# Multiple imputation in Cox regression when there are time-varying effects of exposures 

## Ruth Keogh

Department of Medical Statistics<br>London School of Hygiene and Tropical Medicine

## Bristol, 5 February 2016

## Outline

1. Handling missing data on explanatory variables in Cox regression
2. Modelling time-varying effects in Cox regression
3. Derive an imputation model which handles time-varying effects
4. Simulation study
5. An application
6. An alternative approach
7. Further work

## Outline

1. Handling missing data on explanatory variables in Cox regression
2. Modelling time-varying effects in Cox regression
3. Derive an imputation model which handles time-varying effects
4. Simulation study
5. An application
6. An alternative approach
7. Further work

## Multiple imputation in general

- Aim: To fit an analysis model $Y \sim X, Z$
- Missing data in explanatory variables is a very common problem in epidemiology
- Basic approach: Complete case analysis

Multiple imputation (MI)
For a partially missing exposure $X$, fully observed covariates $Z$
2. Obtain several imputed data sets
3. Fit the analysis model in each imputed data set and combine parameter estimates using Rubin's Rules

## Multiple imputation in general

- Aim: To fit an analysis model $Y \sim X, Z$
- Missing data in explanatory variables is a very common problem in epidemiology
- Basic approach: Complete case analysis


## Multiple imputation in general

- Aim: To fit an analysis model $Y \sim X, Z$
- Missing data in explanatory variables is a very common problem in epidemiology
- Basic approach: Complete case analysis


## Multiple imputation (MI)

For a partially missing exposure $X$, fully observed covariates $Z$

1. Draw values of $X$ from $X \mid Z, Y$
2. Obtain several imputed data sets
3. Fit the analysis model in each imputed data set and combine parameter estimates using Rubin's Rules

## Multiple imputation in general

## Main challenge

What is the distribution of $X \mid Z, Y$ ?
Example: Linear regression

$$
Y=\beta_{0}+\beta_{X} X+\beta_{Z} Z+\varepsilon
$$

- If $Y \mid X, Z \sim$ Normal and $X \mid Z \sim$ Normal then $X \mid Z, Y \sim$ Normal - Imputation model: $X=\alpha_{0}+\alpha_{1} Z+\alpha_{2} Y+\delta$ Steps

1. Obtain estimates $\hat{\alpha}_{0}, \hat{\alpha}_{1}, \hat{\alpha}_{2}, \hat{\sigma}_{\delta}^{2}$, and their variances/covariances
2. Draw values $\hat{\alpha}_{0}^{(m)}, \hat{\alpha}_{1}^{(m)}, \hat{\alpha}_{2}^{(m)}, \hat{\sigma}_{\delta}^{2(m)}$ from their estimated distn
3. The $m$ th imputation of $X$ is

## Multiple imputation in general

## Main challenge

What is the distribution of $X \mid Z, Y$ ?
Example: Linear regression

$$
Y=\beta_{0}+\beta_{X} X+\beta_{Z} Z+\varepsilon
$$

- If $Y \mid X, Z \sim$ Normal and $X \mid Z \sim$ Normal then $X \mid Z, Y \sim$ Normal
- Imputation model: $X=\alpha_{0}+\alpha_{1} Z+\alpha_{2} Y+\delta$

Steps

1. Obtain estimates $\hat{\alpha}_{0}, \hat{\alpha}_{1}, \hat{\alpha}_{2}, \hat{\sigma}_{\delta}^{2}$, and their variances/covariances
2. Draw values $\hat{\alpha}_{0}^{(m)}, \hat{\alpha}_{1}^{(m)}, \hat{\alpha}_{2}^{(m)}, \hat{\sigma}_{\delta}^{2(m)}$ from their estimated distn
3. The $m$ th imputation of $X$ is

## Multiple imputation in general

## Main challenge

What is the distribution of $X \mid Z, Y$ ?
Example: Linear regression

$$
Y=\beta_{0}+\beta_{X} X+\beta_{Z} Z+\varepsilon
$$

- If $Y \mid X, Z \sim$ Normal and $X \mid Z \sim$ Normal then $X \mid Z, Y \sim$ Normal
- Imputation model: $X=\alpha_{0}+\alpha_{1} Z+\alpha_{2} Y+\delta$


