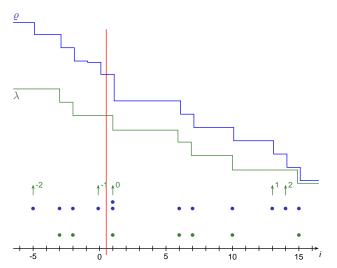


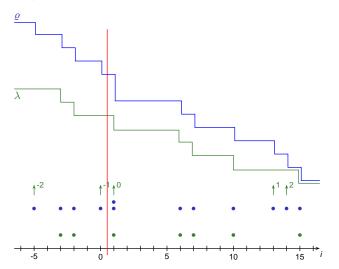


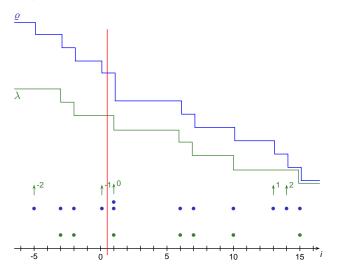


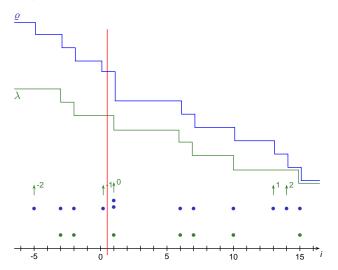


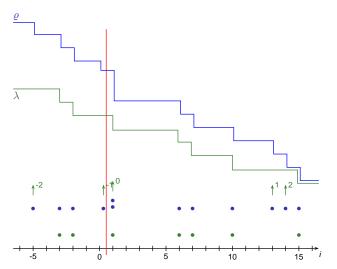


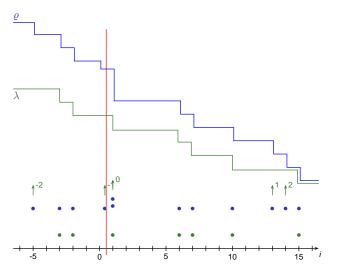


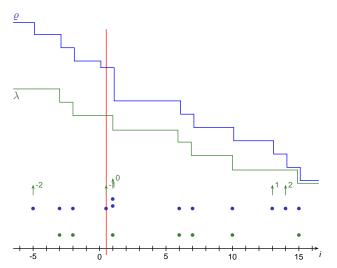


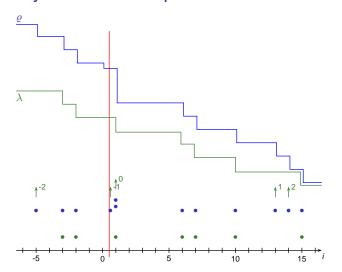


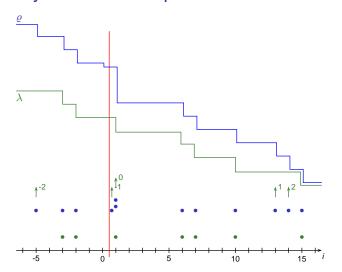


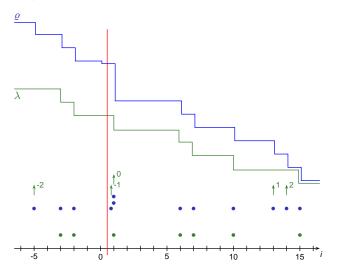


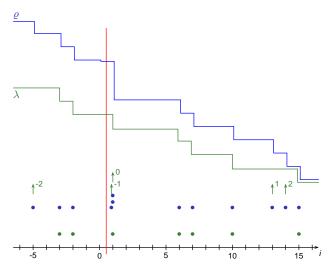


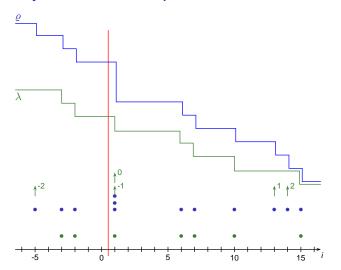


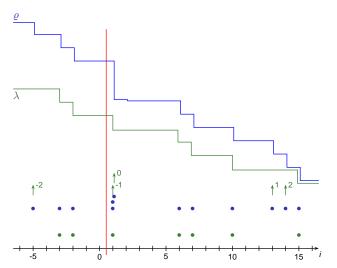


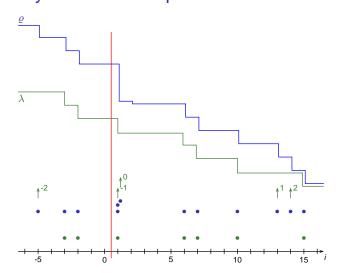


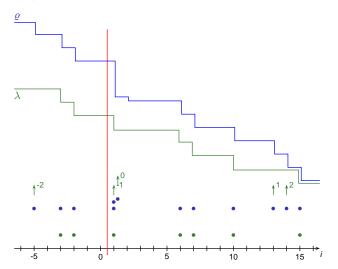


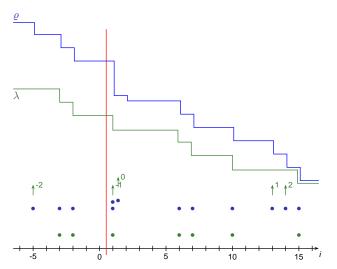


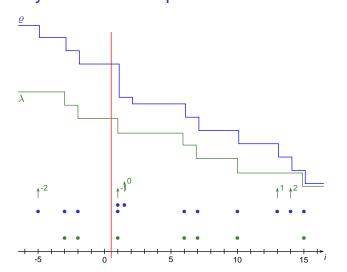


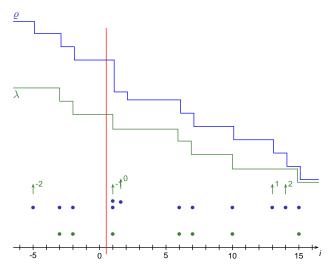


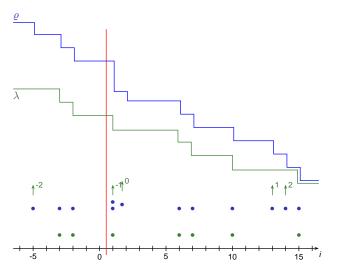




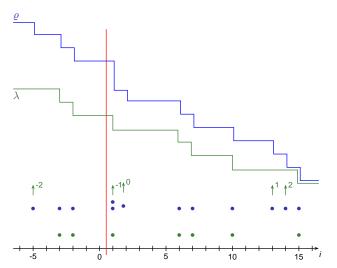






