A microscopic concavity property and $t^{1/3}$ scaling of current fluctuations in particle systems I.

Joint with Júlia Komjáthy and Timo Seppäläinen

Márton Balázs

Budapest University of Technology and Economics

Interacting Particle Systems and Percolation IHP October 27, 2008.

The models

Asymmetric simple exclusion process Zero range Bricklayers

Hydrodynamics

Characteristics

Tool: the second class particle

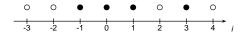
Single Many second class particles

Results

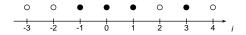
Normal fluctuations Abnormal fluctuations

Proof

Upper bound Microscopic concavity/convexity



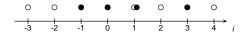
Bernoulli(ϱ) distribution; $\omega_i = 0$ or 1.



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Particles try to jump

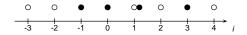
to the right with rate p, to the left with rate q = 1 - p < p.



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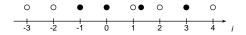
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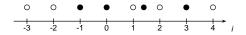
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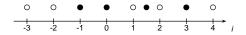
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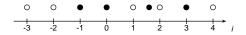
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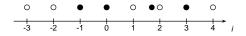
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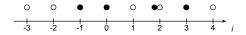
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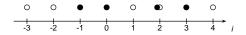
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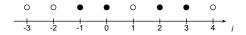
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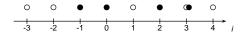
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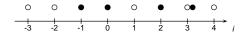
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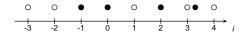
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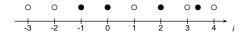
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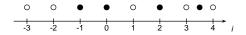
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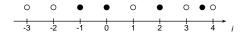
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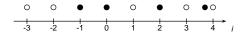
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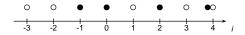
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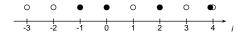
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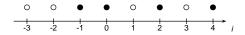
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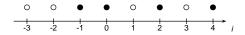
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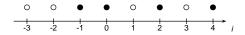
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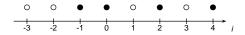
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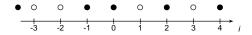
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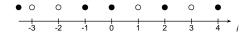
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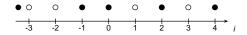
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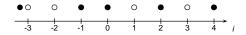
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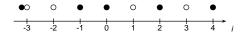
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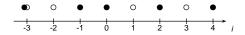
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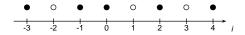
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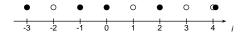
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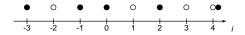
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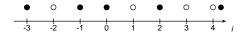
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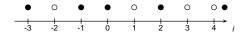
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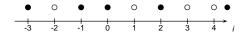
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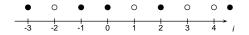
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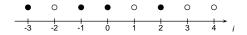
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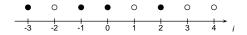
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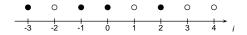
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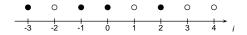
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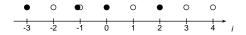
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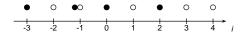
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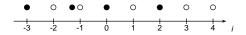
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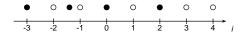
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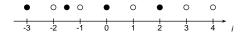
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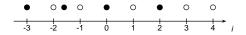
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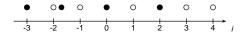
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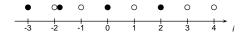
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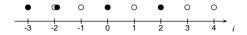
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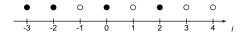
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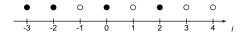
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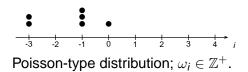
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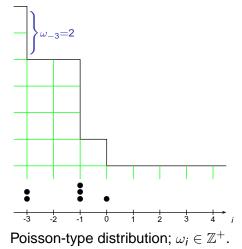
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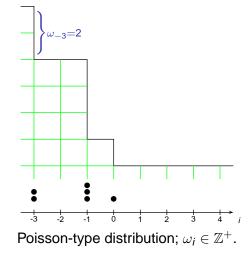
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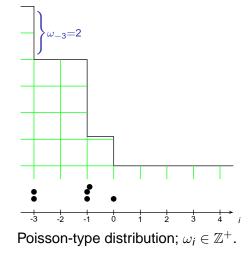
The jump is suppressed if the destination site is occupied by another particle.

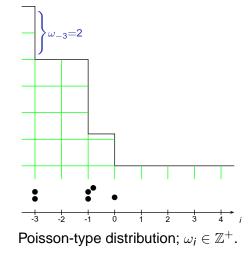
The Bernoulli(ϱ) distribution is time-stationary for any ($0 \le \varrho \le 1$). Any translation-invariant stationary distribution is a mixture of Bernoullis.

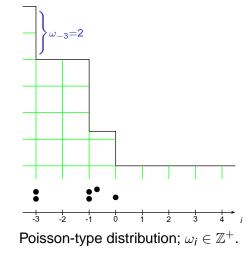


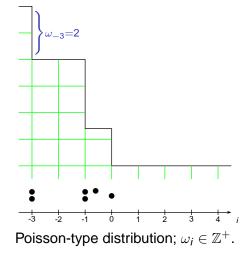


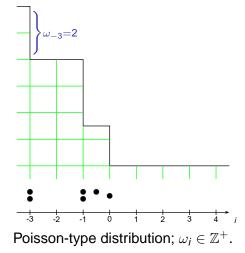


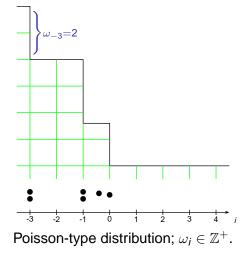


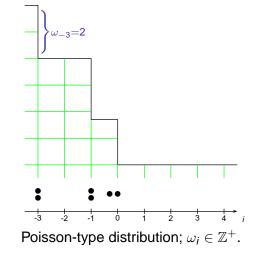






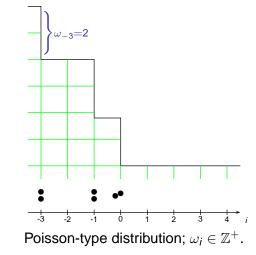


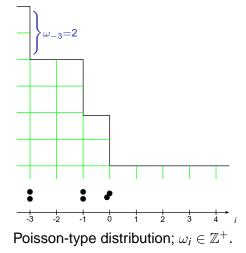


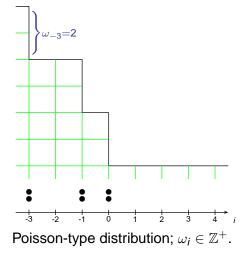


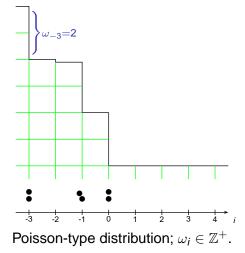
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The asymmetric zero range process



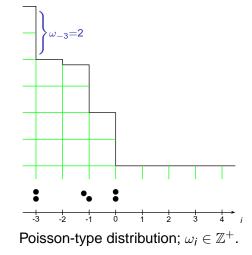


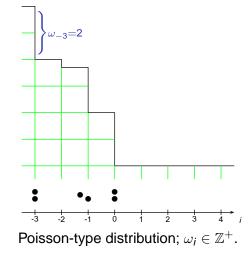


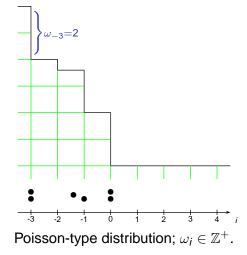


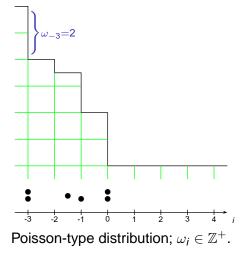
AZRP ABLP

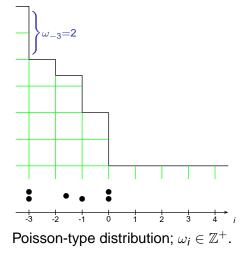
The asymmetric zero range process

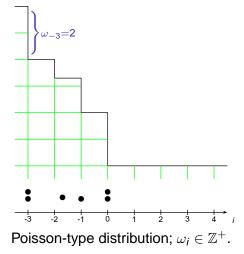


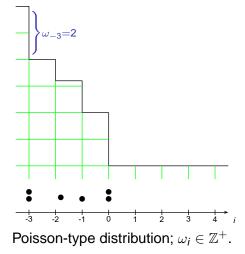


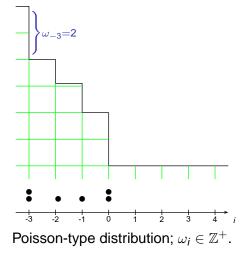


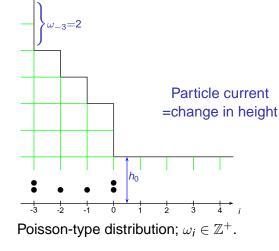


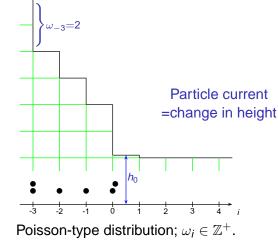


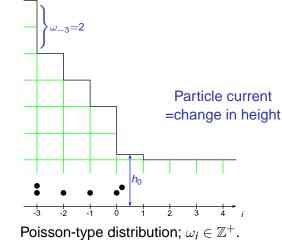


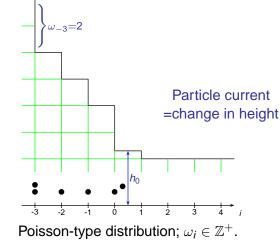


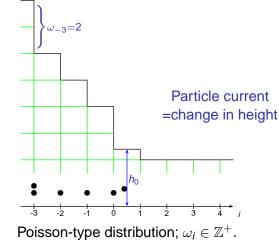


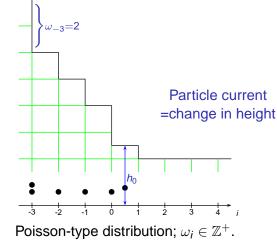


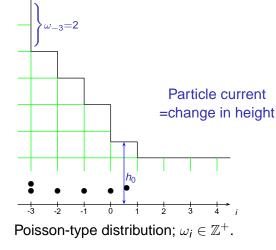


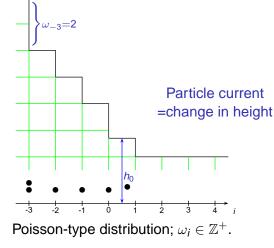


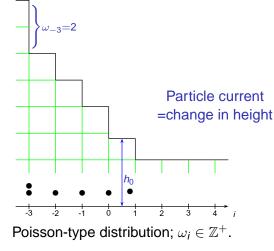


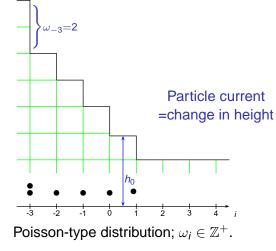


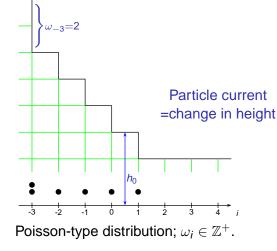


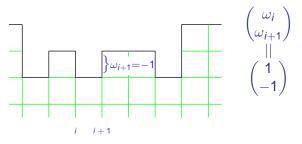




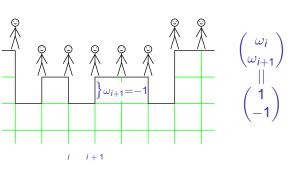






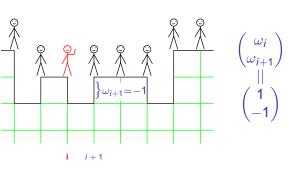


Poisson-type distribution; $\omega_i \in \mathbb{Z}$.



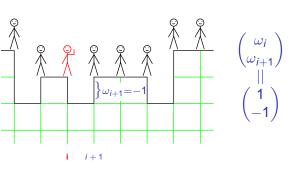
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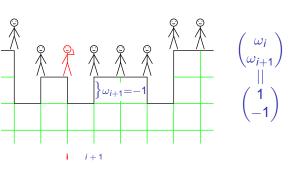
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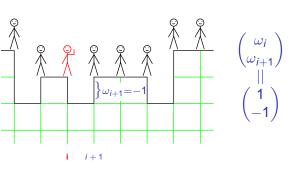
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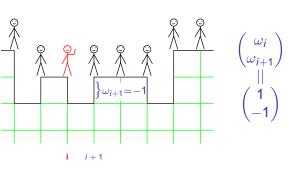
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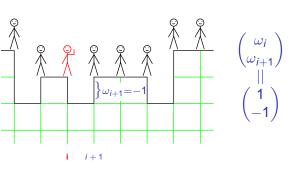
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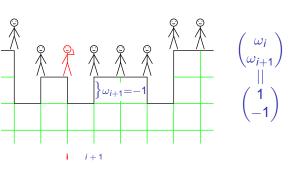
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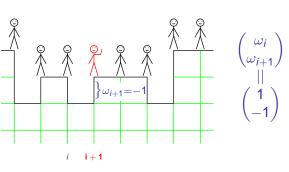
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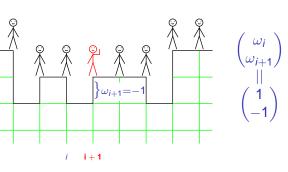
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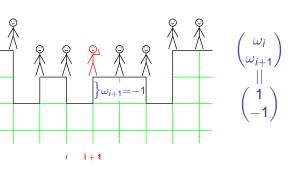
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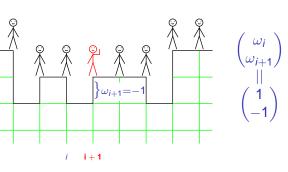
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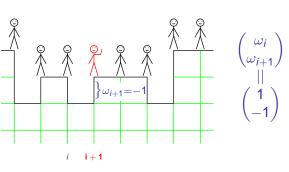
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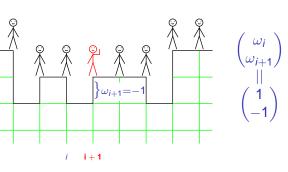
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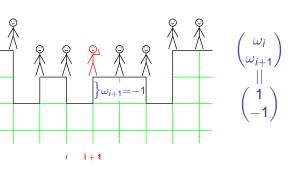
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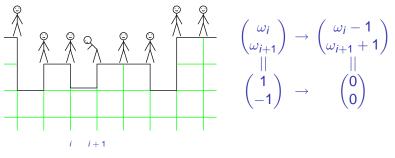
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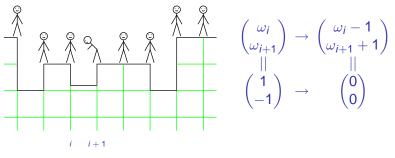
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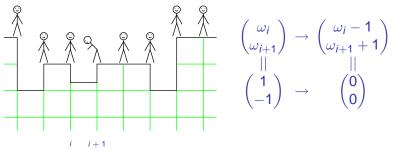
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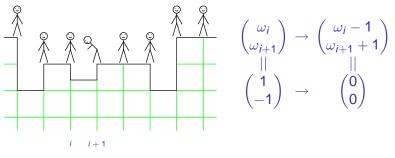
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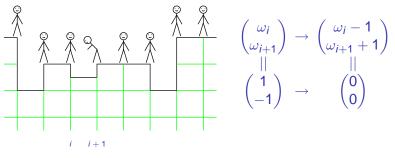
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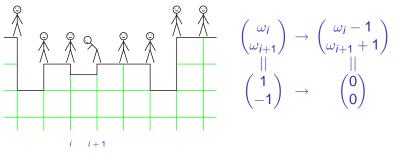
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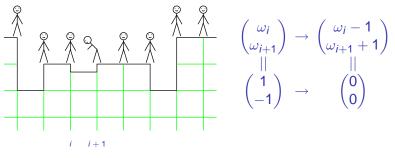
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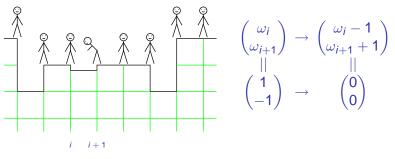
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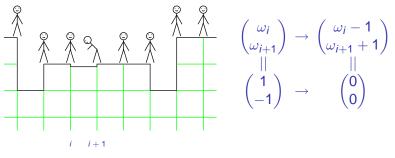
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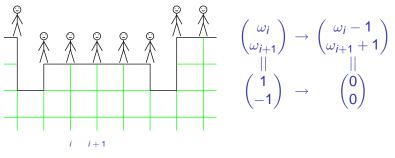
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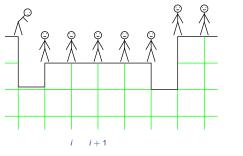
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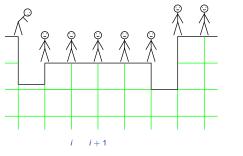
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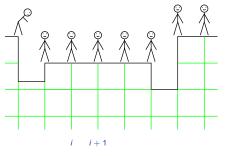
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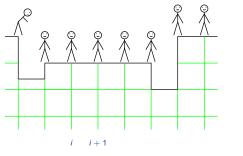
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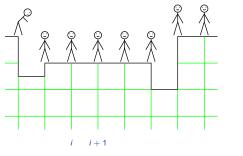
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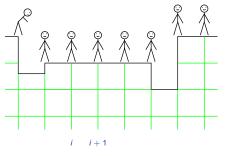
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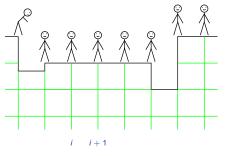
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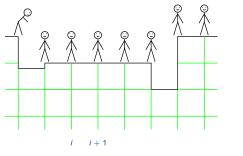
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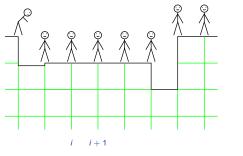
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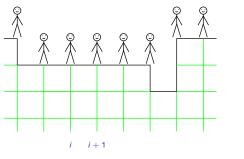
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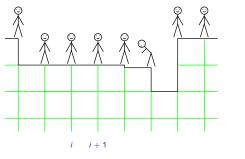
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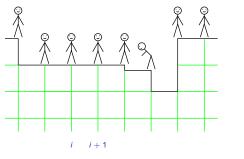
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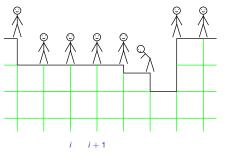
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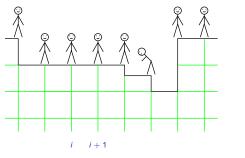
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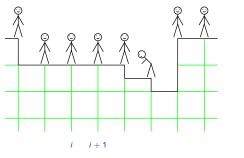
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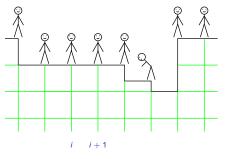
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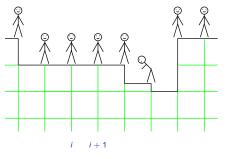
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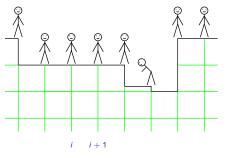
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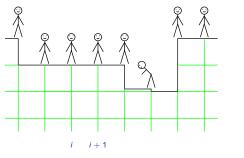
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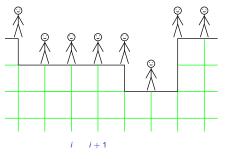
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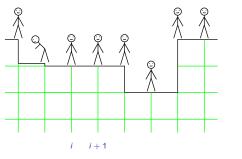
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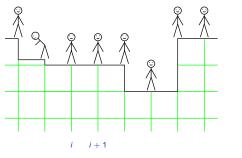
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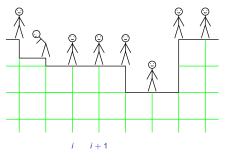
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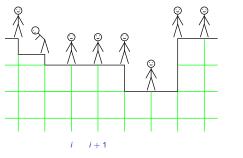
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a brick is added with rate $p \cdot [r(\omega_i) + r(-\omega_{i+1})]$ a brick is removed with rate $q \cdot [r(-\omega_i) + r(\omega_{i+1})]$.