## Steps

1. Obtain estimates $\hat{\alpha}_{0}, \hat{\alpha}_{1}, \hat{\alpha}_{2}, \hat{\sigma}_{\delta}^{2}$, and their variances/covariances
2. Draw values $\hat{\alpha}_{0}^{(m)}, \hat{\alpha}_{1}^{(m)}, \hat{\alpha}_{2}^{(m)}, \hat{\sigma}_{\delta}^{2(m)}$ from their estimated distn
3. The $m$ th imputation of $X$ is

## Multiple imputation in general

## Main challenge

What is the distribution of $X \mid Z, Y$ ?
Example: Linear regression

$$
Y=\beta_{0}+\beta_{X} X+\beta_{Z} Z+\varepsilon
$$

- If $Y \mid X, Z \sim$ Normal and $X \mid Z \sim$ Normal then $X \mid Z, Y \sim$ Normal
- Imputation model: $X=\alpha_{0}+\alpha_{1} Z+\alpha_{2} Y+\delta$


## Steps

1. Obtain estimates $\hat{\alpha}_{0}, \hat{\alpha}_{1}, \hat{\alpha}_{2}, \hat{\sigma}_{\delta}^{2}$, and their variances/covariances
2. Draw values $\hat{\alpha}_{0}^{(m)}, \hat{\alpha}_{1}^{(m)}, \hat{\alpha}_{2}^{(m)}, \hat{\sigma}_{\delta}^{2(m)}$ from their estimated distn
3. The $m$ th imputation of $X$ is

## Multiple imputation in general

## Main challenge

What is the distribution of $X \mid Z, Y$ ?
Example: Linear regression

$$
Y=\beta_{0}+\beta_{X} X+\beta_{Z} Z+\varepsilon
$$

- If $Y \mid X, Z \sim$ Normal and $X \mid Z \sim$ Normal then $X \mid Z, Y \sim$ Normal
- Imputation model: $X=\alpha_{0}+\alpha_{1} Z+\alpha_{2} Y+\delta$


## Steps

1. Obtain estimates $\hat{\alpha}_{0}, \hat{\alpha}_{1}, \hat{\alpha}_{2}, \hat{\sigma}_{\delta}^{2}$, and their variances/covariances
2. Draw values $\hat{\alpha}_{0}^{(m)}, \hat{\alpha}_{1}^{(m)}, \hat{\alpha}_{2}^{(m)}, \hat{\sigma}_{\delta}^{2(m)}$ from their estimated distn
3. The $m$ th imputation of $X$ is

$$
X^{(m)}=\hat{\alpha}_{0}^{(m)}+\hat{\alpha}_{1}^{(m)} Z+\hat{\alpha}_{2}^{(m)} Y+\delta^{*}
$$

## Multiple imputation in Cox Regression

Cox proportional hazards model

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X} X+\beta_{Z} Z}
$$

- T: Event or censoring time
- D: Event indicator

Distribution of interest for the imputation:
$X \mid Z$, outcome

$$
\text { Event/censoring time } T \text {, event indicator D }
$$

## Multiple imputation in Cox Regression

## Cox proportional hazards model

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X} X+\beta_{Z} Z}
$$

- T: Event or censoring time
- D: Event indicator

Distribution of interest for the imputation:

$$
X \mid Z \text {, outcome }
$$

Event/censoring time $T$, event indicator $D$

## Multiple imputation in Cox Regression

## Cox proportional hazards model

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X} X+\beta_{Z} Z}
$$

- T: Event or censoring time
- D: Event indicator

Distribution of interest for the imputation:

$$
X \mid Z \text {, outcome }
$$

Event/censoring time $T$, event indicator $D$
What is this distribution $X \mid Z, T, D$ ??

## Multiple imputation in Cox Regression

Previously suggested imputation models:

$$
X \sim Z+D+T, \quad X \sim Z+D+\log T
$$

STATISTICS IN MEDICINE
Statist. Med. 2009; 28:1982-1998
Published online 19 May 2009 in Wiley InterScience
(www.interscience.wiley.com) DOI: $10.1002 / \mathrm{sim} .3618$

$$
\begin{aligned}
& \text { Imputing missing covariate values for the Cox model } \\
& \text { Ian R. White }{ }^{1, *, \dagger} \text { and Patrick Royston }{ }^{2} \\
& { }^{1} \text { MRC Biostatistics Unit, Institute of Public Health, Robinson Way, Cambridge CB2 osR, U.K. } \\
& { }^{2} \text { MRC Clinical Trials Unit, Cancer Group, London, U.K. }
\end{aligned}
$$