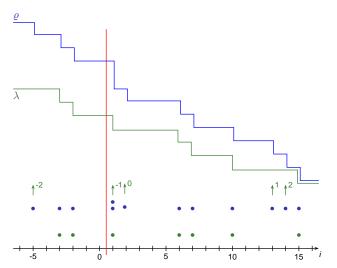


Proof: many second class particles



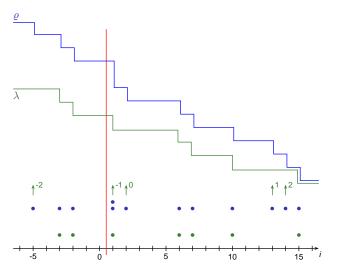
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Started from (almost) equilibrium,

 $\operatorname{Var}(h_{Ct}(t)) = c \cdot \mathsf{E}|\frac{\mathsf{Q}(t)}{\mathsf{Q}(t)} - C \cdot t|$

in the whole family of processes.

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 $\begin{array}{l} \underset{\mathbf{Q}(t)}{\text{with } \widetilde{\mathbf{Q}}(t) := \mathbf{Q}(t) - Ct \text{ and } E := \mathbf{E} |\widetilde{\mathbf{Q}}(t)|. \\ \mathbf{P} \{ \mathbf{Q}(t) - Ct \ge u \} \le c \cdot \frac{t^2}{u^4} \cdot \operatorname{Var}(h_{Ct}(t)) \\ \end{array}$

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that is, $E^3 \leq c \cdot t^2$.

$$\mathbf{P}\{|\widetilde{\mathbf{Q}}(t)| > u\} \le c \cdot \frac{t^2}{u^4} \cdot E$$