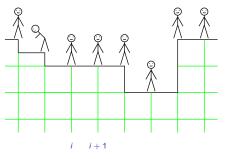
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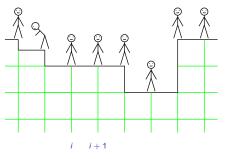
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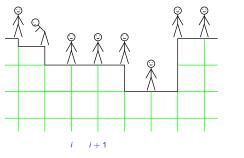
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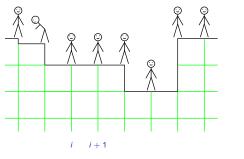
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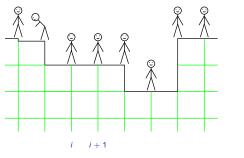
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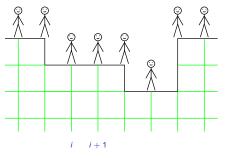
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$$\begin{pmatrix} \omega_i \\ \omega_{i+1} \end{pmatrix} \rightarrow \begin{pmatrix} \omega_i + 1 \\ \omega_{i+1} - 1 \end{pmatrix}$$

with rate $p(\omega_i, \omega_{i+1})$,

with rate
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, where

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- *p* is non-decreasing in the first, non-increasing in the second variable, and *q* vice-versa (attractivity),

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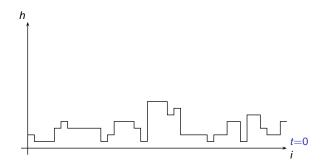
- p and q are such that they keep the state space (ASEP, ZRP),
- *p* is non-decreasing in the first, non-increasing in the second variable, and *q* vice-versa (attractivity),
- they satisfy some algebraic conditions to get a product stationary distribution for the process,

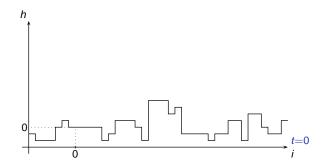
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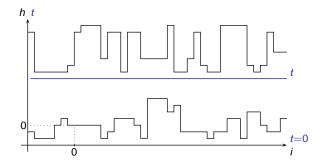
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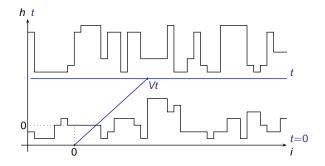
with rate
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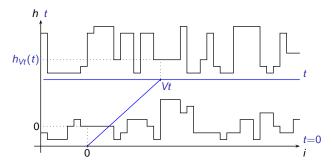
- p and q are such that they keep the state space (ASEP, ZRP),
- *p* is non-decreasing in the first, non-increasing in the second variable, and *q* vice-versa (attractivity),
- they satisfy some algebraic conditions to get a product stationary distribution for the process,
- they satisfy some regularity conditions to make sure the dynamics exists.





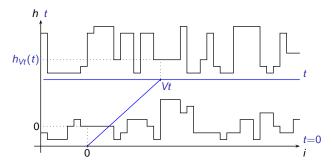






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(Remember: particle current=change in height.)



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Question: What is the time-order of $Var(h_{Vt}(t))$?

The *density* $\varrho := \mathbf{E}(\omega)$ and the *hydrodynamic flux* $H := \mathbf{E}$ [growth rate] both depend on a parameter of the stationary distribution.

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► The characteristics is a path X(T) where *e*(T, X(T)) is constant.

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$$R=\frac{H(\varrho)-H(\lambda)}{\varrho-\lambda}.$$

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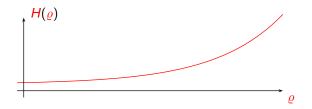
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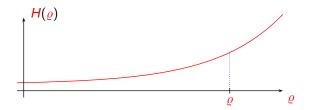
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This would be the speed of a shock of densities ρ and λ .

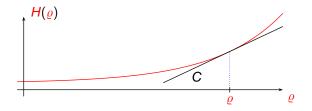
Convex flux (some cases of AZRP, ABLP):



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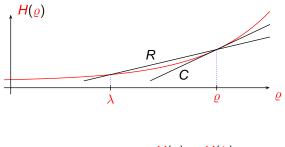


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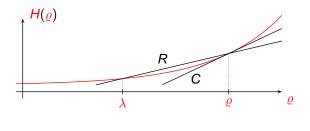
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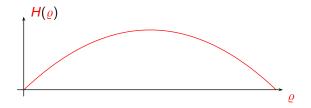
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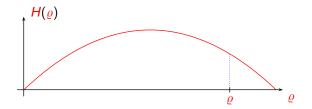


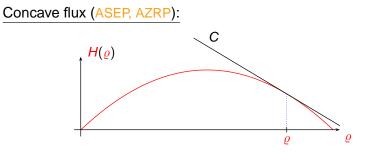
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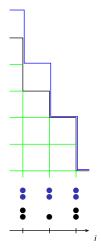


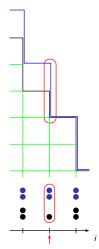
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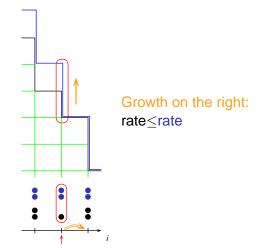
Concave flux (ASEP, AZRP): С $H(\varrho)$ R ϱ λ ϱ $C = H'(\varrho)$ $R = \frac{H(\varrho) - H(\lambda)}{\rho - \lambda}$

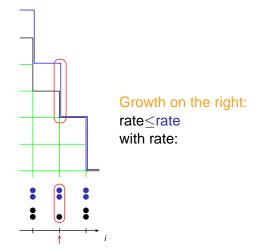
Concave flux (ASEP, AZRP): С $H(\varrho)$ R ϱ ϱ λ

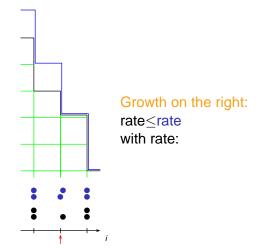
$$C = H'(\varrho) < R = rac{H(\varrho) - H(\lambda)}{\varrho - \lambda}$$

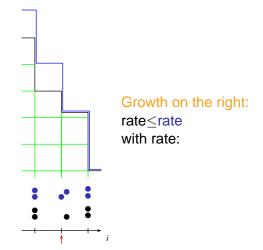


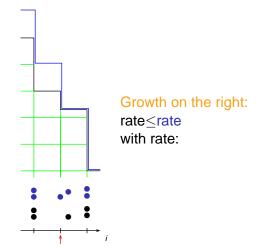


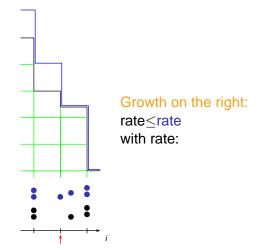


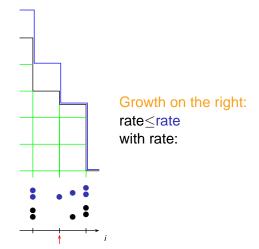


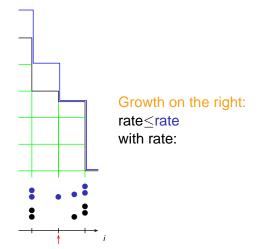


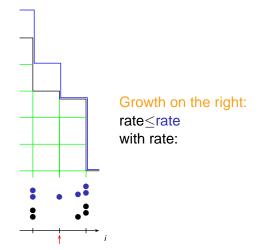


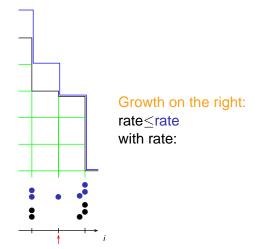


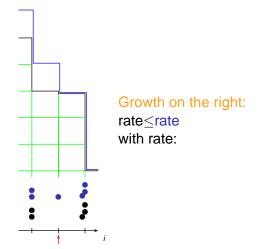


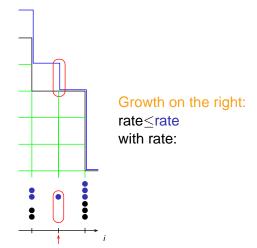


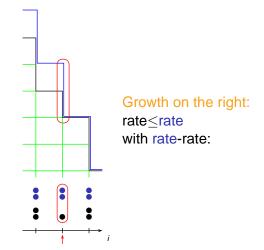


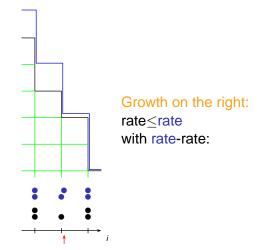


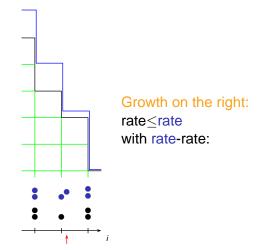


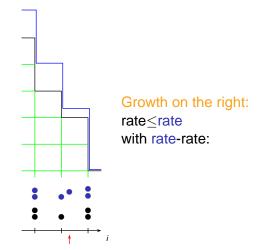


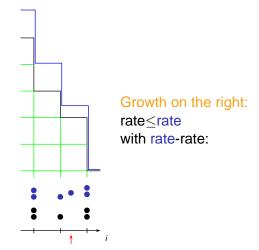


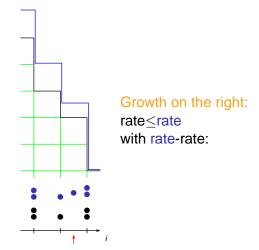


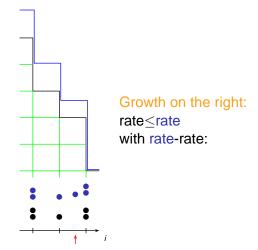


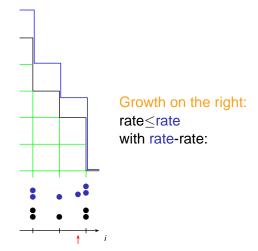


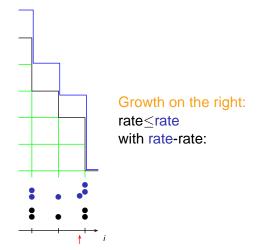


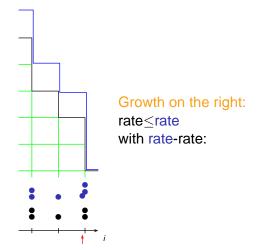


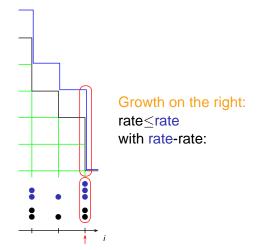


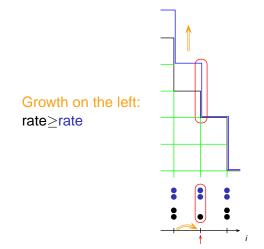


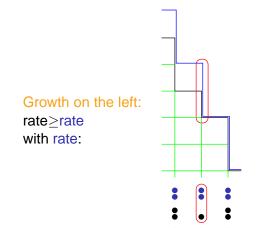


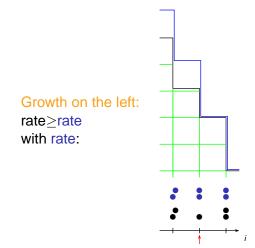


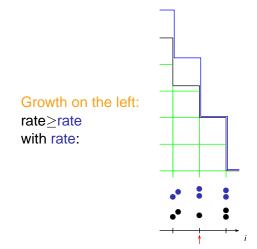


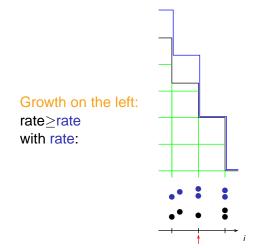


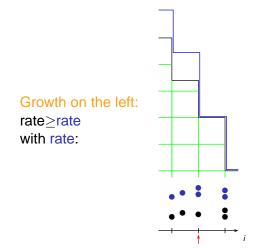


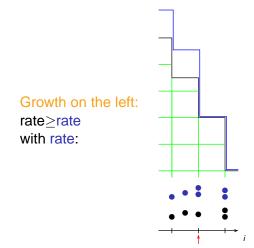


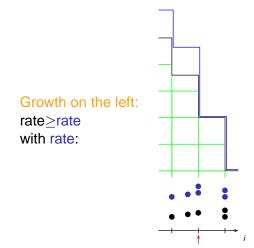


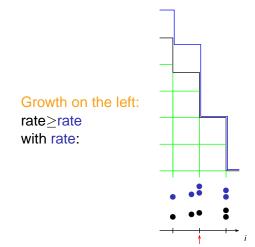


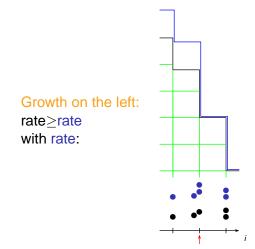


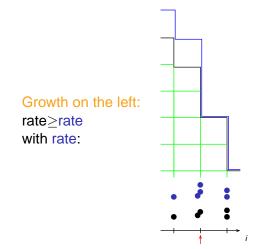


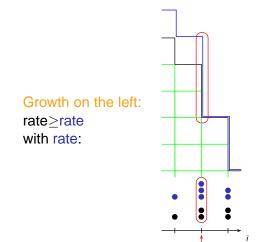






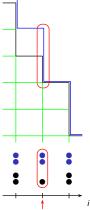


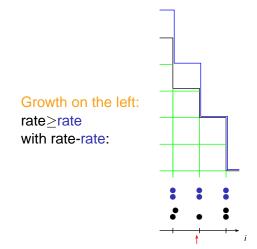


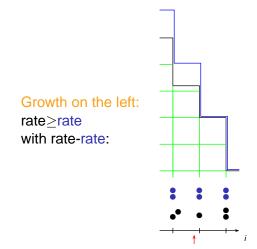


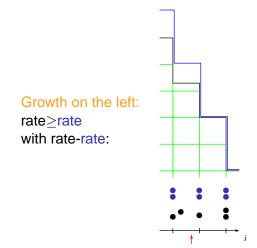
States ω and ω only differ at one site.