White and Royston imputation model


## Multiple imputation in Cox Regression

Previously suggested imputation models:

$$
X \sim Z+D+T, \quad X \sim Z+D+\log T
$$

STATISTICS IN MEDICINE
Statist. Med. 2009; 28:1982-1998
Published online 19 May 2009 in Wiley InterScience
(www.interscience.wiley.com) DOI: $10.1002 / \mathrm{sim} .3618$

Imputing missing covariate values for the Cox model
Ian R. White ${ }^{1, *, \dagger}$ and Patrick Royston ${ }^{2}$
${ }^{1}$ MRC Biostatistics Unit, Institute of Public Health, Robinson Way, Cambridge CB2 OSR, U.K.
${ }^{2}$ MRC Clinical Trials Unit, Cancer Group, London, U.K.
White and Royston imputation model

$$
X \sim Z+D+H_{0}(T)
$$

Cumulative baseline hazard

## Outline

1. Handling missing data on explanatory variables in Cox regression
2. Modelling time-varying effects in Cox regression
3. Derive an imputation model which handles time-varying effects
4. Simulation study
5. An application
6. An alternative approach
7. Further work

## Modelling time-varying effects in Cox regression

Standard Cox proportional hazards model

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X} X+\beta_{Z} Z}
$$

- Sometimes we want to study how the effect of the exposure changes over time

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X}}
$$

- This also enables a test of the proportional hazards assumption


## Modelling time-varying effects in Cox regression

## Standard Cox proportional hazards model

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X} X+\beta_{Z} Z}
$$

- Sometimes we want to study how the effect of the exposure changes over time


## Extended Cox model with time-varying effects

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X}(T) X+\beta_{Z} Z}
$$

- This also enables a test of the proportional hazards assumption


## Modelling time-varying effects in Cox regression

## Extended Cox model with time-varying effects

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X}(T) X+\beta_{Z} Z}
$$

- Smooth pre-specified form:

$$
\beta_{X}(T)=\beta_{X}+\beta_{X T} \log (T)
$$



- Step function:



## Modelling time-varying effects in Cox regression

## Extended Cox model with time-varying effects

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X}(T) X+\beta_{Z} Z}
$$

- Smooth pre-specified form:

$$
\beta_{X}(T)=\beta_{X}+\beta_{X T} \log (T)
$$



- Step function:

$$
\beta_{X}(T)= \begin{cases}\beta_{X 1} & 0<T \leq u_{1} \\ \beta_{X 2} & u_{1}<T \leq u_{2} \\ \beta_{X 3} & u_{2}<T \leq u_{3} \\ \beta_{X 4} & T>u_{3}\end{cases}
$$



## Modelling time-varying effects in Cox regression

## Extended Cox model with time-varying effects

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X}(T) X+\beta_{Z} Z}
$$

- Restricted cubic spline

$$
\beta_{X}(T)=\beta_{X 0}+\beta_{X 1} T+\beta_{X 2}\left\{\left(T-u_{1}\right)_{+}^{3}-\left(\frac{\left(T-u_{2}\right)_{+}^{3}\left(u_{3}-u_{1}\right)}{\left(u_{3}-u_{2}\right)}\right)+\left(\frac{\left(T-u_{3}\right)_{+}^{3}\left(u_{2}-u_{1}\right)}{\left(u_{3}-u_{2}\right)}\right)\right\}
$$

## Modelling time-varying effects in Cox regression

## Extended Cox model with time-varying effects

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X}(T) X+\beta_{Z} Z}
$$

- Restricted cubic spline

$$
\beta_{X}(T)=\beta_{X 0}+\beta_{X 1} T+\beta_{X 2}\left\{\left(T-u_{1}\right)_{+}^{3}-\left(\frac{\left(T-u_{2}\right)_{+}^{3}\left(u_{3}-u_{1}\right)}{\left(u_{3}-u_{2}\right)}\right)+\left(\frac{\left(T-u_{3}\right)_{+}^{3}\left(u_{2}-u_{1}\right)}{\left(u_{3}-u_{2}\right)}\right)\right\}
$$

## How do we handle missing data in this situations?

## Extended Cox model with time-varying effects

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X}(T) X+\beta_{Z} Z}
$$

What is the distribution of $X \mid T, D, Z$ ?

