

## 2 Probability

### The measure-theoretic parts

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We are now ready for a proper definition of probability.

**Definition 3** A function  $\mathbf{P} : \mathcal{F} \rightarrow \mathbb{R}$  is called a probability, or probability measure, if it is

- non-negative:  $\mathbf{P}\{E\} \geq 0 \quad \forall E \in \mathcal{F},$
- countably additive (or  $\sigma$ -additive): for all  $E_1, E_2, \dots$  finitely or countably infinitely many mutually exclusive events,

$$\mathbf{P}\left\{\bigcup_i E_i\right\} = \sum_i \mathbf{P}\{E_i\},$$

This little write-up is part of important foundations of probability that were left out of the unit Probability 1 due to lack of time and prerequisites. Here we include measure-theoretic definitions and a few simple propositions that could not be included in Probability 1. If you are after the well-posedness and rationale of those definitions, you can find them in any course or book on elementary measure theory.

### 1 Sample space and events

Probability deals with random experiments, the outcomes of which are modelled by a sample space  $\Omega$ . Events are special subsets of the set  $\Omega$ . When  $\Omega$  is finite or countably infinite, then we can consider all of its subsets without problems. However, if  $\Omega$  is uncountable, then we need measure theory to guide us along the subsets. We make some of the most basic definitions, those needed to properly build up probability, of measure theory below.

**Definition 1** Let  $\mathcal{F}$  be a set of subsets of  $\Omega$ , that is,  $\mathcal{F} \subseteq \mathcal{P}(\Omega)$ . Then  $\mathcal{F}$  is called a  $\sigma$ -algebra, if

- $\Omega \in \mathcal{F}$ , that is, the full sample space is included in  $\mathcal{F}$ ,
- $\forall E \in \mathcal{F} \quad E^c := \Omega - E \in \mathcal{F}$ , that is,  $\mathcal{F}$  is closed for taking complements,
- for any countably many sets  $E_1, E_2, \dots$  in  $\mathcal{F}$ ,  $\bigcup_{i=1}^{\infty} E_i \in \mathcal{F}$ , that is,  $\mathcal{F}$  is closed for taking countable unions.

Elements of the  $\sigma$ -algebra are usually called measurable sets.

From now on,  $\mathcal{F}$  will always denote a  $\sigma$ -algebra of  $\Omega$ , and its elements  $E$  (the measurable sets) will be called events. When  $\Omega$  is finite or countable, we almost always work with  $\mathcal{F} = \mathcal{P}(\Omega)$  = the power set of  $\Omega$ , being the set of all subsets of  $\Omega$ . When  $\Omega = \mathbb{R}$ , or an interval thereof, then we usually consider the Borel  $\sigma$ -algebra (the one generated by open intervals). Thus, in this case, not all subsets of the sample space can be considered events, only those measurable w.r.t. the Borel  $\sigma$ -algebra. We shall not exploit the theory of  $\sigma$ -algebras in detail, we only use the following simple facts that follow immediately from the definition:

- For all finitely many  $E_1, E_2, \dots, E_n$  in  $\mathcal{F}$ ,  $\bigcup_{i=1}^n E_i \in \mathcal{F}$ , thus  $\mathcal{F}$  is also closed for taking finite unions.
- It is also closed for taking finite or countably infinite intersections.
- $\emptyset \in \mathcal{F}$ , the empty set (or null event) is contained.

Many detailed down-to-earth examples have been provided in Probability 1. We proceed here with the important notion of limits of events.

**Definition 2** A sequence  $\{E_i\}_{i=1}^{\infty}$  of sets in  $\mathcal{F}$  is called increasing, if for all  $i \geq 1$  we have  $E_i \subseteq E_{i+1}$ . In this case  $E_i = \bigcup_{j=1}^i E_j$ , and we define the limit  $\lim_{i \rightarrow \infty} E_i = \bigcup_{i=1}^{\infty} E_i$ . Due to the definition of  $\sigma$ -algebras, this will again be an element of the  $\sigma$ -algebra. Similarly, a sequence  $\{E_i\}_{i=1}^{\infty}$  in  $\mathcal{F}$  is decreasing, if for all  $i \geq 1$  we have  $E_i \supseteq E_{i+1}$ . Then  $E_i = \bigcap_{j=1}^i E_j$ , and we define the limit  $\lim_{i \rightarrow \infty} E_i = \bigcap_{i=1}^{\infty} E_i$ , again an element of the  $\sigma$ -algebra.

Conditional probability has been motivated and its properties investigated in Probability 1. Here we only repeat its definition and notice one of its simple properties.

**Definition 5** Let  $F$  be an event of positive probability. The conditional probability of the event  $E$  given the condition  $F$  is defined as

$$\mathbf{P}\{E | F\} := \frac{\mathbf{P}\{E \cap F\}}{\mathbf{P}\{F\}}.$$

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In this case the triplet  $(\Omega, \mathcal{F}, \mathbf{P})$  is called a probability space.