Upper bound We had $\mathbf{P}\{|\mathbf{Q}(t)| > u\} < c \cdot \frac{t^2}{t^4} \cdot E$. $E = \mathbf{E}|\widetilde{\mathbf{Q}}(t)| = \int_0^\infty \mathbf{P}\{|\widetilde{\mathbf{Q}}(t)| > u\} \, \mathrm{d}u$ $= E \int_{0}^{\infty} \mathbf{P}\{|\widetilde{\mathbf{Q}}(t)| > vE\} \, \mathrm{d}v$ $\leq E \int_{1/2}^{\infty} \mathbf{P}\{|\widetilde{\mathbf{Q}}(t)| > vE\} \, \mathrm{d}v + \frac{1}{2}E$ $\leq \mathbf{c}\cdot\frac{t^2}{E^2}+\frac{1}{2}E,$ that is, $E^3 < c \cdot t^2$. $\operatorname{Var}(h_{Ct}(t)) \stackrel{\mathsf{Thm}}{=} \operatorname{const.} \cdot \mathbf{E}[\mathbf{Q}(t) - Ct]$

$$= \text{ const.} \cdot E \leq c \cdot t^{2/3}.$$

$$\mathbf{P}\{|\widetilde{\mathbf{Q}}(t)| > u\} \le c \cdot \frac{t^2}{u^4} \cdot E$$

Lower bound

In the upper bound, the relevant orders were

$$u$$
 (deviation of $Q(t)$) ~ $t^{2/3}$, $\varrho - \lambda \sim t^{-1/3}$.

The lower bound works with similar arguments: compare models of which the densities differ by $t^{-1/3}$, and use connections between Q(t), X(t) and heights.

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The lower bound works with similar arguments: compare models of which the densities differ by $t^{-1/3}$, and use connections between Q(t), X(t) and heights.

The critical feature in both the upper bound and lower bound was microscopic convexity/concavity: $Q(t) \ge X(t)$ (convex) or $Q(t) \le X(t)$ (concave).

Model	<u>Η(</u> _{<i>ℓ</i>}) is	Micro c.?	<i>t</i> ^{2/3} law

Model	<u> </u>	Micro c.?	$t^{2/3}$ law
TASEP			

Model	<u>Η(</u> ₀) is	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave		
	1		

Model	<u> </u>	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave	$Q(t) \leq X(t)$	

Model	<u> </u>	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave	$Q(t) \leq X(t)$	proved (BS.)

Model	$H(\varrho)$ is	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave	$Q(t) \leq X(t)$	proved (BS.)
ASEP (WASEP)			
	1		

Model	<u>Η(</u> ₀) is	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave	$Q(t) \leq X(t)$	proved (BS.)
ASEP (WASEP)	concave		

Model	<i>Η</i> (<i>ϱ</i>) is	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave	$Q(t) \leq X(t)$	proved (BS.)
ASEP (WASEP)	concave	$Q(t) \leq X(t) + Err$	

Model	<u> </u>	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave	$Q(t) \leq X(t)$	proved (BS.)
ASEP (WASEP)	concave	$Q(t) \leq X(t) + Err$	proved (<mark>BS</mark> .)

Model	<u>Η(</u> ₀) is	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave	$Q(t) \leq X(t)$	proved (BS.)
ASEP (WASEP)	concave	$Q(t) \le X(t) + Err$	proved (<mark>BS</mark> .)
rate 1 TAZRP			
	1	I	I

Model	<u>Η(</u> ₀) is	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave	$Q(t) \leq X(t)$	proved (BS.)
ASEP (WASEP)	concave	$Q(t) \le X(t) + Err$	proved (BS.)
rate 1 TAZRP	concave		

Model	<u> </u>	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave	$Q(t) \leq X(t)$	proved (BS.)
ASEP (WASEP)	concave	$Q(t) \leq X(t) + Err$	proved (BS.)
rate 1 TAZRP	concave	$Q(t) \leq X(t)$	

Model	<u> </u>	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave	$Q(t) \leq X(t)$	proved (BS.)
ASEP (WASEP)	concave	$Q(t) \leq X(t) + Err$	proved (<mark>BS</mark> .)
rate 1 TAZRP	concave	$Q(t) \leq X(t)$	proved (BK.)