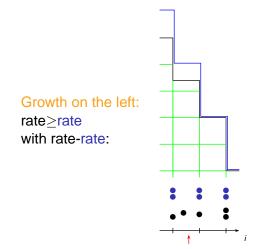
Growth on the left: rate > rate with rate-rate:

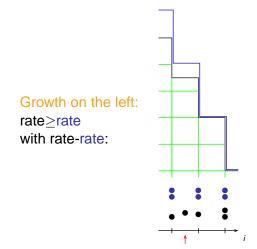


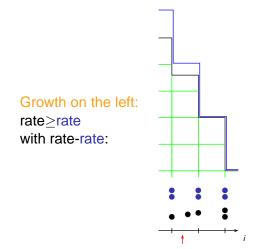


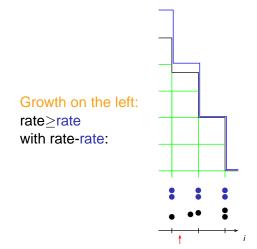


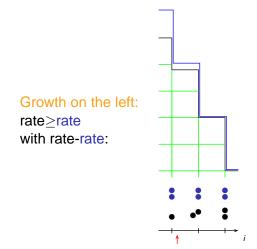


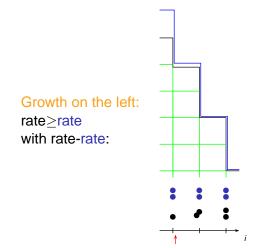


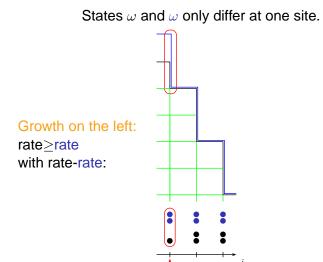


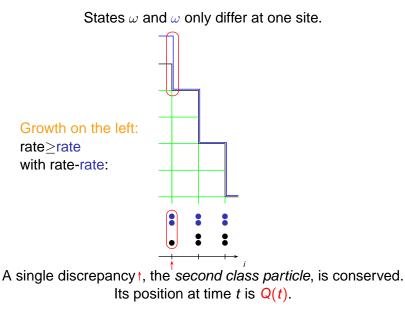












Theorem (B. - Seppäläinen; also ideas from B. Tóth, H. Spohn and M. Prähofer)

Started from (almost) equilibrium,

 $\mathsf{E}(\mathsf{Q}(t)) = C \cdot t$

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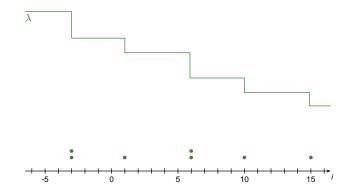
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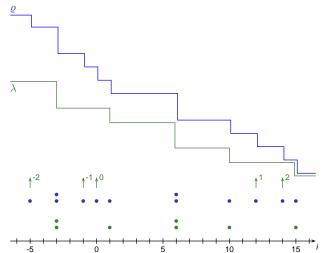
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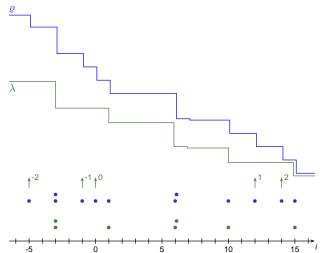
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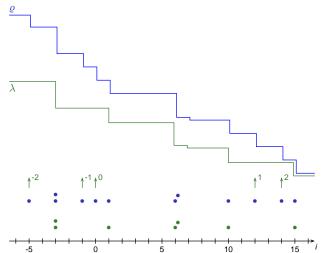
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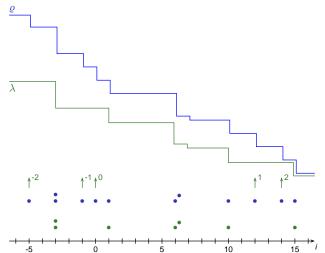
The second class particle follows the characteristics, people have known this for a long time.