$$
p(X \mid T, D, Z)
$$

## Aims

1. Derive an (approximate) imputation model

- By extending the work of White \& Royston

2. Assess the performance of the imputation model using simulations

## Motivation

- Investigation of the long-term efficacy of the BCG vaccine for TB
- Time-varying effect investigated for vaccination status:
- 0-5 yrs
- 5-10 yrs
- 10-15 yrs
- 15+ yrs post-vaccination
- Missing data on vaccination status
- Also missing data on adjustment variables


## Outline

1. Handling missing data on explanatory variables in Cox regression
2. Modelling time-varying effects in Cox regression
3. Derive an imputation model which handles time-varying effects
4. Simulation study
5. An application
6. An alternative approach
7. Further work

## Derivation of imputation model

## Extended Cox model with time-varying effects

$$
\begin{gathered}
h(T \mid X, Z)=h_{0}(T) e^{\beta \chi(T) X+\beta_{Z} Z} \\
p(X \mid T, D, Z)=p(X \mid Z) p(T, D \mid X, Z) / p(T, D \mid Z) \\
\text { We will specify } \\
\propto h(T \mid X, Z)^{D} \times \operatorname{Pr}(\text { survive to time } T \mid X, Z)
\end{gathered}
$$

General result
$\log n(X \mid T, D, Z)=\log p(X \mid Z)+D \beta_{X}(T) X+D \beta_{Z} Z$ $h_{0}(u) e^{\beta_{X}(u) X+\beta_{Z} Z} \mathrm{~d} u+$ const

## Derivation of imputation model

Extended Cox model with time-varying effects

$$
\begin{gathered}
h(T \mid X, Z)=h_{0}(T) e^{\beta X(T) X+\beta_{Z} Z} \\
p(X \mid T, D, Z)=p(X \mid Z) p(T, D \mid X, Z) / p(T, D \mid Z)
\end{gathered}
$$

We will specify

$$
\propto h(T \mid X, Z)^{D} \times \operatorname{Pr}(\text { survive to time } T \mid X, Z)
$$

General result

## Derivation of imputation model

## Extended Cox model with time-varying effects

$$
\begin{gathered}
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X}(T) X+\beta_{Z} Z} \\
p(X \mid T, D, Z)=p(X \mid Z) p(T, D \mid X, Z) / p(T, D \mid Z) \\
\text { We will specify }
\end{gathered}
$$

$$
\propto h(T \mid X, Z)^{D} \times \operatorname{Pr}(\text { survive to time } T \mid X, Z)
$$

General result
$\log n(X \mid T, D, Z)=\log p(X \mid Z)+D \beta_{X}(T) X+D \beta_{Z} Z$

## Derivation of imputation model

## Extended Cox model with time-varying effects

$$
\begin{gathered}
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X}(T) X+\beta_{Z} Z} \\
p(X \mid T, D, Z)=p(X \mid Z) p(T, D \mid X, Z) / p(T, D \mid Z) \\
\text { We will specify }
\end{gathered}
$$

$$
\propto h(T \mid X, Z)^{D} \times \operatorname{Pr}(\text { survive to time } T \mid X, Z)
$$

## Derivation of imputation model

## Extended Cox model with time-varying effects

$$
\begin{gathered}
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X}(T) X+\beta_{Z} Z} \\
p(X \mid T, D, Z)=p(X \mid Z) p(T, D \mid X, Z) / p(T, D \mid Z) \\
\text { We will specify }
\end{gathered}
$$

$$
\propto h(T \mid X, Z)^{D} \times \operatorname{Pr}(\text { survive to time } T \mid X, Z)
$$

## General result

$$
\begin{aligned}
\log p(X \mid T, D, Z) & =\log p(X \mid Z)+D \beta_{X}(T) X+D \beta_{Z} Z \\
& -\int_{0}^{T} h_{0}(u) e^{\beta_{X}(u) X+\beta_{Z} Z} \mathrm{~d} u+\text { const }
\end{aligned}
$$

## Derivation of imputation model

## General result

$$
\begin{aligned}
\log p(X \mid T, D, Z) & =\log p(X \mid Z)+D \beta_{X}(T) X+D \beta_{Z} Z \\
& -\int_{0}^{T} h_{0}(u) e^{\beta_{X}(u) X+\beta_{Z} Z} \mathrm{~d} u+\text { const }
\end{aligned}
$$

How do we apply this when...?