The first two properties make up for the definition of a measure. It is the third property that in particular results in a probability measure. Several elementary propositions and examples have been included in Probability 1. One that was left out from there is the following:

**Proposition 4** (continuity of probability) Let  $\{E_i\}_i$  be an increasing or decreasing sequence of events. Then the limit on the left hand-side below exists, and

$$\lim_{i \rightarrow \infty} \mathbf{P}\{E_i\} = \mathbf{P}\left\{\lim_{i \rightarrow \infty} E_i\right\}.$$

*Proof.* Consider the case of increasing events first. Let

$$F_1 := E_1, \quad F_i := E_i - E_{i-1} \quad i > 1.$$

These events are mutually exclusive,

$$\bigcup_{j=1}^i F_j = \bigcup_{j=1}^i E_j = E_i \quad \text{and} \quad \bigcup_{j=1}^{\infty} F_j = \bigcup_{j=1}^{\infty} E_j = \lim_{j \rightarrow \infty} E_j.$$

Therefore

$$\lim_{i \rightarrow \infty} \mathbf{P}\{E_i\} = \lim_{i \rightarrow \infty} \mathbf{P}\left\{\bigcup_{j=1}^i F_j\right\} = \lim_{i \rightarrow \infty} \sum_{j=1}^i \mathbf{P}\{F_j\} = \mathbf{P}\left\{\bigcup_{j=1}^{\infty} F_j\right\} = \mathbf{P}\left\{\lim_{j \rightarrow \infty} E_j\right\}.$$

For decreasing events  $\{E_i^c\}_i$  is increasing, and

$$\begin{aligned} \lim_{i \rightarrow \infty} \mathbf{P}\{E_i\} &= 1 - \lim_{i \rightarrow \infty} \mathbf{P}\{E_i^c\} = 1 - \mathbf{P}\left\{\lim_{i \rightarrow \infty} E_i^c\right\} = 1 - \mathbf{P}\left\{\bigcup_{i=1}^{\infty} E_i^c\right\} \\ &= 1 - \mathbf{P}\left\{\left(\bigcap_{i=1}^{\infty} E_i\right)^c\right\} = \mathbf{P}\left\{\bigcap_{i=1}^{\infty} E_i\right\} = \mathbf{P}\left\{\lim_{i \rightarrow \infty} E_i\right\}. \end{aligned}$$

□

### 3 Conditional probability

Conditional probability has been motivated and its properties investigated in Probability 1. Here we only repeat its definition and notice one of its simple properties.

**Proposition 6** Let  $(\Omega, \mathcal{F}, \mathbf{P})$  be a probability space, and  $F \in \mathcal{F}$  an event of positive probability. Then  $\mathbf{P}\{\cdot | F\}$  is a probability measure:  $\mathbf{P}\{\cdot | F\} : \mathcal{F} \rightarrow \mathbb{R}$  is a set function that is

- non-negative:

$$\mathbf{P}\{E | F\} \geq 0 \quad \forall E \in \mathcal{F},$$

- countably additive (or  $\sigma$ -additive): for all  $E_1, E_2, \dots$  finitely or countably infinitely many mutually exclusive events

$$\mathbf{P}\left\{\bigcup_i E_i | F\right\} = \sum_i \mathbf{P}\{E_i | F\},$$

- normed to 1:

$$\mathbf{P}\{\Omega | F\} = 1.$$

*Proof.* Non-negativity is a trivial consequence of the definition. For countable additivity just notice that  $\{E_i \cap F\}_i$  is also a sequence of mutually exclusive events:

$$\mathbf{P}\left\{\bigcup_i E_i | F\right\} = \frac{\mathbf{P}\{(\bigcup_i E_i) \cap F\}}{\mathbf{P}\{F\}} = \frac{\mathbf{P}\{\bigcup_i (E_i \cap F)\}}{\mathbf{P}\{F\}} = \frac{\sum_i \mathbf{P}\{E_i \cap F\}}{\mathbf{P}\{F\}} = \sum_i \mathbf{P}\{E_i | F\}.$$

The third property is also easy:

$$\mathbf{P}\{\Omega | F\} = \frac{\mathbf{P}\{\Omega \cap F\}}{\mathbf{P}\{F\}} = \frac{\mathbf{P}\{F\}}{\mathbf{P}\{F\}} = 1.$$

**Corollary 7** All properties of  $\mathbf{P}\{\cdot | F\}$  remain valid for  $\mathbf{P}\{\cdot | F\}$ , unless one changes the condition  $F$ .

## 4 Random variables

Random variables have also been treated in Probability 1. Here we make a proper definition and explore some properties of the distribution function which needs continuity of probability from above.

**Definition 8** Fix the probability space  $(\Omega, \mathcal{F}, \mathbf{P})$ . A random variable is a measurable function  $X : \Omega \rightarrow \mathbb{R}$ , where  $\mathbb{R}$  is endowed with the Borel  $\sigma$ -algebra.