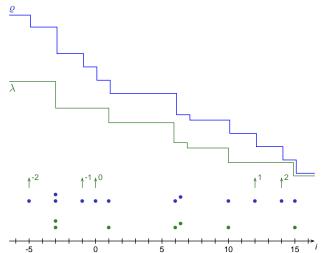


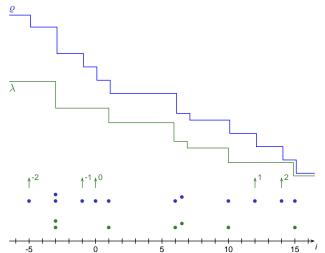


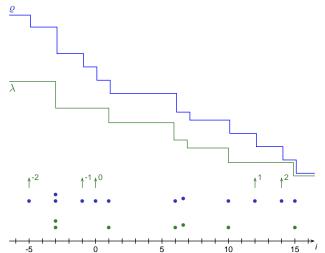


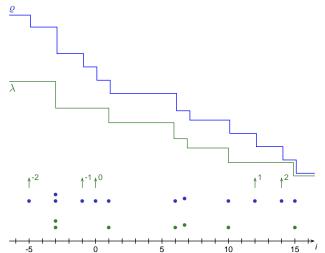


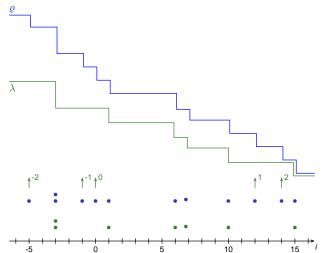


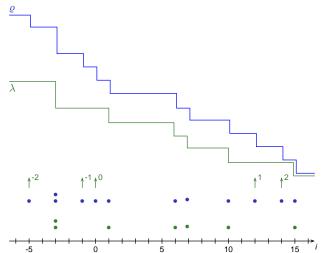


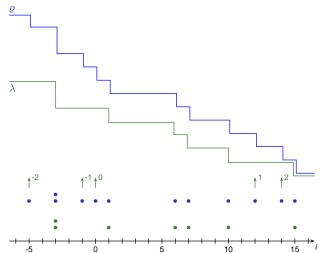


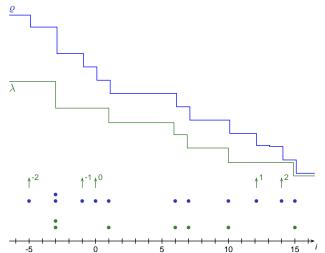


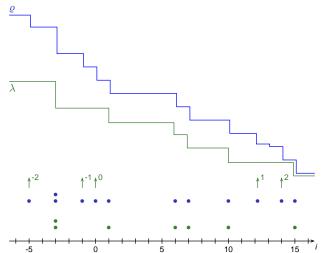


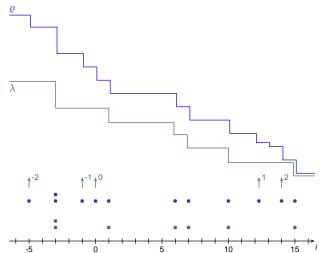


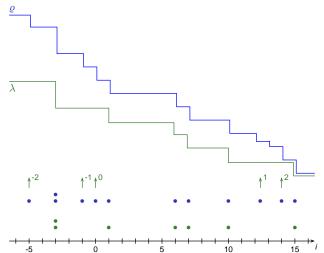


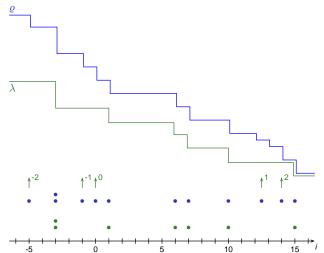


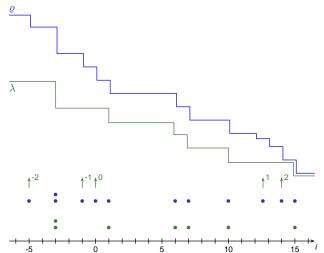


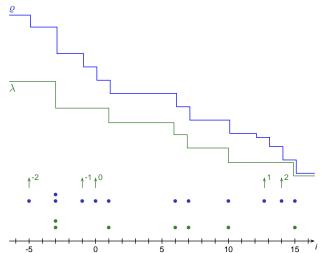


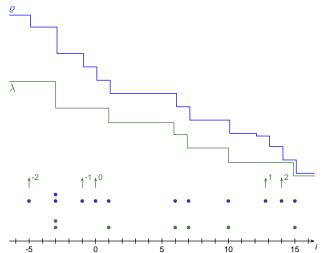


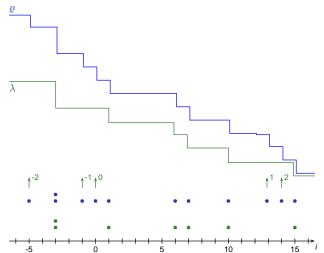


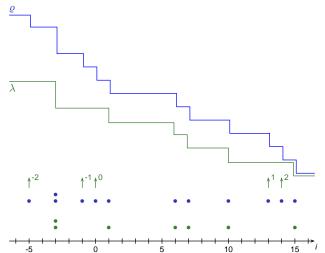


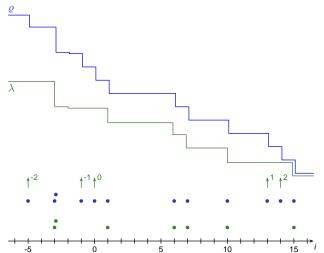


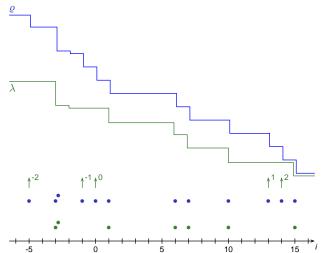


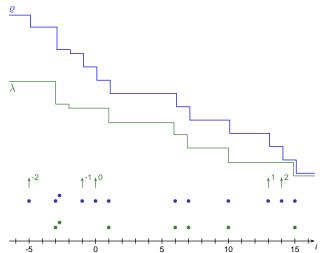


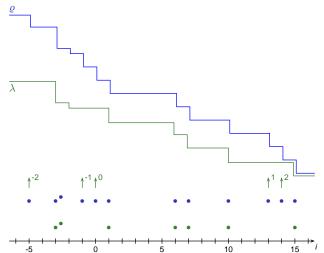


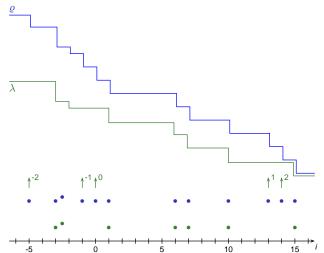


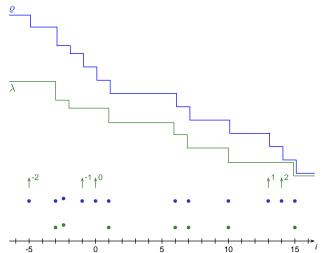


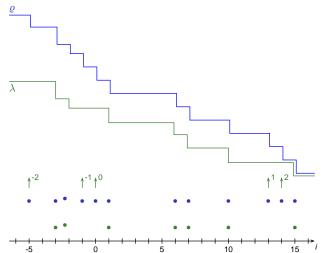


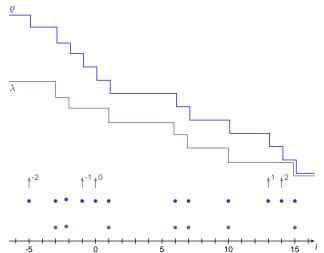


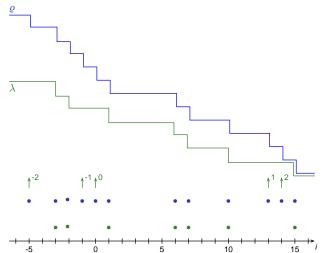


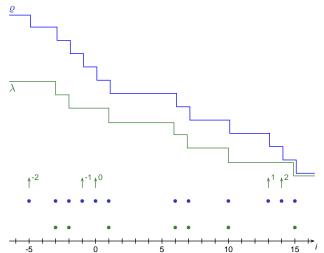


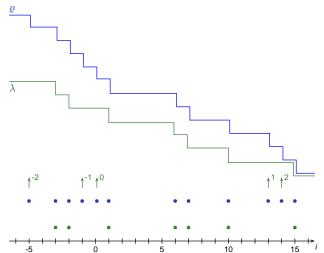


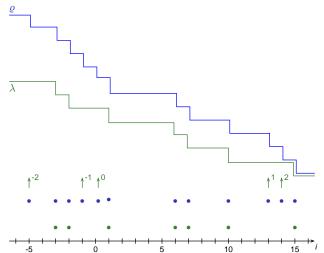


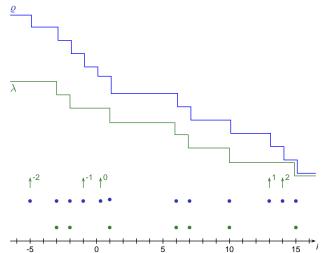


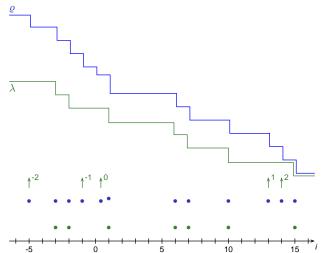


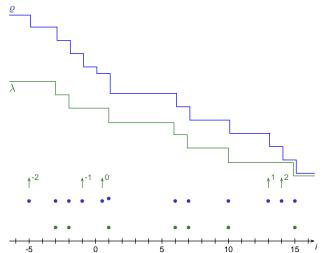


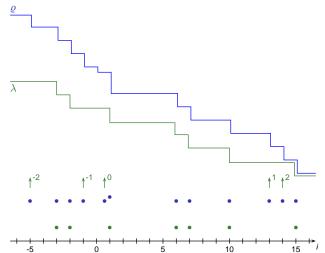


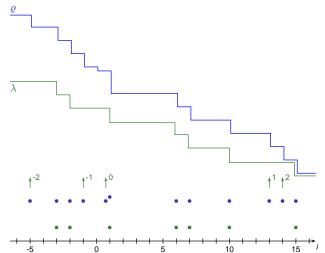


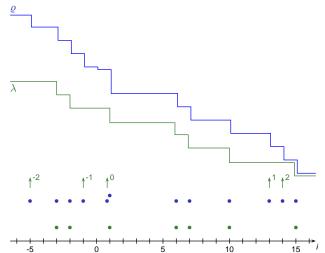


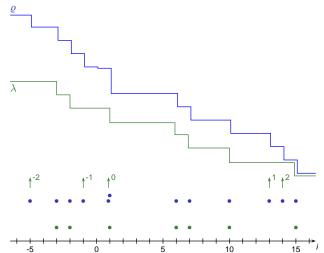


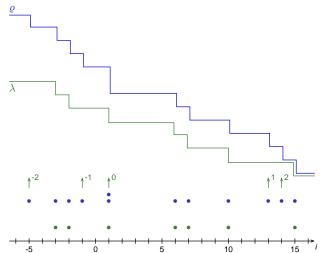


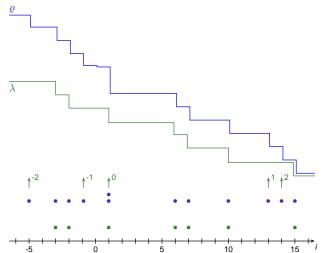


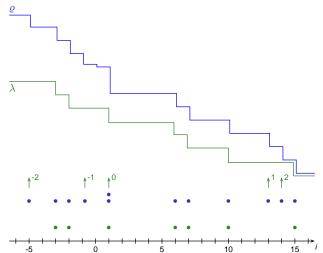


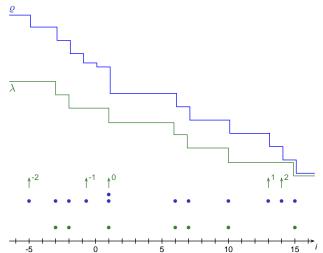


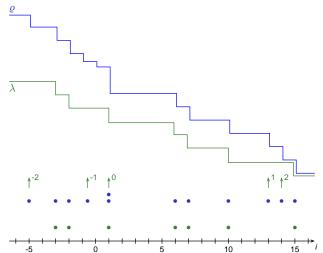


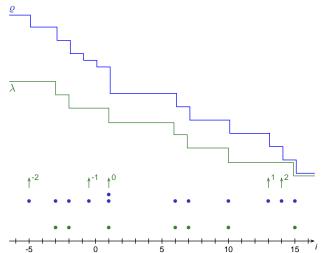


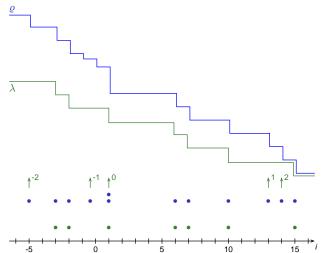


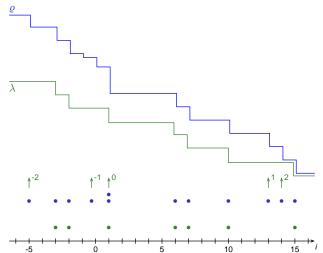


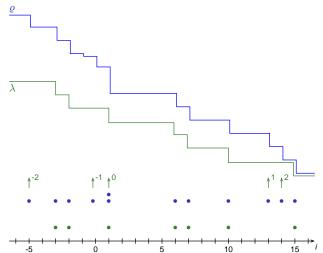


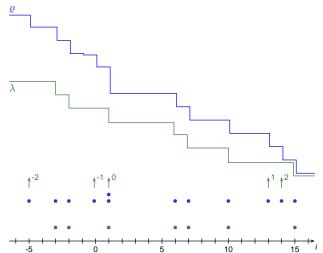


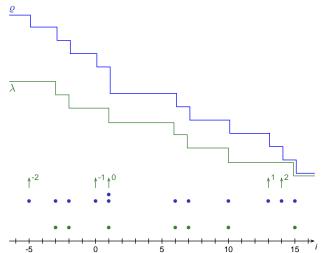


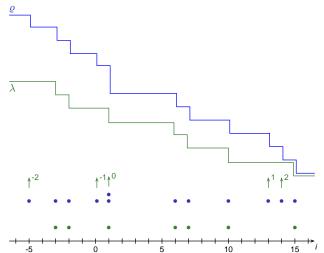


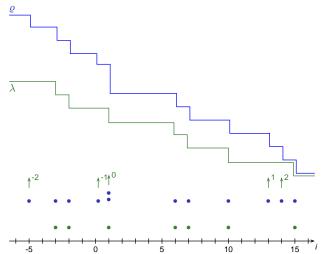


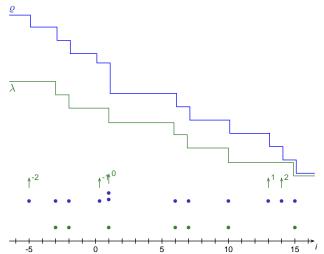


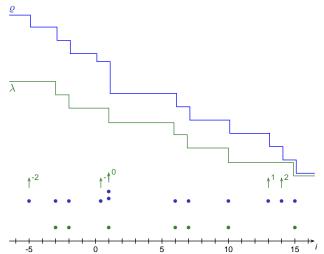


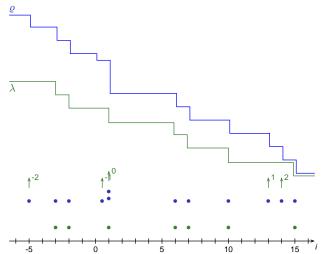


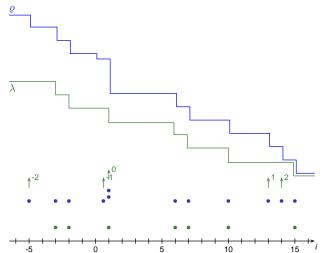


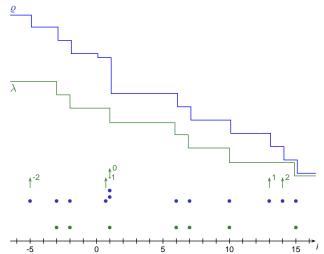


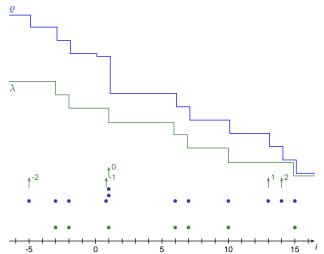


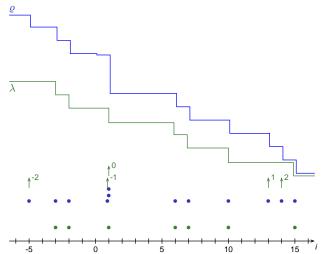


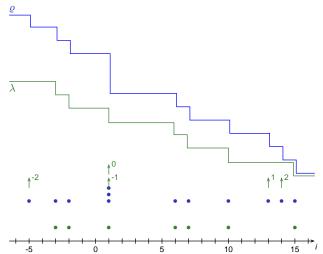


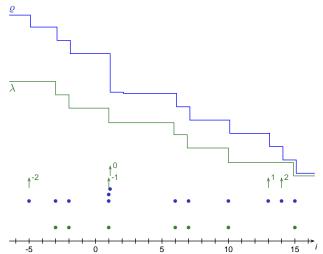


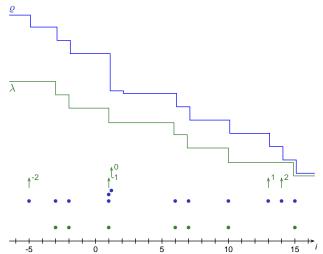


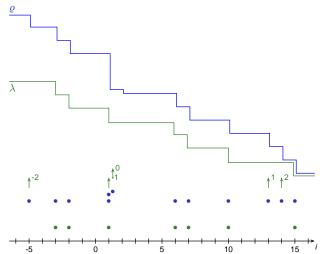


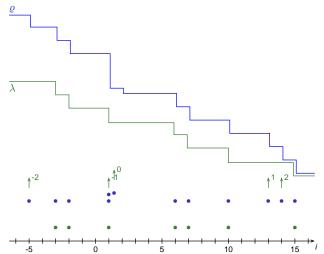


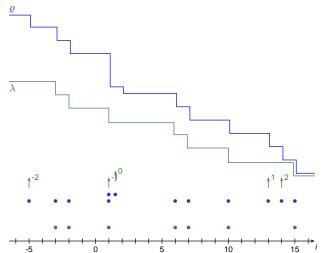


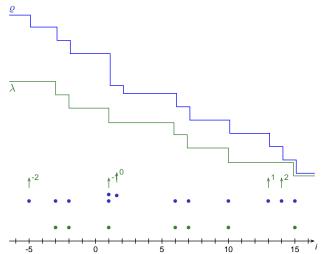


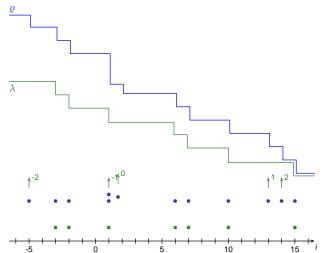


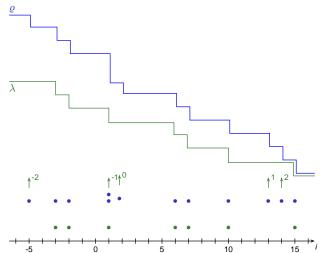


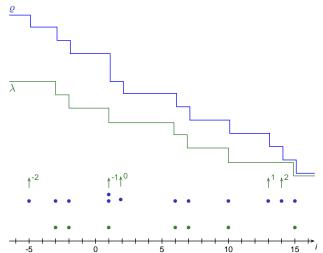


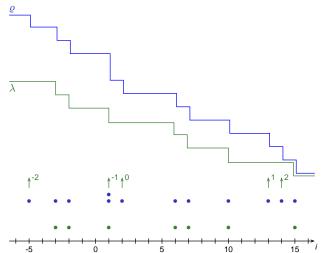


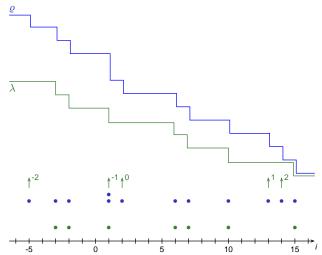








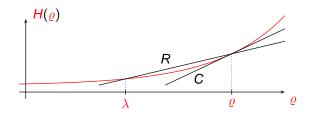




Picture:

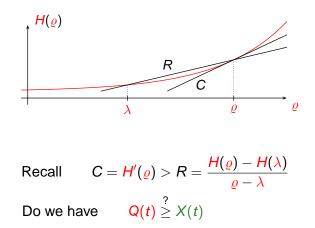
The position X(t) of \uparrow^0 follows the Rankine-Hugoniot speed *R*.

Convex flux (some cases of AZRP, ABLP):

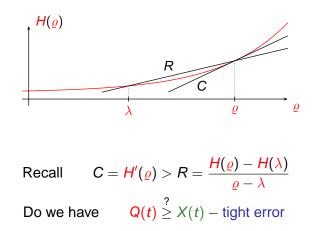


Recall
$$C = H'(\varrho) > R = \frac{H(\varrho) - H(\lambda)}{\varrho - \lambda}$$

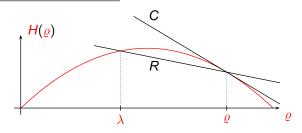
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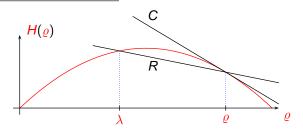


Concave flux (ASEP, AZRP):



$$C = H'(\varrho) < R = rac{H(\varrho) - H(\lambda)}{\varrho - \lambda}$$

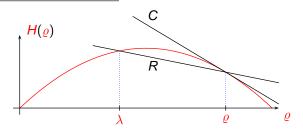
Concave flux (ASEP, AZRP):



$$C = H'(\varrho) < R = \frac{H(\varrho) - H(\lambda)}{\varrho - \lambda}$$

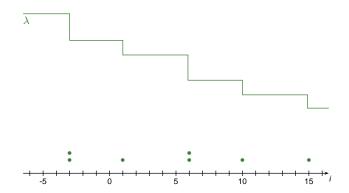
Do we have $Q(t) \stackrel{?}{\leq} X(t)$

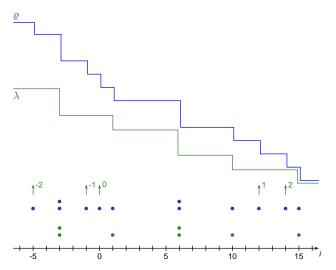
Concave flux (ASEP, AZRP):

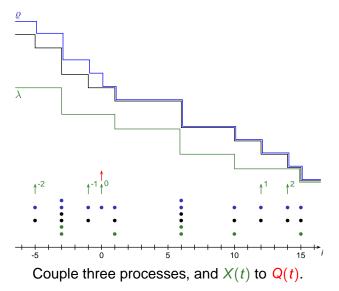


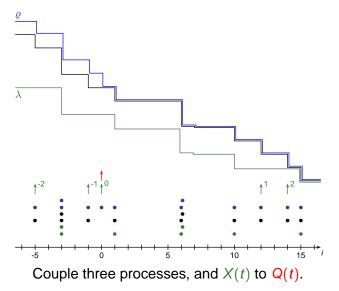
$$C = H'(\varrho) < R = \frac{H(\varrho) - H(\lambda)}{\varrho - \lambda}$$

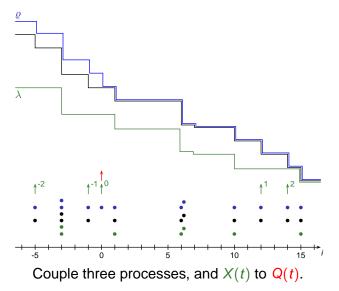
Do we have $Q(t) \stackrel{?}{\leq} X(t) + \text{tight error}$