1. $X$ is binary

$$
\text { logit } \operatorname{Pr}(X=1 \mid Z)=\zeta_{0}+\zeta_{1} Z
$$

2. $X$ is Normally distributed given $Z$

$$
X \mid Z \sim N\left(\zeta_{0}+\zeta_{1} Z, \sigma^{2}\right)
$$

## Binary $X$

## General result

$$
\begin{aligned}
\log p(X \mid T, D, Z) & =\log p(X \mid Z)+D \beta_{X}(T) X+D \beta_{Z} Z \\
& -\int_{0}^{T} h_{0}(u) e^{\beta_{X}(u) X+\beta_{Z} Z} \mathrm{~d} u+\text { const }
\end{aligned}
$$

$$
\text { logit } p(X=1 \mid Z)=\zeta_{0}+\zeta_{1} Z
$$

## Binary $X$

## General result

$$
\begin{aligned}
\log p(X \mid T, D, Z) & =\log p(X \mid Z)+D \beta_{X}(T) X+D \beta_{Z} Z \\
& -\int_{0}^{T} h_{0}(u) e^{\beta_{X}(u) X+\beta_{Z} z} \mathrm{~d} u+\text { const }
\end{aligned}
$$

$$
\operatorname{logit} p(X=1 \mid Z)=\zeta_{0}+\zeta_{1} Z
$$

## Binary $X$

## General result

$$
\begin{aligned}
& \log p(X \mid T, D, Z)=\log p(X \mid Z)+D \beta_{X}(T) X+D \beta_{Z} Z \\
&-\int_{0}^{T} h_{0}(u) e^{\beta_{X}(u) X+\beta_{Z} Z} \mathrm{~d} u+\mathrm{const} \\
& \text { logit } p(X=1 \mid Z)=\zeta_{0}+\zeta_{1} Z \\
& e^{\beta_{X}(u)} \approx e^{\beta_{X}(\bar{u})}+(u-\bar{u}) \beta_{X}^{\prime}(\bar{u}) e^{\beta_{X}(\bar{u})}
\end{aligned}
$$

## Binary $X$

## General result

$$
\begin{aligned}
\log p(X \mid T, D, Z) & =\log p(X \mid Z)+D \beta_{X}(T) X+D \beta_{Z} Z \\
& -\int_{0}^{T} h_{0}(u) e^{\beta_{X}(u) X+\beta_{Z} Z} \mathrm{~d} u+\text { const }
\end{aligned}
$$

$$
\text { logit } p(X=1 \mid Z)=\zeta_{0}+\zeta_{1} Z
$$

$$
e^{\beta_{X}(u)} \approx e^{\beta_{X}(\bar{u})}+(u-\bar{u}) \beta_{X}^{\prime}(\bar{u}) e^{\beta_{X}(\bar{u})}
$$

## Imputation model: $Z$ categorical

$$
\begin{array}{r}
\quad \text { logit } p(X=1 \mid T, D, Z) \approx \alpha_{0}+\alpha_{1} Z+\alpha_{2} D \beta_{X}(T) \\
+\alpha_{3} H_{0}(T)+\alpha_{5} Z H_{0}(T)+\alpha_{4} H_{0}^{(1)}(T)+\alpha_{6} Z H_{0}^{(1)}(T)
\end{array}
$$

## Binary $X$

## General result

$$
\begin{aligned}
\log p(X \mid T, D, Z) & =\log p(X \mid Z)+D \beta_{X}(T) X+D \beta_{Z} Z \\
& -\int_{0}^{T} h_{0}(u) e^{\beta_{X}(u) X+\beta_{Z} z^{2} u+\text { const }}
\end{aligned}
$$

$$
\operatorname{logit} p(X=1 \mid Z)=\zeta_{0}+\zeta_{1} Z
$$

$$
e^{\beta_{x}(u)} \approx e^{\beta_{x}(\bar{u})}+(u-\bar{u}) \beta_{x}^{\prime}(\bar{u}) e^{\beta_{x}(\bar{u})}
$$