Model	<u> </u>	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave	$Q(t) \leq X(t)$	proved (BS.)
ASEP (WASEP)	concave	$Q(t) \leq X(t) + Err$	proved (BS.)
rate 1 TAZRP	concave	$Q(t) \leq X(t)$	proved (BK.)
concave exp rate TAZRP			

Model	<i>Η</i> (<i>ϱ</i>) is	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave	$Q(t) \leq X(t)$	proved (BS.)
ASEP (WASEP)	concave	$Q(t) \leq X(t) + Err$	proved (BS.)
rate 1 TAZRP	concave	$Q(t) \leq X(t)$	proved (BK.)
concave exp rate TAZRP	concave		

Model	<u></u> <i>Η</i> (<i>ϱ</i>) is	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave	$Q(t) \leq X(t)$	proved (BS.)
ASEP (WASEP)	concave	$Q(t) \leq X(t) + Err$	proved (BS.)
rate 1 TAZRP	concave	$Q(t) \leq X(t)$	proved (<mark>BK.</mark>)
concave exp rate TAZRP	concave	$Q(t) \le X(t) + Err$	

<i>Η</i> (<i>ϱ</i>) is	Micro c.?	<i>t</i> ^{2/3} law
concave	$Q(t) \leq X(t)$	proved (BS.)
concave	$Q(t) \leq X(t) + Err$	proved (BS.)
concave	$Q(t) \leq X(t)$	proved (BK.)
concave	$Q(t) \le X(t) + Err$	proved (BKS.)
	concave concave concave	concave $Q(t) \le X(t)$ concave $Q(t) \le X(t) + \text{Err}$ concave $Q(t) \le X(t)$

Model	<i>Η</i> (<i>ϱ</i>) is	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave	$Q(t) \leq X(t)$	proved (BS.)
ASEP (WASEP)	concave	$Q(t) \leq X(t) + Err$	proved (BS.)
rate 1 TAZRP	concave	$Q(t) \leq X(t)$	proved (<mark>BK</mark> .)
concave exp rate TAZRP	concave	$Q(t) \le X(t) + Err$	proved (BKS.)
convex exp rate TABLP			

Model	<u> </u>	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave	$Q(t) \leq X(t)$	proved (BS.)
ASEP (WASEP)	concave	$Q(t) \le X(t) + Err$	proved (BS.)
rate 1 TAZRP	concave	$Q(t) \leq X(t)$	proved (BK.)
concave exp rate TAZRP	concave	$Q(t) \le X(t) + Err$	proved (BKS.)
convex exp rate TABLP	convex		

Model	<u> </u>	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave	$Q(t) \leq X(t)$	proved (BS.)
ASEP (WASEP)	concave	$Q(t) \leq X(t) + Err$	proved (BS.)
rate 1 TAZRP	concave	$Q(t) \leq X(t)$	proved (BK.)
concave exp rate TAZRP	concave	$Q(t) \le X(t) + Err$	proved (<mark>BKS</mark> .)
convex exp rate TABLP	convex	$Q(t) \ge X(t) - Err$	

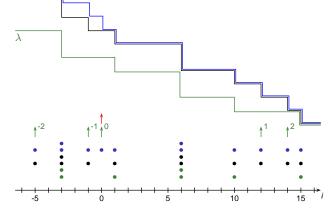
Model	<u> </u>	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave	$Q(t) \leq X(t)$	proved (BS.)
ASEP (WASEP)	concave	$Q(t) \le X(t) + Err$	proved (BS.)
rate 1 TAZRP	concave	$Q(t) \leq X(t)$	proved (BK.)
concave exp rate TAZRP	concave	$Q(t) \le X(t) + Err$	proved (BKS.)
convex exp rate TABLP	convex	$Q(t) \ge X(t) - Err$	proved (BKS.)