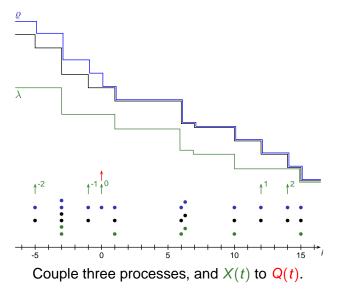


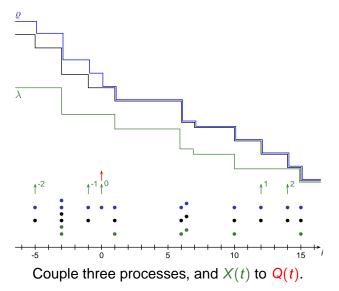


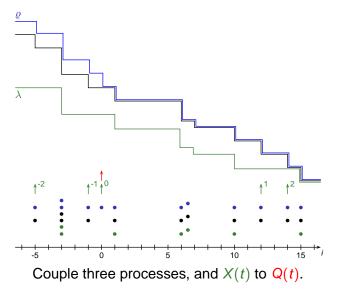


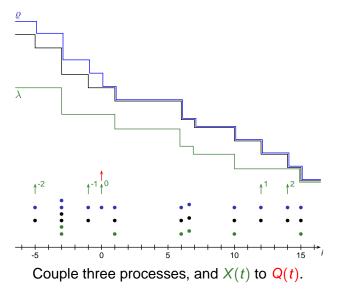


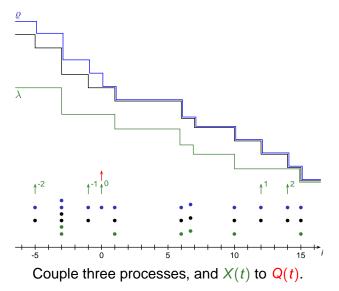


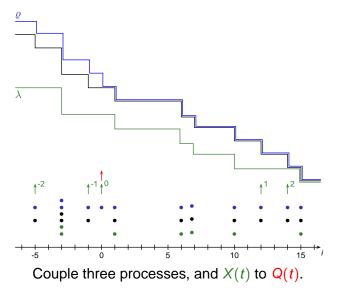


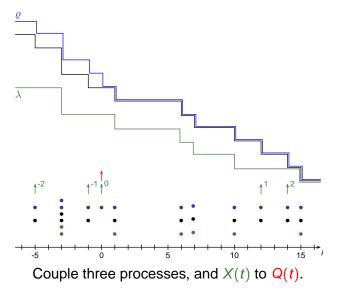


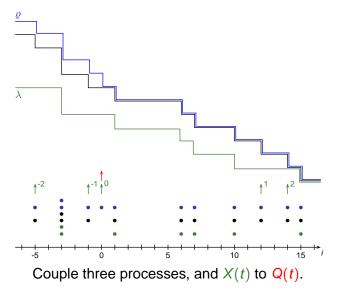


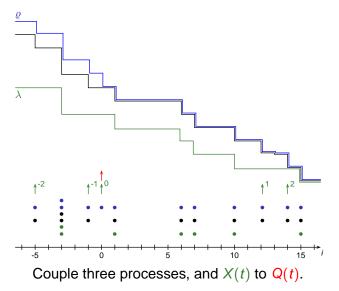


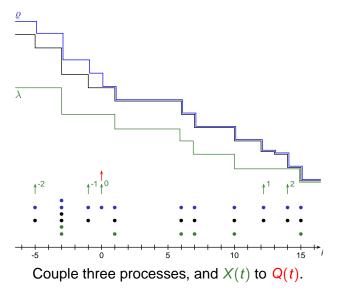


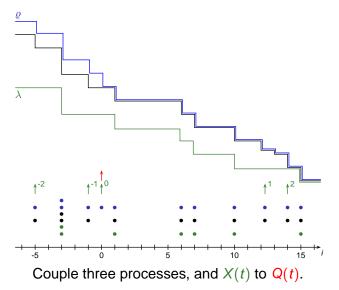


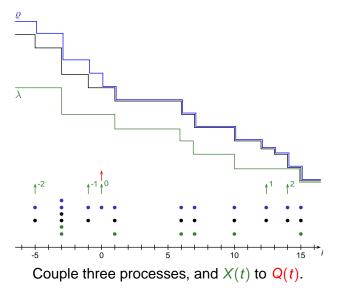


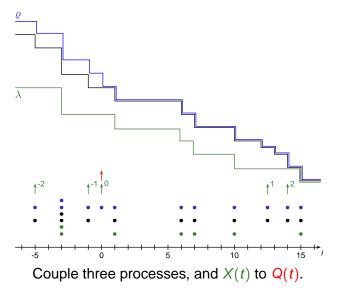


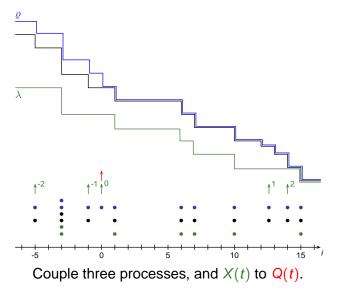


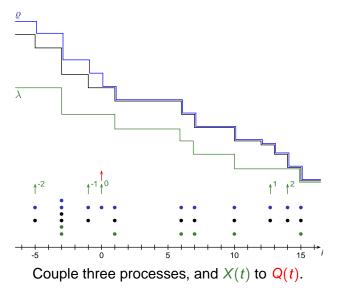


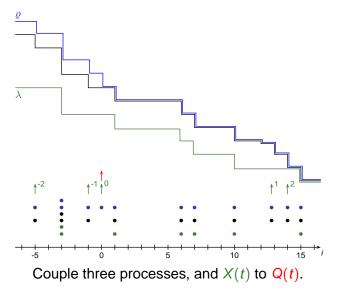


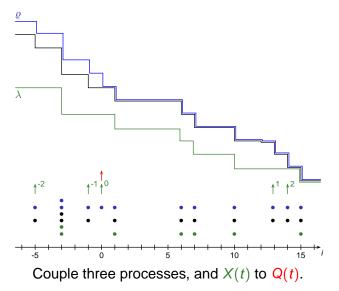


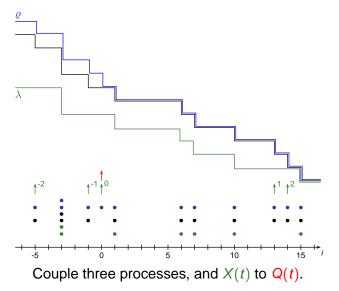


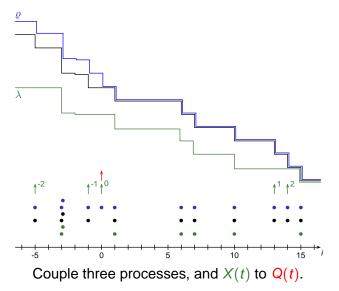


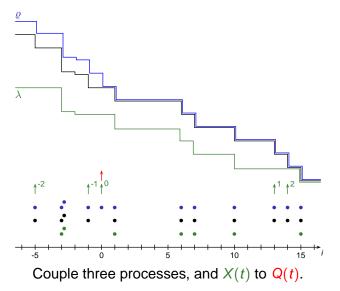


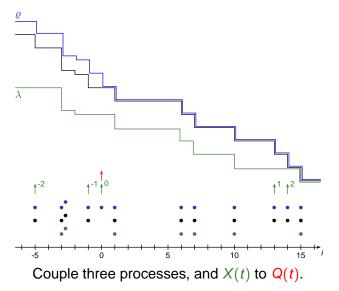


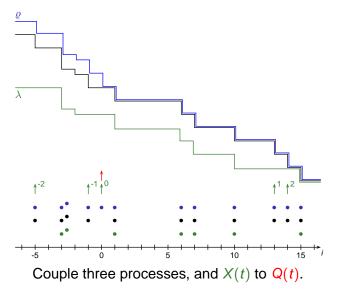


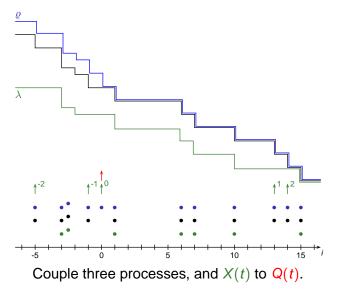


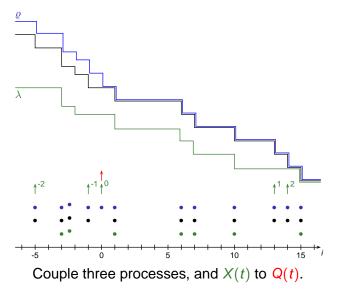


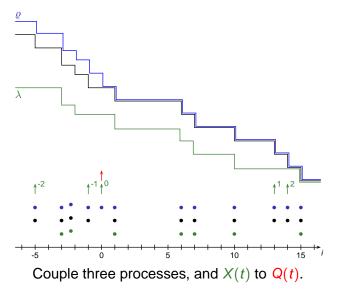


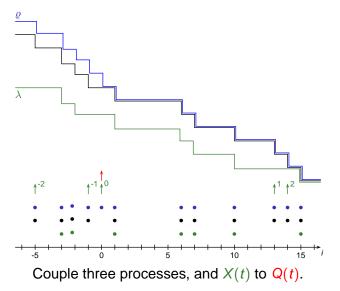


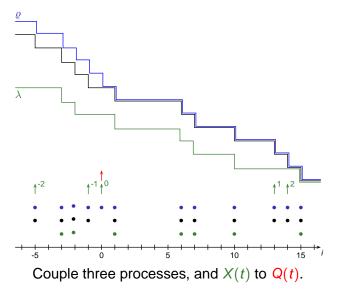


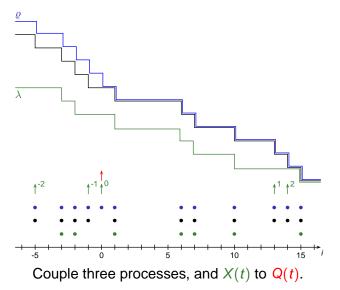


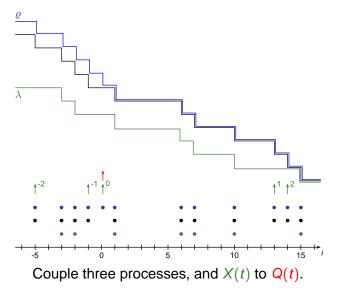


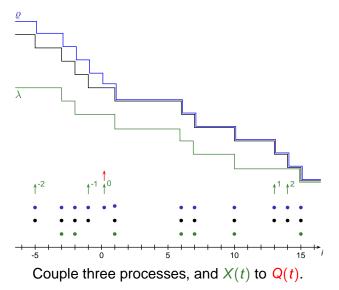


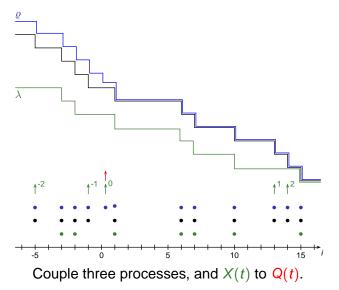


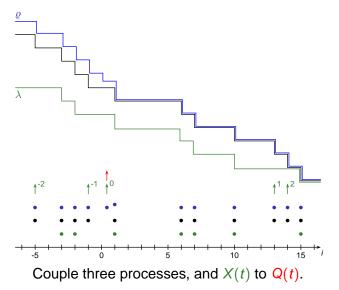


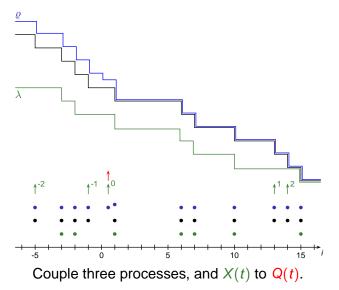


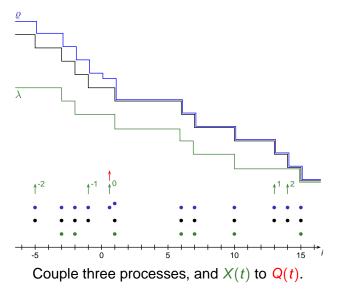


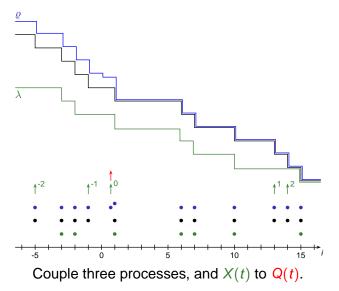


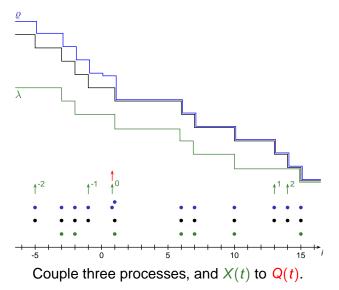


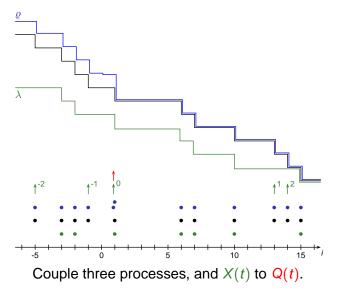


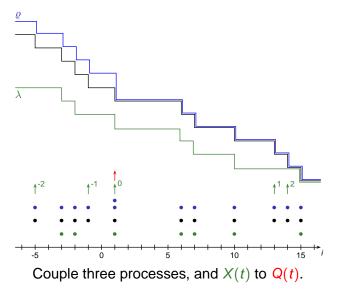


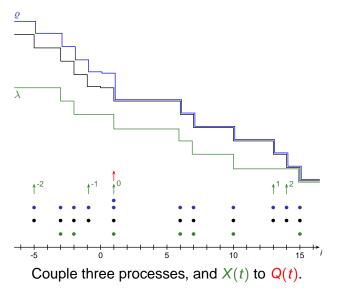


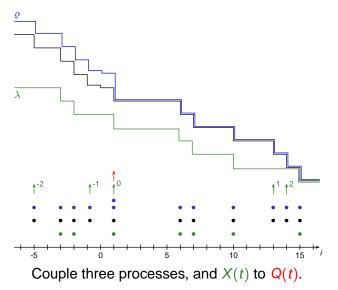


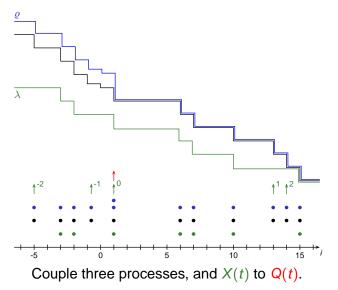


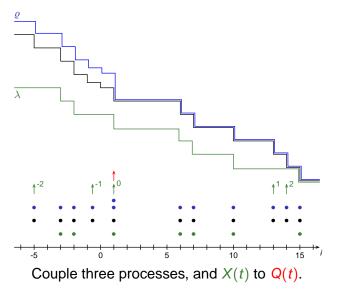


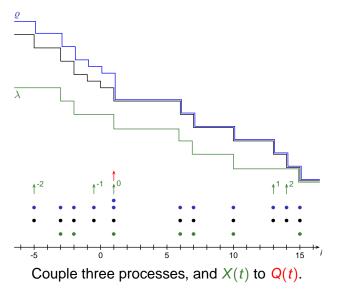


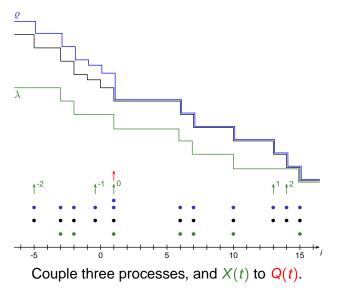


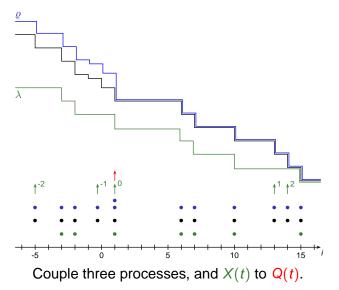


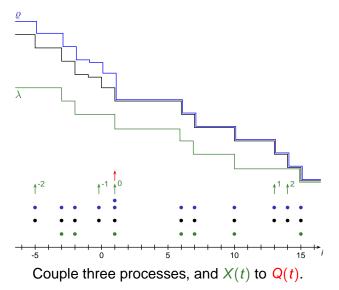


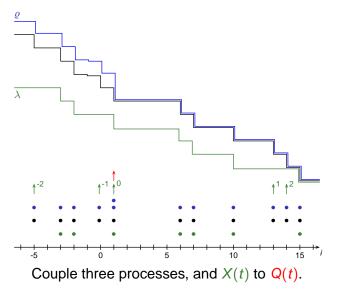


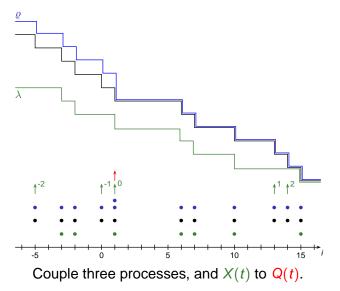


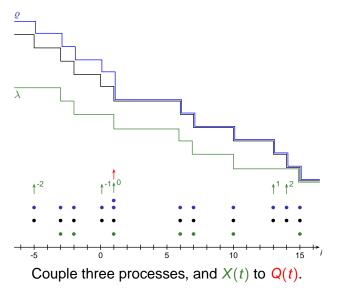


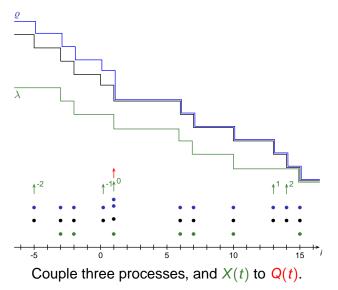


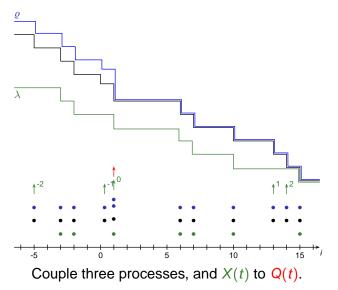


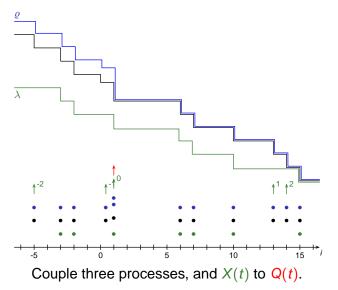


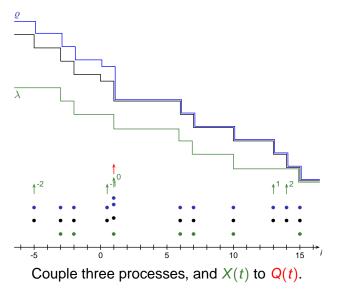


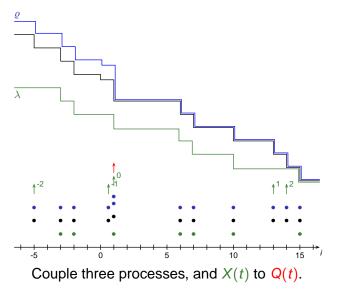


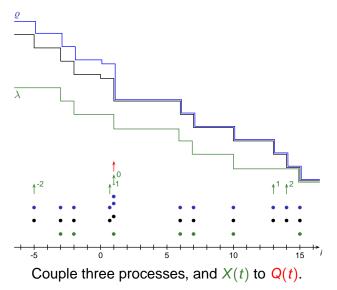


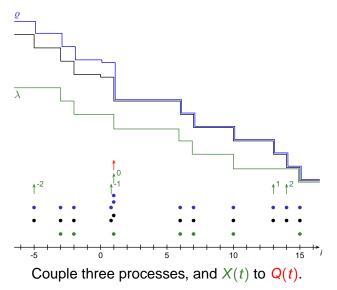


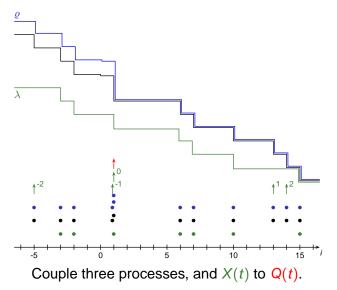


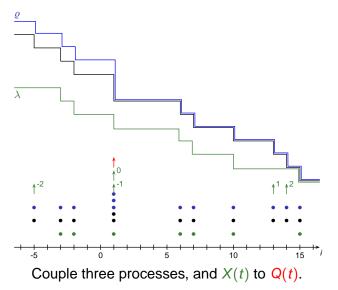


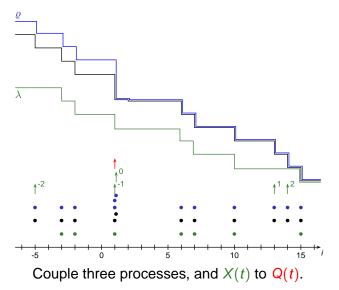


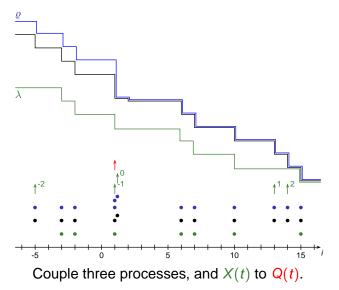


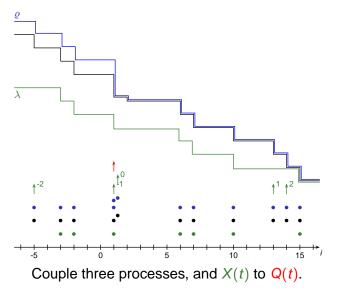


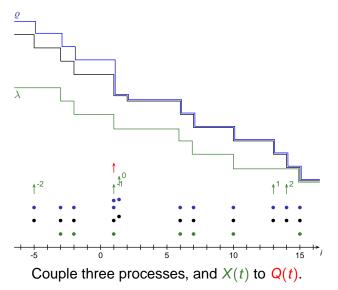


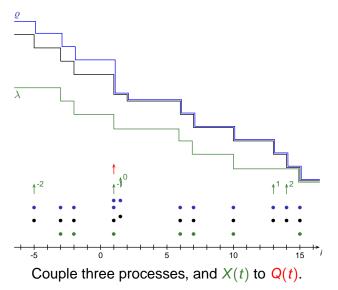


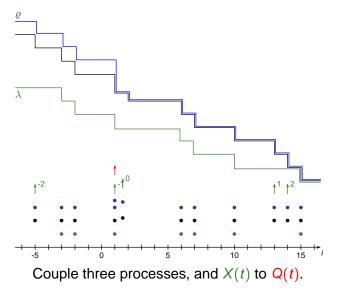


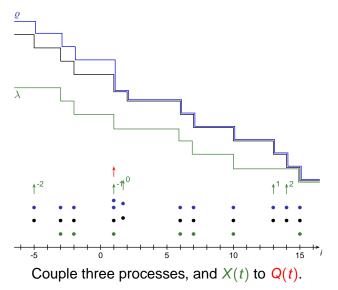


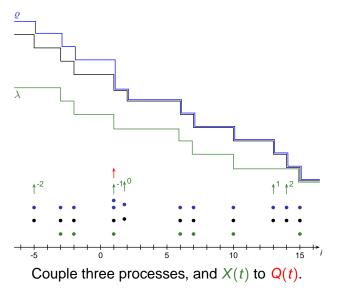


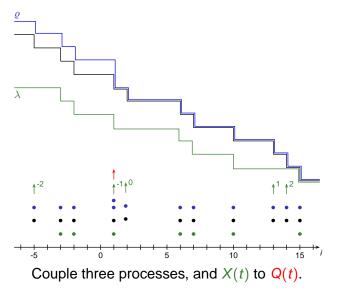


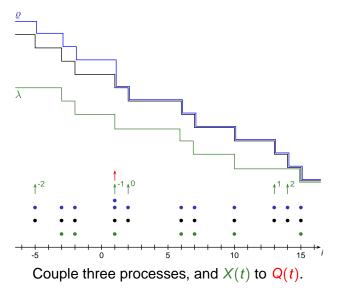












Microscopic convexity/concavity

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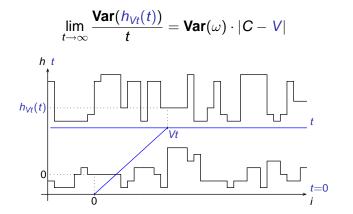
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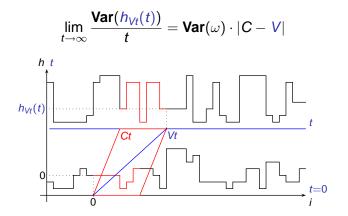
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Initial fluctuations are transported along the characteristics on this scale.