## Imputation model: $Z$ categorical

$$
\begin{array}{r}
\quad \text { logit } p(X=1 \mid T, D, Z) \approx \alpha_{0}+\alpha_{1} Z+\alpha_{2} D \beta_{X}(T) \\
+\alpha_{3} H_{0}(T)+\alpha_{5} Z H_{0}(T)+\alpha_{4} H_{0}^{(1)}(T)+\alpha_{6} Z H_{0}^{(1)}(T)
\end{array}
$$

$$
H_{0}(T)=\int_{0}^{T} h_{0}(u) d u
$$

$$
H_{0}^{(1)}(T)=\int_{0}^{T} u h_{0}(u) d u
$$

## Binary $X$

## General result

$$
\begin{aligned}
\log p(X \mid T, D, Z) & =\log p(X \mid Z)+D \beta_{X}(T) X+D \beta_{Z} Z \\
& -\int_{0}^{T} h_{0}(u) e^{\beta_{X}(u) X+\beta_{Z} z} \mathrm{~d} u+\text { const }
\end{aligned}
$$

logit $p(X=1 \mid Z)=\zeta_{0}+\zeta_{1} Z$

$$
e^{\beta_{X}(u)} \approx e^{\beta_{X}(\bar{u})}+(u-\bar{u}) \beta_{X}^{\prime}(\bar{u}) e^{\beta_{X}(\bar{u})}
$$

logit $p(X=1 \mid T, D, Z) \approx \alpha_{0}+\alpha_{1} Z+\alpha_{2} D \beta_{X}(T)+$


## Binary $X$

General result

$$
\begin{aligned}
\log p(X \mid T, D, Z) & =\log p(X \mid Z)+D \beta_{X}(T) X+D \beta_{Z} Z \\
& -\int_{0}^{T} h_{0}(u) e^{\beta_{X}(u) X+\beta_{Z} z} \mathrm{~d} u+\text { const } \\
\text { logit } p(X=1 \mid Z) & =\zeta_{0}+\zeta_{1} Z \quad e^{\beta_{Z} Z} \approx e^{\beta_{Z} \bar{Z}}+(Z-\bar{Z}) \beta_{Z} e^{\beta_{Z} \bar{Z}} \\
& e^{\beta_{X}(u)} \approx e^{\beta_{X}(\bar{u})}+(u-\bar{u}) \beta_{X}^{\prime}(\bar{u}) e^{\beta_{X}(\bar{u})}
\end{aligned}
$$

logit $p(X=1 \mid T, D, Z) \approx \alpha_{0}+\alpha_{1} Z+\alpha_{2} D \beta_{X}(T)+$


## Binary $X$

## General result

$$
\begin{aligned}
\log p(X \mid T, D, Z) & =\log p(X \mid Z)+D \beta_{X}(T) X+D \beta_{Z} Z \\
& -\int_{0}^{T} h_{0}(u) e^{\beta_{X}(u) X+\beta_{Z} Z} \mathrm{~d} u+\text { const } \\
\text { logit } p(X=1 \mid Z) & =\zeta_{0}+\zeta_{1} Z \quad e^{\beta_{Z} Z} \approx e^{\beta_{z} \bar{Z}}+(Z-\bar{Z}) \beta_{Z} e^{\beta_{Z} \bar{Z}} \\
& e^{\beta_{X}(u)} \approx e^{\beta_{X}(\bar{u})}+(u-\bar{u}) \beta_{X}^{\prime}(\bar{u}) e^{\beta_{X}(\bar{u})}
\end{aligned}
$$

## Imputation model: $Z$ continuous

$$
\begin{aligned}
& \text { logit } p(X=1 \mid T, D, Z) \approx \alpha_{0}+\alpha_{1} Z+\alpha_{2} D \beta_{X}(T)+ \\
& \alpha_{3} H_{0}(T)+\alpha_{5} Z H_{0}(T)+\alpha_{4} H_{0}^{(1)}(T)+\alpha_{6} Z H_{0}^{(1)}(T)
\end{aligned}
$$

## Normally distributed $X$

General result

$$
\begin{aligned}
\log p(X \mid T, D, Z) & =\log p(X \mid Z)+D \beta_{X}(T) X+D \beta_{Z} Z \\
& -\int_{0}^{T} h_{0}(u) e^{\beta_{X}(u) X+\beta_{Z} Z} \mathrm{~d} u+\text { const }
\end{aligned}
$$

$$
X \mid Z \sim N\left(\zeta_{0}+\zeta_{1} Z, \sigma^{2}\right)
$$

linear or quadratic approximation for $e^{\beta_{X}(u) X+\beta_{Z} Z}$

## Normally distributed $X$

General result

$$
\left.\begin{array}{rl}
\log p(X \mid T, D, Z) & =\log p(X \mid Z)+D \beta_{X}(T) X+D \beta_{Z} Z \\
& -\int_{0}^{T} h_{0}(u) e^{\beta_{X}(u) X+\beta_{Z} Z} \mathrm{~d} u+\text { const }
\end{array}\right\}
$$