Often we just write  $X$  for a random variable and omit the function notation  $X(\omega)$ . Measurability of a function between two sets endowed with  $\sigma$  algebras means that the pre-image of measurable sets is measurable. In our case, the pre-image of a Borel set in  $\mathbb{R}$  is an event in  $\mathcal{F}$ . This make perfect sense: almost any question we might be interested in regarding a random variable is of the form  $X \in B$  with  $B$  in the Borel  $\sigma$ -algebra as this latter contains all countable unions and intersections of intervals. Then, the probability of such an event

$$\{X \in B\} = \{\omega \in \Omega : X(\omega) \in B\} = X^{-1}\{B\}$$

is meaningful as by measurability  $X^{-1}\{B\} \in \mathcal{F}$  is an event and as such it does have a probability.

Recall the definition

$$F : \mathbb{R} \rightarrow [0, 1] \quad ; \quad x \mapsto F(x) = \mathbf{P}\{X \leq x\}$$

of the cumulative distribution function of a random variable. We now give a proper proof of its limits and right-continuity.

**Proposition 9** Let  $F$  be the distribution function of the random variable  $X$ . Then

1.  $F$  is non-decreasing,

$$2. \lim_{x \rightarrow \infty} F(x) = 1,$$

$$3. \lim_{x \rightarrow -\infty} F(x) = 0,$$

4.  $F$  is continuous from the right.

Vice versa: any function  $F$  with the above properties is a cumulative distribution function. There is a sample space and a random variable on it that realises this distribution function.

*Proof.* We prove here the four properties only.

1. Let  $x < y$  be two fixed real numbers. Then as events  $\{X \leq x\} \subseteq \{X \leq y\}$ , thus  $F(x) = \mathbf{P}\{X \leq x\} \leq$

2. By the monotonicity of  $F$  and Proposition 4,

$$\begin{aligned} \lim_{x \rightarrow \infty} F(x) &= \lim_{n \rightarrow \infty} F(n) = \lim_{n \rightarrow \infty} \mathbf{P}\{X \leq n\} = \mathbf{P}\left\{\lim_{n \rightarrow \infty} \{X \leq n\}\right\} = \mathbf{P}\{\bigcup_{n \geq 0} \{X \leq n\}\} = \mathbf{P}\{\Omega\} = 1. \end{aligned}$$

3. Similarly,

$$\lim_{x \rightarrow -\infty} F(x) = \lim_{n \rightarrow -\infty} F(n) = \lim_{n \rightarrow -\infty} \mathbf{P}\{X \leq n\} = \mathbf{P}\left\{\bigcap_{n < 0} \{X \leq n\}\right\} = \mathbf{P}\{\emptyset\} = 0.$$

4. Let  $y \in \mathbb{R}$  be fixed. Then using monotonicity of  $F$  and Proposition 4 again,

$$\begin{aligned} \lim_{x \searrow y} F(x) &= \lim_{n \rightarrow \infty} F\left(y + \frac{1}{n}\right) = \lim_{n \rightarrow \infty} \mathbf{P}\left\{X \leq y + \frac{1}{n}\right\} \\ &= \mathbf{P}\left\{\lim_{n \rightarrow \infty} \left\{X \leq y + \frac{1}{n}\right\}\right\} = \mathbf{P}\left\{\bigcap_{n \geq 0} \left\{X \leq y + \frac{1}{n}\right\}\right\} = \mathbf{P}\{X \leq y\} = F(y). \end{aligned}$$

□

We refer to Probability 1 for the definition of discrete and absolutely continuous random variables, and mention Lebesgue's Decomposition Theorem without proof:

**Theorem 10** (Lebesgue's Decomposition Theorem) Let  $F$  be a distribution function. Then

$$F = F_{\text{absolutely continuous}} + F_{\text{discrete}} + F_{\text{singular}},$$

where

- $F_{\text{absolutely continuous}}$  is an absolutely continuous function, that is, there exists a function  $h \geq 0$  with
- $F_{\text{discrete}}$  is a piecewise constant, right-continuous non-decreasing function;
- $F_{\text{singular}}$  is a continuous, non-decreasing function which is singular to the Lebesgue measure. This is to say that its derivative is Lebesgue-almost everywhere zero. An example is the Cantor function which is the infinite composition of

$$G(x) = \begin{cases} \frac{3}{2}x, & 0 \leq x \leq \frac{1}{3}, \\ \frac{1}{2}, & \frac{1}{3} \leq x \leq \frac{2}{3}, \\ \frac{3}{2}x - \frac{1}{2}, & \frac{2}{3} \leq x \leq 1 \end{cases}$$

with itself.

Notice that in general the above  $F_\bullet$  terms are not distribution functions on their own (their limits do not necessarily satisfy Proposition 9).