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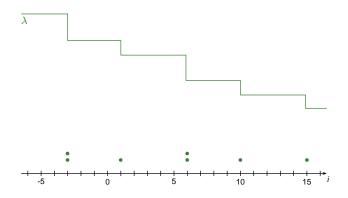
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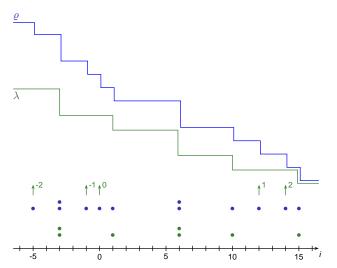
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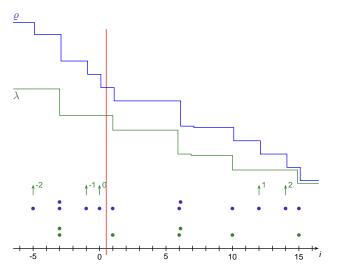
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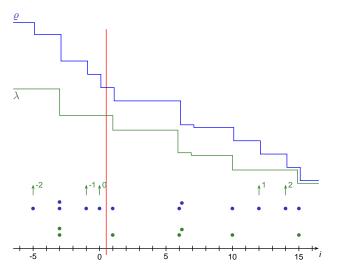
There are limit distribution results for TASEP e.g. by Johansson 2000, Prähofer and Spohn 2001, Ferrari and Spohn 2006. Their methods give limit distributions as well, but are very model-dependent: they rewrite the model as a determinantal process, and perform asymptotic analysis of the determinants.

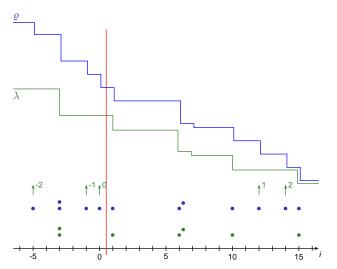


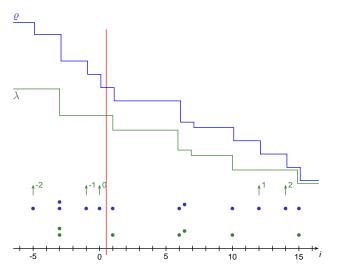
Second class particle current: difference in growth.