Model	<u>Η(</u> ₂) is	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave	$Q(t) \leq X(t)$	proved (BS.)
ASEP (WASEP)	concave	$Q(t) \leq X(t) + Err$	proved (BS.)
rate 1 TAZRP	concave	$Q(t) \leq X(t)$	proved (BK.)
concave exp rate TAZRP	concave	$Q(t) \le X(t) + Err$	proved (BKS.)
convex exp rate TABLP	convex	$Q(t) \ge X(t) - Err$	proved (BKS.)
less concave/convex rate (T)AZRP, (T)ABLP			

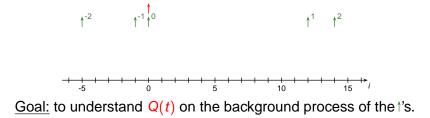
Model	<u>Η(</u> ₀) is	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave	$Q(t) \leq X(t)$	proved (BS.)
ASEP (WASEP)	concave	$Q(t) \le X(t) + Err$	proved (BS.)
rate 1 TAZRP	concave	$Q(t) \leq X(t)$	proved (BK.)
concave exp rate TAZRP	concave	$Q(t) \le X(t) + Err$	proved (BKS.)
convex exp rate TABLP	convex	$Q(t) \ge X(t) - Err$	proved (BKS.)
less concave/convex rate (T)AZRP, (T)ABLP	concave/ convex		

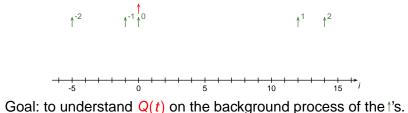
Model	<u></u> <i>H</i> (<i>ρ</i>) is	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave	$Q(t) \leq X(t)$	proved (BS.)
ASEP (WASEP)	concave	$Q(t) \le X(t) + Err$	proved (<mark>BS</mark> .)
rate 1 TAZRP	concave	$Q(t) \leq X(t)$	proved (BK.)
concave exp rate TAZRP	concave	$Q(t) \le X(t) + Err$	proved (BKS.)
convex exp rate TABLP	convex	$Q(t) \ge X(t) - Err$	proved (BKS.)
less concave/convex rate (T)AZRP, (T)ABLP	concave/ convex	??	

Model	<u>Η(</u> _ℓ) is	Micro c.?	<i>t</i> ^{2/3} law
TASEP	concave	$Q(t) \leq X(t)$	proved (BS.)
ASEP (WASEP)	concave	$Q(t) \le X(t) + Err$	proved (<mark>BS</mark> .)
rate 1 TAZRP	concave	$Q(t) \leq X(t)$	proved (BK.)
concave exp rate TAZRP	concave	$Q(t) \le X(t) + Err$	proved (BKS.)
convex exp rate TABLP	convex	$Q(t) \ge X(t) - Err$	proved (BKS.)
less concave/convex rate (T)AZRP, (T)ABLP	concave/ convex	??	??

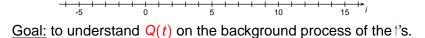


<u>Goal</u>: to understand Q(t) on the background process of the t's.

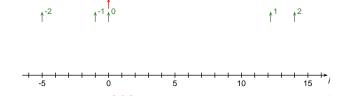




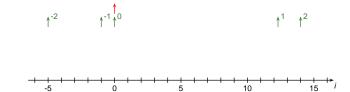




 $m_{\mathsf{Q}}(t) = [\text{the label of } \uparrow \text{ at } \mathbf{Q}(t)] = 0$ $m_{\mathsf{Q}}(t) \le 0 \Rightarrow \mathbf{Q}(t) \le X(t).$

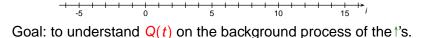


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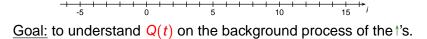


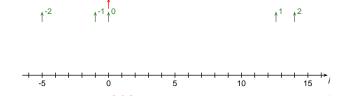
<u>Goal</u>: to understand Q(t) on the background process of the t's.





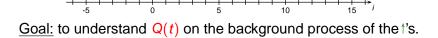




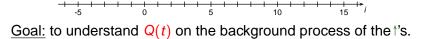


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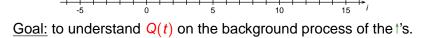




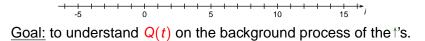




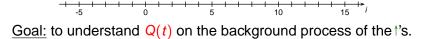




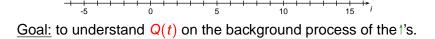




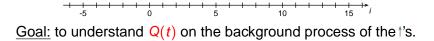




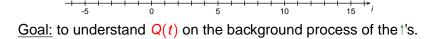




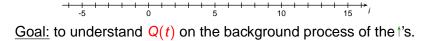




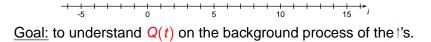




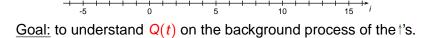




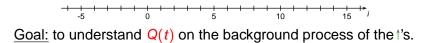




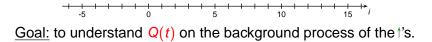




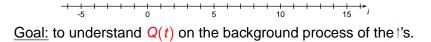




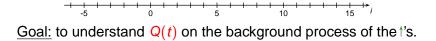




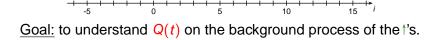




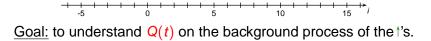




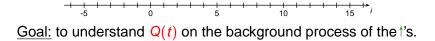




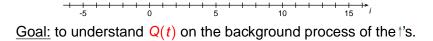


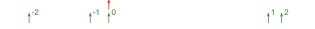


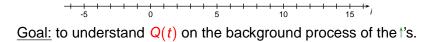


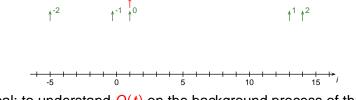




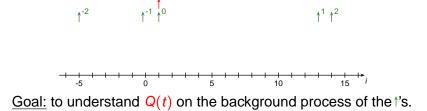


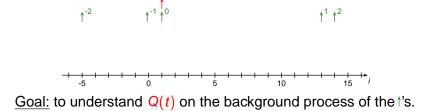


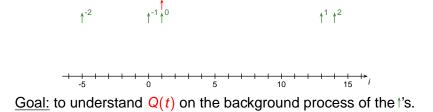


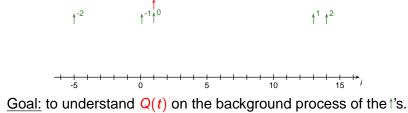


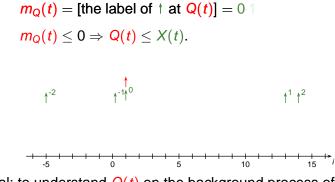
<u>Goal</u>: to understand Q(t) on the background process of the t's.



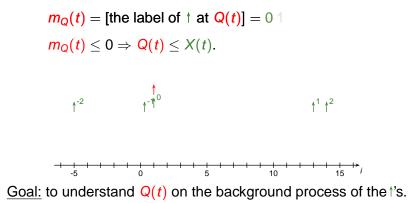


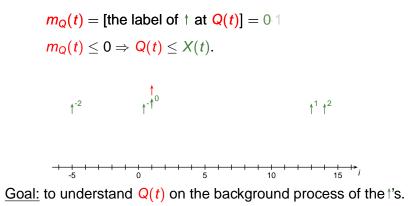


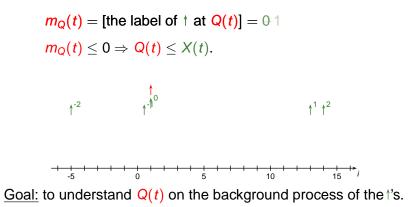


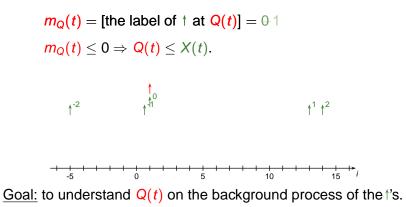


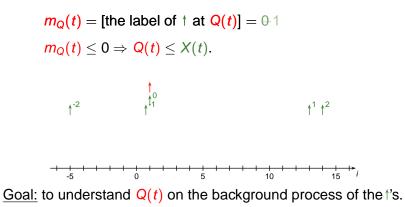
<u>Goal</u>: to understand Q(t) on the background process of the t's.