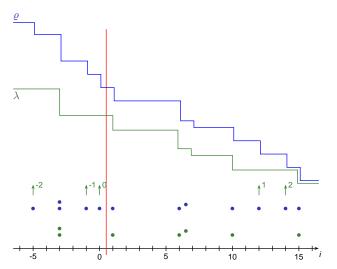


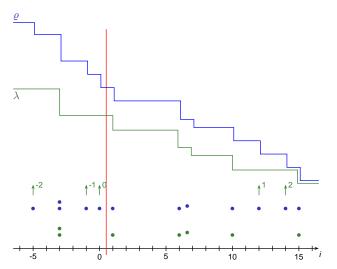


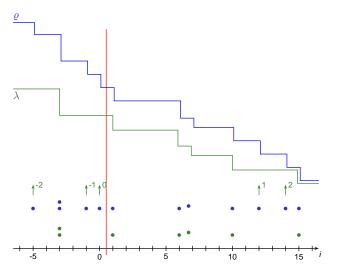


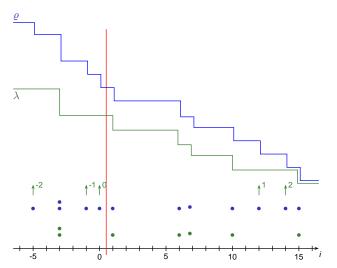


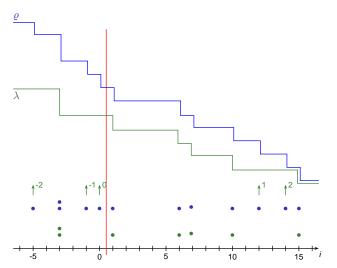


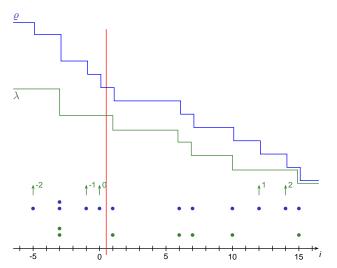


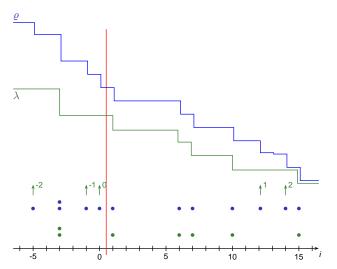


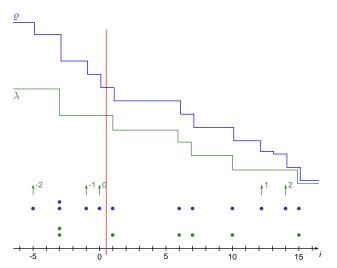


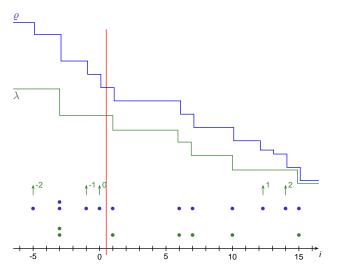


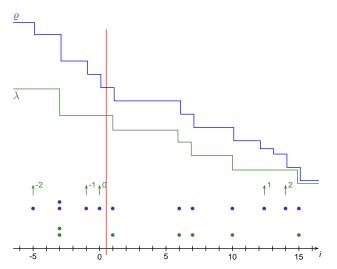


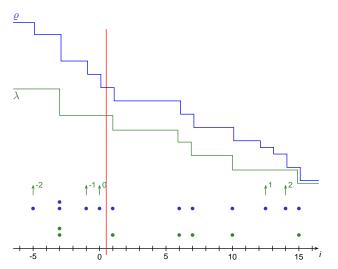


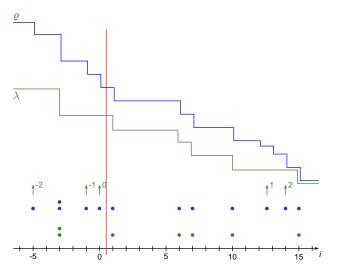


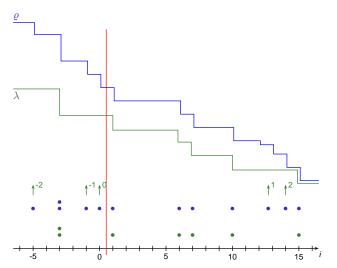


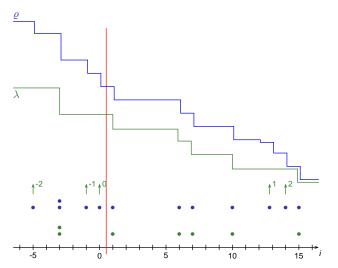


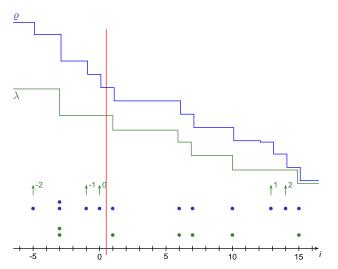


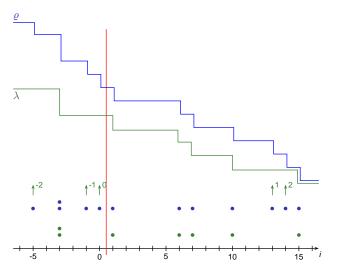


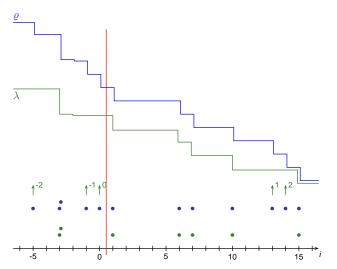


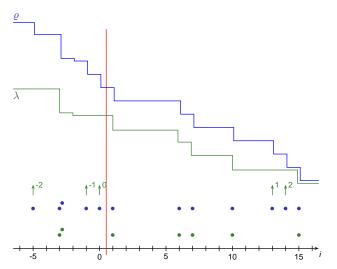


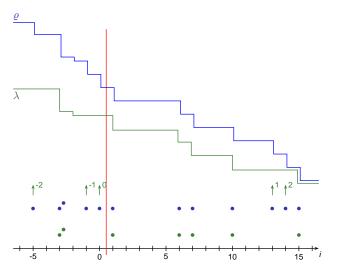


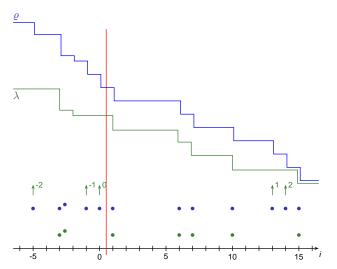


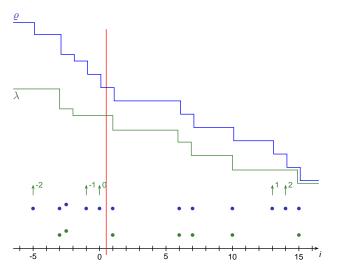


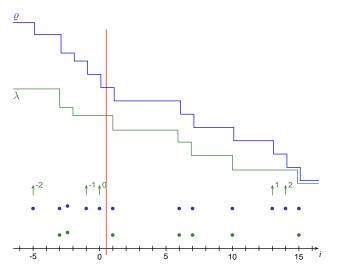


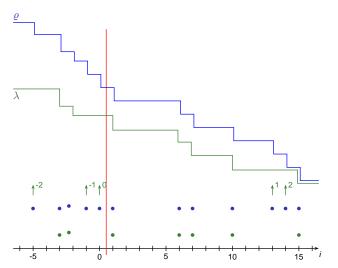


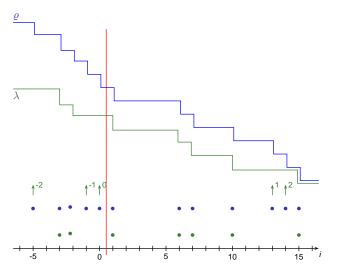


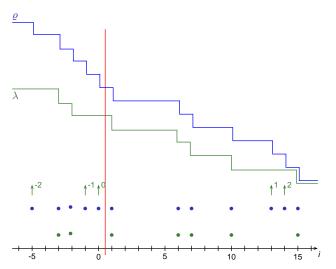


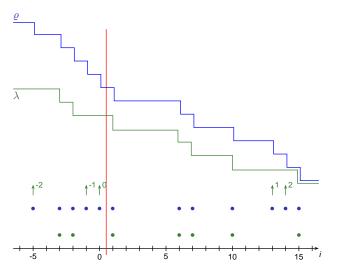


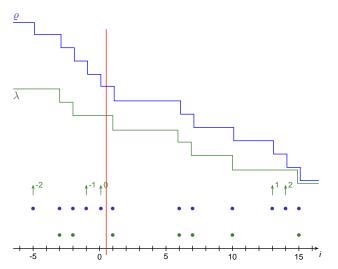


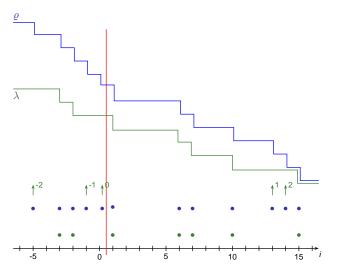


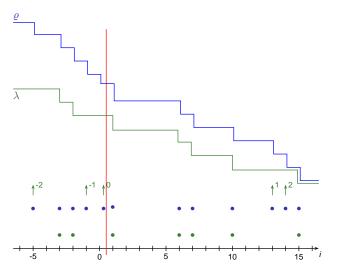


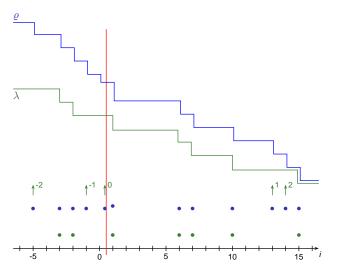


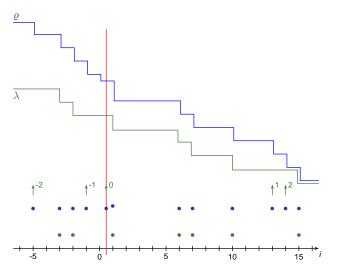


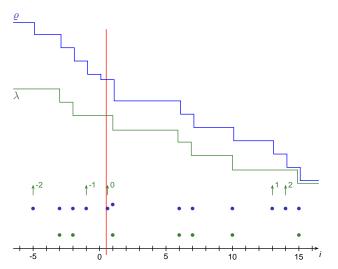


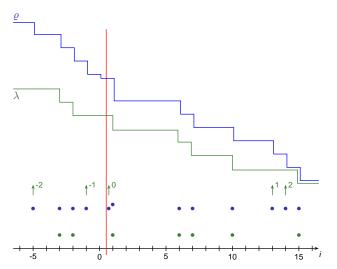


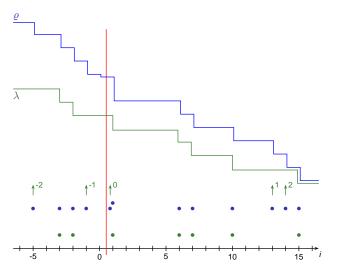


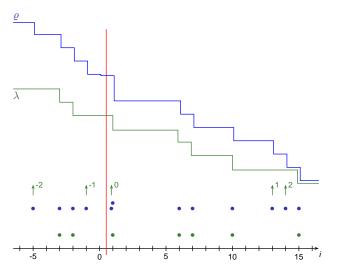


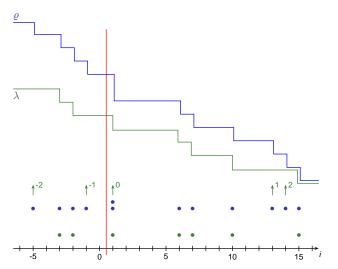


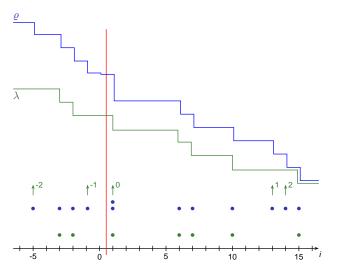


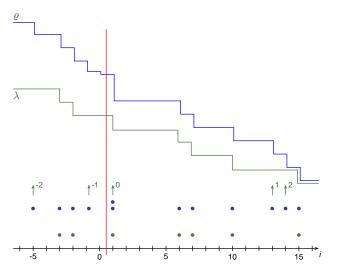


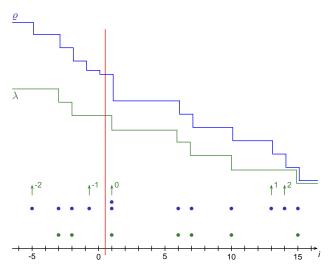


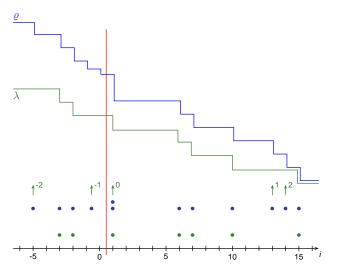


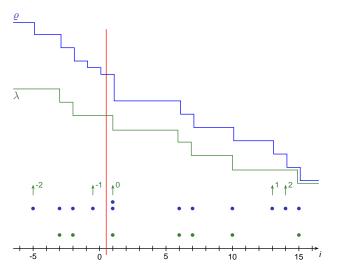


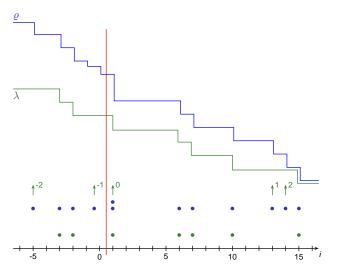


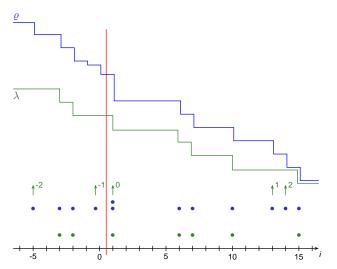


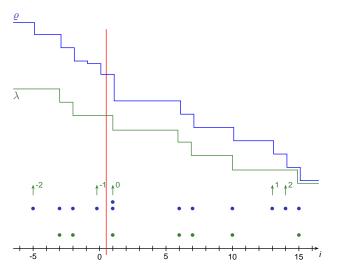


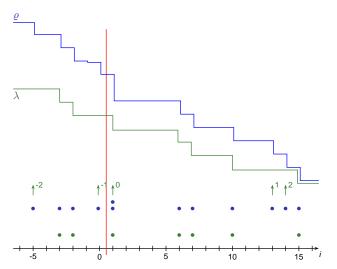


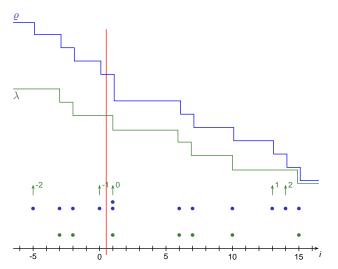


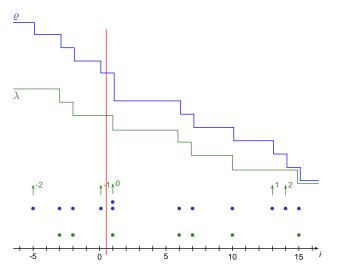


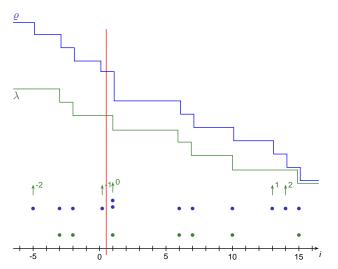


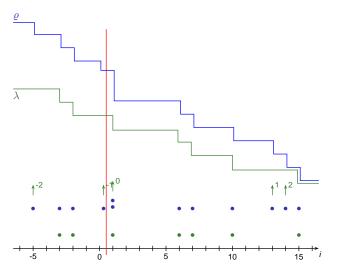


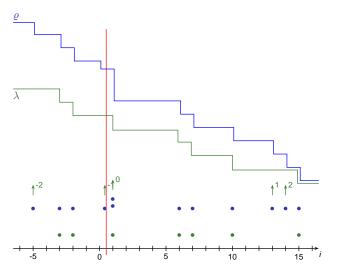


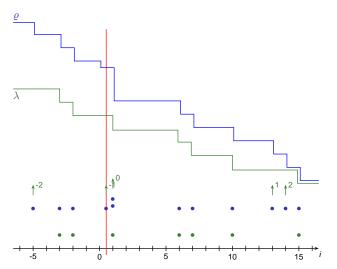


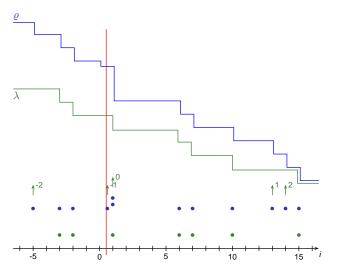


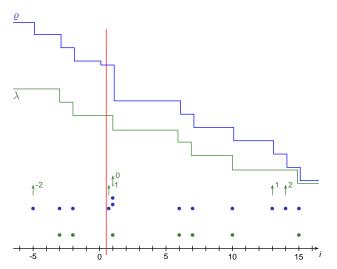


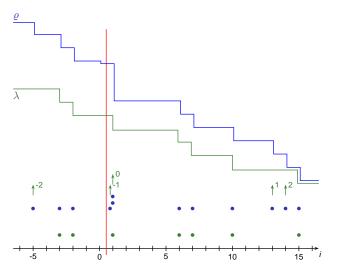


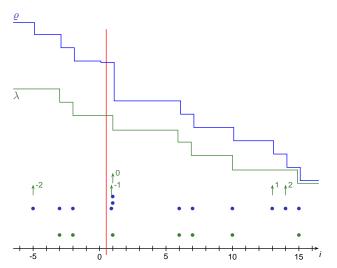


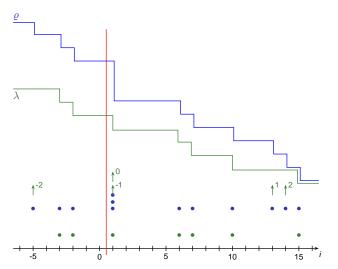


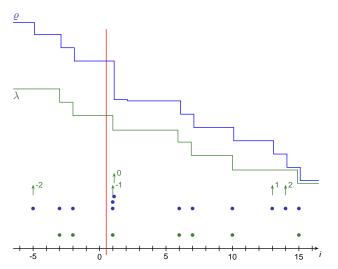


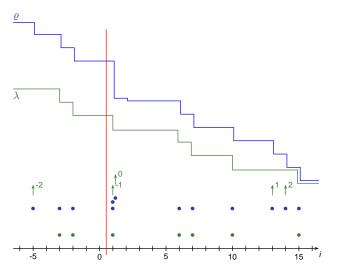


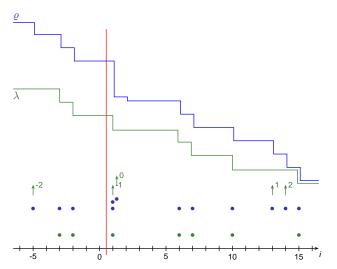


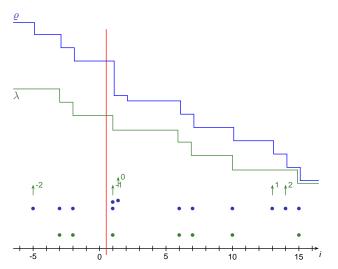


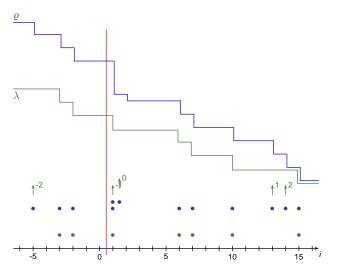


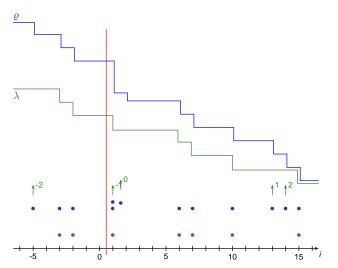


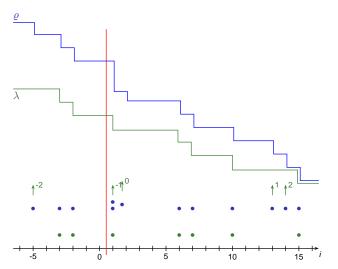


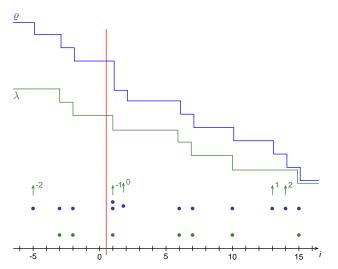


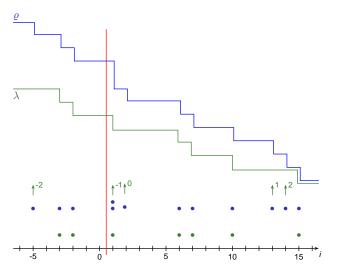


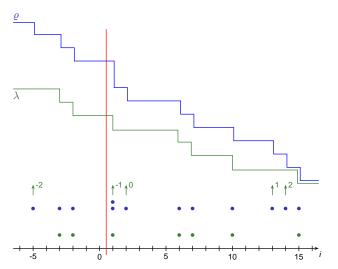












 $P{Q(t) \text{ is too large}}$

 $\mathbf{P}{\mathbf{Q}(t) \text{ is too large}} \le \mathbf{P}{X(t) \text{ is too large}}$

 $\mathbf{P}{\mathbf{Q}(t) \text{ is too large}} \le \mathbf{P}{X(t) \text{ is too large}}$

 $\leq \mathbf{P}$ {too many 's have crossed *Ct*}

 $\mathbf{P}{\mathbf{Q}(t) \text{ is too large}} \le \mathbf{P}{X(t) \text{ is too large}}$

 $\leq \mathbf{P}$ {too many 's have crossed Ct}

 $\leq \mathbf{P}\{h_{Ct}(t) - h_{Ct}(t) \text{ is too large}\}.$

 $\mathbf{P}{\mathbf{Q}(t) \text{ is too large}} \le \mathbf{P}{X(t) \text{ is too large}}$

$$\leq \mathbf{P}$$
{too many 's have crossed Ct }

 $\leq \mathbf{P}\{h_{Ct}(t) - h_{Ct}(t) \text{ is too large}\}.$

Centering $h_{Ct}(t) - h_{Ct}(t)$ brings in a second-order Taylor-expansion of $H(\varrho)$.

 $\mathbf{P}\{\mathbf{Q}(t) \text{ is too large}\} \le \mathbf{P}\{X(t) \text{ is too large}\}$

$$\leq \mathbf{P}$$
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 $\leq \mathbf{P}\{h_{Ct}(t) - h_{Ct}(t) \text{ is too large}\}.$

Centering $h_{Ct}(t) - h_{Ct}(t)$ brings in a second-order Taylor-expansion of $H(\varrho)$. This is another point where concavity of the flux matters.

 $\mathbf{P}{\mathbf{Q}(t) \text{ is too large}} \le \mathbf{P}{X(t) \text{ is too large}}$

 $\leq \mathbf{P}$ {too many 's have crossed Ct}

 $\leq \mathbf{P}\{h_{Ct}(t) - h_{Ct}(t) \text{ is too large}(\lambda)\}.$

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Optimize "too large(λ)" in λ ,

 $\mathbf{P}{\mathbf{Q}(t) \text{ is too large}} \le \mathbf{P}{X(t) \text{ is too large}}$

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Optimize "too large(λ)" in λ , use Chebyshev's inequality and relate **Var**($h_{Ct}(t)$) to **Var**($h_{Ct}(t)$).

 $\mathbf{P}{\mathbf{Q}(t) \text{ is too large}} \le \mathbf{P}{X(t) \text{ is too large}}$

 $\leq \mathbf{P}$ {too many \uparrow 's have crossed Ct}

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Centering $h_{Ct}(t) - h_{Ct}(t)$ brings in a second-order Taylor-expansion of $H(\varrho)$. This is another point where concavity of the flux matters.

Optimize "too large(λ)" in λ , use Chebyshev's inequality and relate **Var**($h_{Ct}(t)$) to **Var**($h_{Ct}(t)$).

The computations result in (remember E(Q(t)) = Ct)

$$\mathbf{P}\{\mathbf{Q}(t) - Ct \ge u\} \le c \cdot \frac{t^2}{u^4} \cdot \operatorname{Var}(h_{Ct}(t)).$$

Theorem (B. - Seppäläinen; also ideas from B. Tóth, H. Spohn and M. Prähofer)

Started from (almost) equilibrium,

$$\operatorname{Var}(h_{Ct}(t)) = c \cdot \mathsf{E}|\mathbf{Q}(t) - C \cdot t|$$

in the whole family of processes.

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Started from (almost) equilibrium,

$$\operatorname{Var}(h_{Ct}(t)) = c \cdot \mathsf{E}|\mathbf{Q}(t) - C \cdot t|$$

in the whole family of processes.

Hence proceed with

$$\begin{split} \mathbf{P}\{\mathbf{Q}(t) - Ct \geq u\} &\leq c \cdot \frac{t^2}{u^4} \cdot \mathbf{Var}(h_{Ct}(t)) \\ &= c \cdot \frac{t^2}{u^4} \cdot \mathbf{E}|\mathbf{Q}(t) - C \cdot t|. \end{split}$$

With

$$\widetilde{\mathsf{Q}}(t) := \mathsf{Q}(t) - Ct$$
 and $E := \mathsf{E}|\widetilde{\mathsf{Q}}(t)|,$

we have (with a similar lower deviation bound)

$$\mathbf{P}\{|\widetilde{\mathbf{Q}}(t)| > u\} \le c \cdot \frac{t^2}{u^4} \cdot E.$$

With

$$\widetilde{\mathsf{Q}}(t) := \mathsf{Q}(t) - Ct$$
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we have (with a similar lower deviation bound)

$$\mathbf{P}\{|\widetilde{\mathbf{Q}}(t)| > u\} \le c \cdot \frac{t^2}{u^4} \cdot E.$$

Claim: this already implies the $t^{2/3}$ upper bound:

$$E = \mathbf{E}|\widetilde{\mathbf{Q}}(t)| = \int_0^\infty \mathbf{P}\{|\widetilde{\mathbf{Q}}(t)| > u\} \, \mathrm{d}u$$

$$E = \mathbf{E}|\widetilde{\mathbf{Q}}(t)| = \int_0^\infty \mathbf{P}\{|\widetilde{\mathbf{Q}}(t)| > u\} \, \mathrm{d}u$$
$$= E \int_0^\infty \mathbf{P}\{|\widetilde{\mathbf{Q}}(t)| > vE\} \, \mathrm{d}v$$

$$E = \mathbf{E}|\widetilde{\mathbf{Q}}(t)| = \int_0^\infty \mathbf{P}\{|\widetilde{\mathbf{Q}}(t)| > u\} \, \mathrm{d}u$$
$$= E \int_0^\infty \mathbf{P}\{|\widetilde{\mathbf{Q}}(t)| > vE\} \, \mathrm{d}v$$
$$\leq E \int_{1/2}^\infty \mathbf{P}\{|\widetilde{\mathbf{Q}}(t)| > vE\} \, \mathrm{d}v + \frac{1}{2}E$$

$$\begin{split} E &= \mathbf{E}|\widetilde{\mathbf{Q}}(t)| = \int_0^\infty \mathbf{P}\{|\widetilde{\mathbf{Q}}(t)| > u\} \, \mathrm{d}u \\ &= E \int_0^\infty \mathbf{P}\{|\widetilde{\mathbf{Q}}(t)| > vE\} \, \mathrm{d}v \\ &\leq E \int_{1/2}^\infty \mathbf{P}\{|\widetilde{\mathbf{Q}}(t)| > vE\} \, \mathrm{d}v + \frac{1}{2}E \\ &\leq c \cdot \frac{t^2}{E^2} + \frac{1}{2}E, \end{split}$$

that is, $E^3 \leq c \cdot t^2$.

$$\begin{split} E &= \mathbf{E}|\widetilde{\mathbf{Q}}(t)| = \int_0^\infty \mathbf{P}\{|\widetilde{\mathbf{Q}}(t)| > u\} \, \mathrm{d}u \\ &= E \int_0^\infty \mathbf{P}\{|\widetilde{\mathbf{Q}}(t)| > vE\} \, \mathrm{d}v \\ &\leq E \int_{1/2}^\infty \mathbf{P}\{|\widetilde{\mathbf{Q}}(t)| > vE\} \, \mathrm{d}v + \frac{1}{2}E \\ &\leq c \cdot \frac{t^2}{E^2} + \frac{1}{2}E, \end{split}$$

that is, $E^3 \leq c \cdot t^2$.

$$\begin{aligned} \mathsf{Var}(h_{Ct}(t)) \stackrel{\mathsf{Thm}}{=} \operatorname{const.} \cdot \mathsf{E}|\mathsf{Q}(t) - Ct| \\ &= \operatorname{const.} \cdot \mathsf{E} \leq c \cdot t^{2/3}. \end{aligned}$$