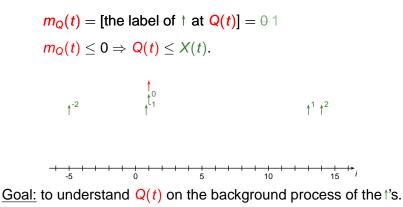


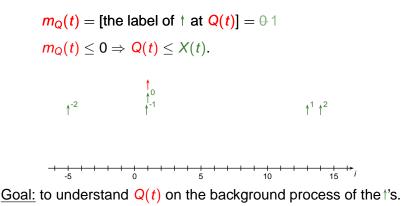


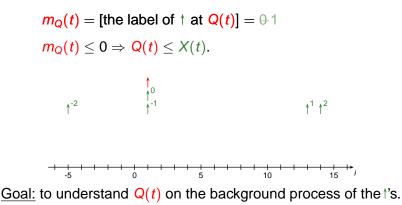


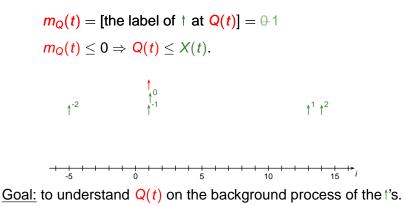


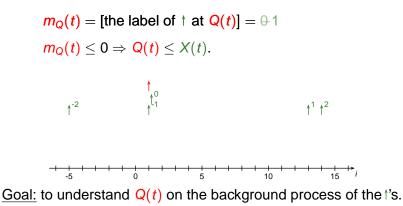


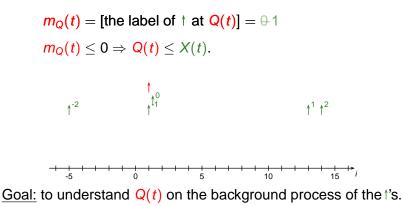


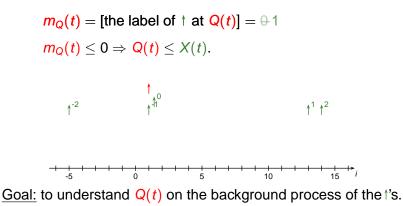


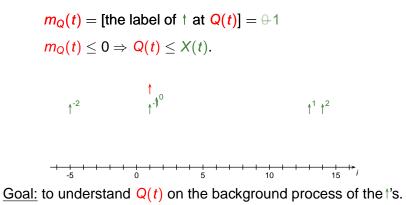


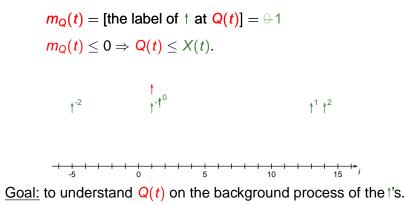


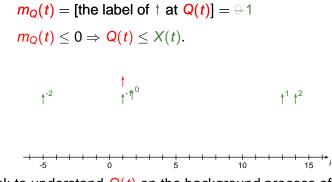










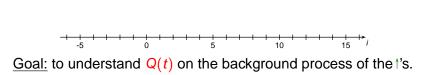


<u>Goal</u>: to understand Q(t) on the background process of the t's.

 $m_{\mathsf{Q}}(t) = [\text{the label of } \uparrow \text{ at } \mathbf{Q}(t)] = \oplus 1$ $m_{\mathsf{Q}}(t) \le 0 \Rightarrow \mathbf{Q}(t) \le X(t).$

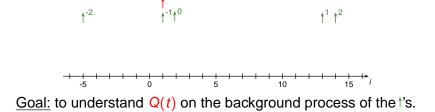
> ↑ ≜-1↑⁰

^-2

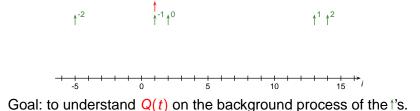


¹ ¹ ²

 $m_{\mathsf{Q}}(t) = [\text{the label of } \uparrow \text{ at } \mathbf{Q}(t)] = -1$ $m_{\mathsf{Q}}(t) \le 0 \Rightarrow \mathbf{Q}(t) \le X(t).$



 $m_{\mathsf{Q}}(t) = [\text{the label of } \uparrow \text{ at } \mathbf{Q}(t)] = -1$ $m_{\mathsf{Q}}(t) \le 0 \Rightarrow \mathbf{Q}(t) \le X(t).$



This process $m_Q(t)$ is influenced by the background, and is pretty complicated in general.

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This is the form of microscopic concavity we currently use: $m_Q(t)$ is dominated by a time-independent distribution with finite variance.

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Once this is done, we could proceed with less and less convex/concave models to see how $t^{1/3}$ scaling turns to $t^{1/4}$ for linear models (random average process, linear rate AZRP)...

Thank you.