| Model | <u> </u> | Micro c.? | <i>t</i> ^{2/3} law |
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| Model | <u> </u> | Micro c.? | <i>t</i> ^{2/3} law |
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| TASEP | | | |
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| Model | <u>Η(</u> ₀) is | Micro c.? | <i>t</i> ^{2/3} law |
|-------|-----------------------------|-----------|-----------------------------|
| TASEP | concave | | |
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| Model | <i>Η</i> (<i>ϱ</i>) is | Micro c.? | <i>t</i> ^{2/3} law |
|-------|--------------------------|------------------|-----------------------------|
| TASEP | concave | $Q(t) \leq X(t)$ | |
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| Model | <i>Η</i> (<i>ϱ</i>) is | Micro c.? | <i>t</i> ^{2/3} law |
|-------|--------------------------|------------------|-----------------------------|
| TASEP | concave | $Q(t) \leq X(t)$ | proved (BS.) |
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| Model | <i>Η</i> (<i>ϱ</i>) is | Micro c.? | <i>t</i> ^{2/3} law |
|-------|--------------------------|------------------|-----------------------------|
| TASEP | concave | $Q(t) \leq X(t)$ | proved (BS.) |
| ASEP | | | |
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| Model | <i>Η</i> (<i>ϱ</i>) is | Micro c.? | <i>t</i> ^{2/3} law |
|-------|--------------------------|------------------|-----------------------------|
| TASEP | concave | $Q(t) \leq X(t)$ | proved (BS.) |
| ASEP | concave | | |
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| Model | <i>Η</i> (<i>ϱ</i>) is | Micro c.? | <i>t</i> ^{2/3} law |
|-------|--------------------------|------------------------|-----------------------------|
| TASEP | concave | $Q(t) \leq X(t)$ | proved (BS.) |
| ASEP | concave | $Q(t) \leq X(t) + Err$ | |
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| Model | <u> </u> | Micro c.? | <i>t</i> ^{2/3} law |
|-------|----------|-----------------------|-----------------------------|
| TASEP | concave | $Q(t) \leq X(t)$ | proved (BS.) |
| ASEP | concave | $Q(t) \le X(t) + Err$ | proved (<mark>BS</mark> .) |
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| Model | <i>Η</i> (<i>ϱ</i>) is | Micro c.? | <i>t</i> ^{2/3} law |
|--------------|--------------------------|-----------------------|-----------------------------|
| TASEP | concave | $Q(t) \leq X(t)$ | proved (BS.) |
| ASEP | concave | $Q(t) \le X(t) + Err$ | proved (BS.) |
| rate 1 TAZRP | | | |
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| Model | <i>Η</i> (<i>ϱ</i>) is | Micro c.? | <i>t</i> ^{2/3} law |
|--------------|--------------------------|-----------------------|-----------------------------|
| TASEP | concave | $Q(t) \leq X(t)$ | proved (BS.) |
| ASEP | concave | $Q(t) \le X(t) + Err$ | proved (BS.) |
| rate 1 TAZRP | concave | | |
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| Model | <i>Η</i> (<i>ϱ</i>) is | Micro c.? | <i>t</i> ^{2/3} law |
|--------------|--------------------------|------------------------|-----------------------------|
| TASEP | concave | $Q(t) \leq X(t)$ | proved (BS.) |
| ASEP | concave | $Q(t) \leq X(t) + Err$ | proved (BS.) |
| rate 1 TAZRP | concave | $Q(t) \leq X(t)$ | |
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| Model | <u> </u> | Micro c.? | <i>t</i> ^{2/3} law |
|--------------|----------|------------------------|-----------------------------|
| TASEP | concave | $Q(t) \leq X(t)$ | proved (BS.) |
| ASEP | concave | $Q(t) \leq X(t) + Err$ | proved (BS.) |
| rate 1 TAZRP | concave | $Q(t) \leq X(t)$ | proved (BK.) |
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| Model | <u> </u> | Micro c.? | <i>t</i> ^{2/3} law |
|---------------------------|----------|------------------------|-----------------------------|
| TASEP | concave | $Q(t) \leq X(t)$ | proved (BS.) |
| ASEP | concave | $Q(t) \leq X(t) + Err$ | proved (BS.) |
| rate 1 TAZRP | concave | $Q(t) \leq X(t)$ | proved (BK.) |
| concave exp rate TAZRP | | | |
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| Model | <u>Η(</u> ₂) is | Micro c.? | <i>t</i> ^{2/3} law |
|---------------------------|-----------------------------|------------------------|-----------------------------|
| TASEP | concave | $Q(t) \leq X(t)$ | proved (BS.) |
| ASEP | concave | $Q(t) \leq X(t) + Err$ | proved (BS.) |
| rate 1 TAZRP | concave | $Q(t) \leq X(t)$ | proved (BK.) |
| concave exp rate TAZRP | concave | | |
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| Model | <i>Η</i> (<i>ϱ</i>) is | Micro c.? | <i>t</i> ^{2/3} law |
|---------------------------|--------------------------|------------------------|-----------------------------|
| TASEP | concave | $Q(t) \leq X(t)$ | proved (BS.) |
| ASEP | concave | $Q(t) \leq X(t) + Err$ | proved (BS.) |
| rate 1 TAZRP | concave | $Q(t) \leq X(t)$ | proved (BK.) |
| concave exp rate TAZRP | concave | $Q(t) \le X(t) + Err$ | |
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| Model | <u> </u> | Micro c.? | <i>t</i> ^{2/3} law |
|---------------------------|----------|------------------------|------------------------------|
| TASEP | concave | $Q(t) \leq X(t)$ | proved (BS.) |
| ASEP | concave | $Q(t) \leq X(t) + Err$ | proved (<mark>BS</mark> .) |
| rate 1 TAZRP | concave | $Q(t) \leq X(t)$ | proved (BK.) |
| concave exp rate TAZRP | concave | $Q(t) \le X(t) + Err$ | proved (<mark>BKS</mark> .) |
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| Model | <u>Η(</u> ₀) is | Micro c.? | <i>t</i> ^{2/3} law |
|---------------------------|-----------------------------|------------------------|-----------------------------|
| TASEP | concave | $Q(t) \leq X(t)$ | proved (BS.) |
| ASEP | concave | $Q(t) \leq X(t) + Err$ | proved (<mark>BS</mark> .) |
| rate 1 TAZRP | concave | $Q(t) \leq X(t)$ | proved (<mark>BK</mark> .) |
| concave exp rate TAZRP | concave | $Q(t) \le X(t) + Err$ | proved (BKS.) |
| convex exp rate TABLP | | | |
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| Model | <u> </u> | Micro c.? | <i>t</i> ^{2/3} law |
|---------------------------|----------|------------------------|-----------------------------|
| TASEP | concave | $Q(t) \leq X(t)$ | proved (BS.) |
| ASEP | concave | $Q(t) \leq X(t) + Err$ | proved (BS.) |
| rate 1 TAZRP | concave | $Q(t) \leq X(t)$ | proved (BK.) |
| concave exp rate TAZRP | concave | $Q(t) \leq X(t) + Err$ | proved (BKS.) |
| convex exp rate TABLP | convex | | |
| | | | |

| Model | <u> </u> | Micro c.? | <i>t</i> ^{2/3} law |
|---------------------------|----------|------------------------|------------------------------|
| TASEP | concave | $Q(t) \leq X(t)$ | proved (BS.) |
| ASEP | concave | $Q(t) \le X(t) + Err$ | proved (<mark>BS</mark> .) |
| rate 1 TAZRP | concave | $Q(t) \leq X(t)$ | proved (BK.) |
| concave exp rate TAZRP | concave | $Q(t) \leq X(t) + Err$ | proved (<mark>BKS</mark> .) |
| convex exp rate TABLP | convex | $Q(t) \ge X(t) - Err$ | |
| | | | |

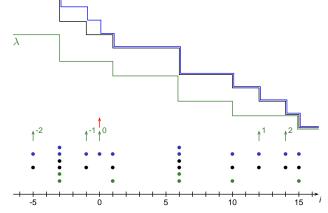
| Model | <i>Η</i> (<i>ϱ</i>) is | Micro c.? | <i>t</i> ^{2/3} law |
|---------------------------|--------------------------|------------------------|-----------------------------|
| TASEP | concave | $Q(t) \leq X(t)$ | proved (BS.) |
| ASEP | concave | $Q(t) \leq X(t) + Err$ | proved (BS.) |
| rate 1 TAZRP | concave | $Q(t) \leq X(t)$ | proved (BK.) |
| concave exp rate TAZRP | concave | $Q(t) \leq X(t) + Err$ | proved (BKS.) |
| convex exp rate TABLP | convex | $Q(t) \ge X(t) - Err$ | proved (BKS.) |
| | | | |

| Model | <u>Η(</u> ₂) is | Micro c.? | <i>t</i> ^{2/3} law |
|---|-----------------------------|------------------------|-----------------------------|
| TASEP | concave | $Q(t) \leq X(t)$ | proved (BS.) |
| ASEP | concave | $Q(t) \leq X(t) + Err$ | proved (BS.) |
| rate 1 TAZRP | concave | $Q(t) \leq X(t)$ | proved (BK.) |
| concave exp rate TAZRP | concave | $Q(t) \leq X(t) + Err$ | proved (BKS.) |
| convex exp rate TABLP | convex | $Q(t) \ge X(t) - Err$ | proved (BKS.) |
| less concave/convex rate (T)AZRP, (T)ABLP | | | |

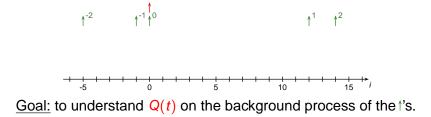
| Model | <i>Η</i> (<i>ϱ</i>) is | Micro c.? | <i>t</i> ^{2/3} law |
|---|--------------------------|------------------------|-----------------------------|
| TASEP | concave | $Q(t) \leq X(t)$ | proved (BS.) |
| ASEP | concave | $Q(t) \leq X(t) + Err$ | proved (BS.) |
| rate 1 TAZRP | concave | $Q(t) \leq X(t)$ | proved (BK.) |
| concave exp rate TAZRP | concave | $Q(t) \le X(t) + Err$ | proved (BKS.) |
| convex exp rate TABLP | convex | $Q(t) \ge X(t) - Err$ | proved (BKS.) |
| less concave/convex rate (T)AZRP, (T)ABLP | concave/ convex | | |

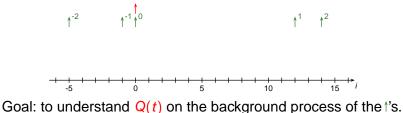
| Model | <i>Η</i> (<i>ϱ</i>) is | Micro c.? | <i>t</i> ^{2/3} law |
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| rate 1 TAZRP | concave | $Q(t) \leq X(t)$ | proved (<mark>BK</mark> .) |
| concave exp rate TAZRP | concave | $Q(t) \le X(t) + Err$ | proved (BKS.) |
| convex exp rate TABLP | convex | $Q(t) \ge X(t) - Err$ | proved (BKS.) |
| less concave/convex rate (T)AZRP, (T)ABLP | concave/ convex | ?? | |

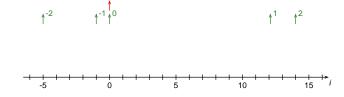
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<u>Goal</u>: to understand Q(t) on the background process of the t's.

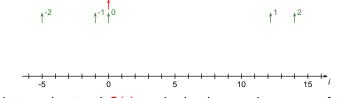




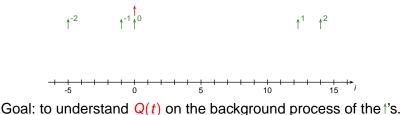


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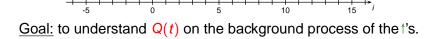
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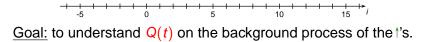
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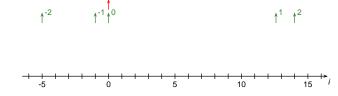






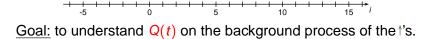




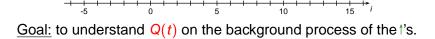


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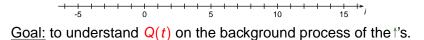




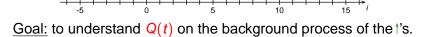




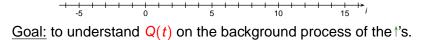




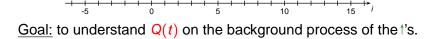




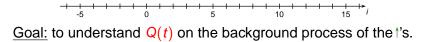




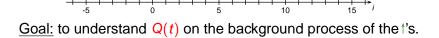




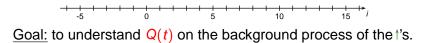




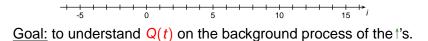




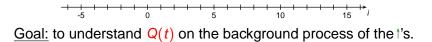




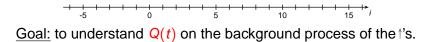




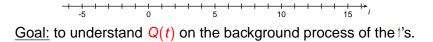




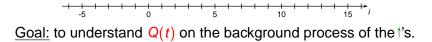




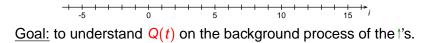




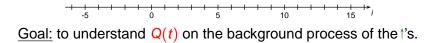




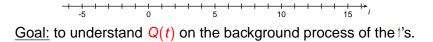




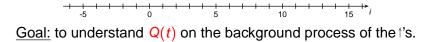




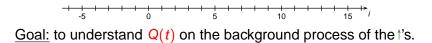




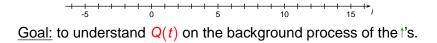


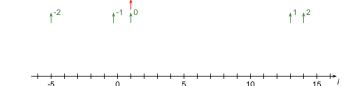




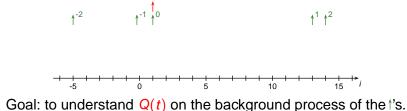


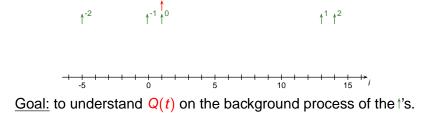


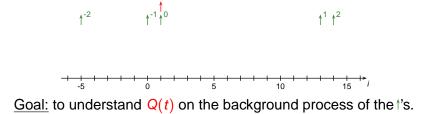




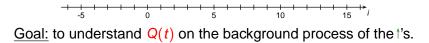
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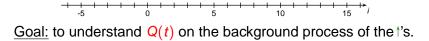


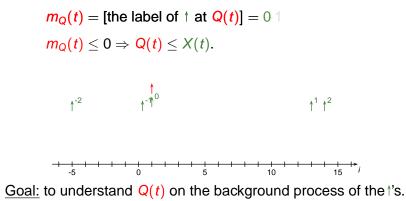


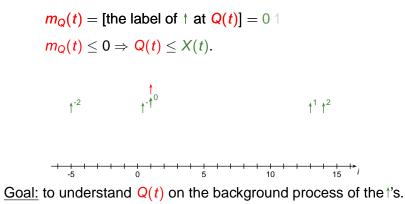
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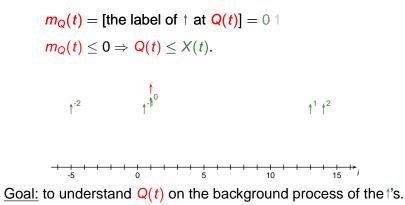


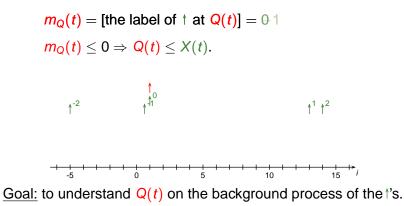
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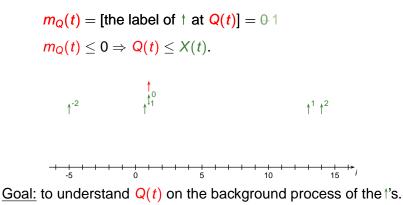


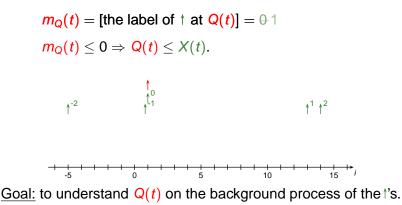


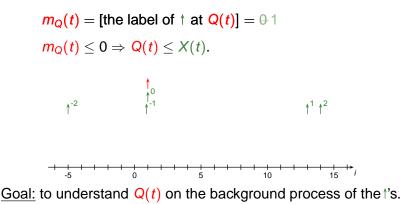


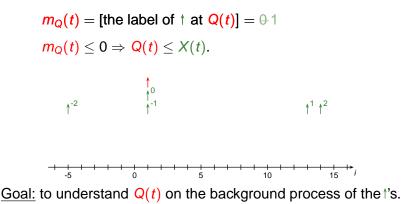


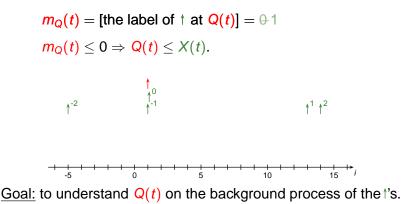


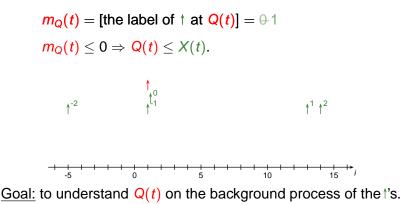


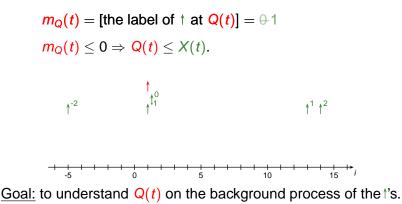


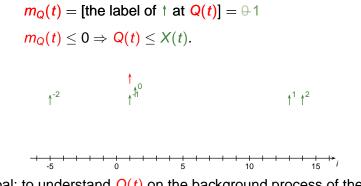




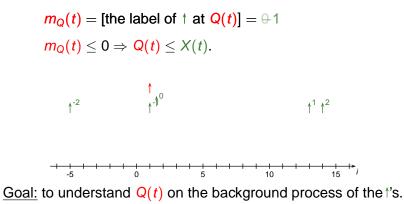


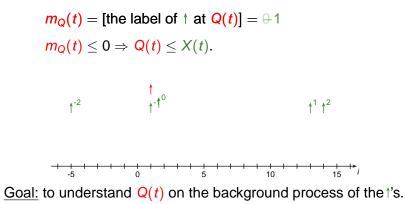






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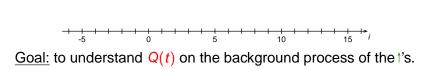


^⁻²

The critical feature: microscopic concavity $Q(t) \le X(t)$ +tight error

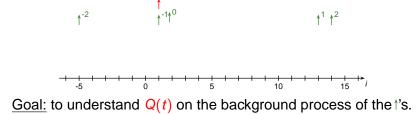
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> ↑ ^-11⁰

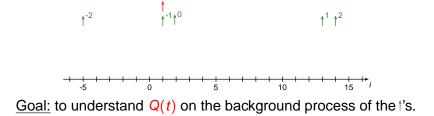


¹ ¹ ²

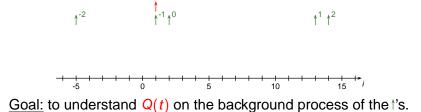
 $m_{O}(t) =$ [the label of \uparrow at $Q(t) = \oplus 1$ $m_{O}(t) < 0 \Rightarrow Q(t) < X(t).$



 $m_{O}(t) =$ [the label of \uparrow at Q(t) = -1 $m_{\rm Q}(t) \leq 0 \Rightarrow Q(t) \leq X(t).$



 $m_{\mathsf{Q}}(t) = [\text{the label of } \dagger \text{ at } \mathbf{Q}(t)] = -1$ $m_{\mathsf{Q}}(t) \le 0 \Rightarrow \mathbf{Q}(t) \le X(t).$



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This is the form of microscopic concavity we currently use: $m_Q(t)$ is dominated by a time-independent distribution with finite variance.

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Once this is done, we could proceed with less and less convex/concave models to see how $t^{1/3}$ scaling turns to $t^{1/4}$ for linear models (random average process, linear rate AZRP)...

Thank you.