linear or quadratic approximation for $e^{\beta_{X}(u) X+\beta_{Z} Z}$

$$
X=\alpha_{0}+\alpha_{1} Z+\alpha_{2} D \beta_{X}(T)+\alpha_{3} H_{0}(T)
$$

## Normally distributed $X$

General result

$$
\begin{aligned}
& \log p(X \mid T, D, Z)=\log p(X \mid Z)+D \beta_{X}(T) X+D \beta_{Z} Z \\
& \quad \int_{0}^{T} h_{0}(u) e^{\beta_{X}(u) X+\beta_{Z} Z} \mathrm{~d} u+\text { const } \\
& X \mid Z \sim N\left(\zeta_{0}+\zeta_{1} Z, \sigma^{2}\right)
\end{aligned}
$$

linear or quadratic approximation for $e^{\beta_{X}(\omega) X+\beta_{Z} z}$

## Imputation model: a linear regression

$$
\begin{array}{r}
X=\alpha_{0}+\alpha_{1} Z+\alpha_{2} D \beta_{X}(T)+\alpha_{3} H_{0}(T) \\
+\alpha_{5} Z H_{0}(T)+\alpha_{4} H_{0}^{(1)}(T)+\alpha_{6} Z H_{0}^{(1)}(T)+\varepsilon
\end{array}
$$

## Normally distributed $X$

## General result

$$
\begin{aligned}
& \log p(X \mid T, D, Z)=\log p(X \mid Z)+D \beta_{X}(T) X+D \beta_{Z} Z \\
& \quad \int_{0}^{T} h_{0}(u) e^{\beta_{X}(u) X+\beta_{Z} z^{\mathrm{d}} \mathrm{~d} u+\text { const }} \\
& X \mid Z \sim N\left(\zeta_{0}+\zeta_{1} Z, \sigma^{2}\right)
\end{aligned}
$$

linear or quadratic approximation for $e^{\beta_{X}(\omega) X+\beta_{z} z}$

## Imputation model: a linear regression

$$
\begin{array}{r}
X=\alpha_{0}+\alpha_{1} Z+\alpha_{2} D \beta_{X}(T)+\alpha_{3} H_{0}(T) \\
+\alpha_{5} Z H_{0}(T)+\alpha_{4} H_{0}^{(1)}(T)+\alpha_{6} Z H_{0}^{(1)}(T)+\varepsilon
\end{array}
$$

- Approximation assumes that $\beta_{X}(u), \beta_{Z}$ or $H_{0}(T)$ is small


## Summary

## Imputation model

$$
\begin{array}{r}
\text { logit } p(X=1 \mid T, D, Z) \approx \alpha_{0}+\alpha_{1} Z+\alpha_{2} D \beta_{X}(T)+\alpha_{3} H_{0}(T) \\
+\alpha_{5} Z H_{0}(T)+\alpha_{4} H_{0}^{(1)}(T)+\alpha_{6} Z H_{0}^{(1)}(T)
\end{array}
$$

- Breslow's estimate

$$
\widehat{H}_{0}(T)=\sum_{t \leq T} \frac{1}{\sum_{R(t)} e^{\hat{\beta}_{X}(t) X+\hat{\beta}_{Z} Z}}
$$

- The Nelson-Aalen estimate

$$
\widehat{H}(T)=\sum_{t \leq T} \frac{\text { number of events at } t}{\text { number at risk at } t}
$$

- A Nelson-Aalen-type estimate

$$
\widehat{H}^{(1)}(T)=\sum_{t \leqslant T} \frac{t \times \text { number of events at } t}{\text { number at risk at } t}
$$

## Summary

## Imputation model

$$
\begin{array}{r}
\text { logit } p(X=1 \mid T, D, Z) \approx \alpha_{0}+\alpha_{1} Z+\alpha_{2} D \beta_{X}(T)+\alpha_{3} H_{0}(T) \\
+\alpha_{5} Z H_{0}(T)+\alpha_{4} H_{0}^{(1)}(T)+\alpha_{6} Z H_{0}^{(1)}(T)
\end{array}
$$

- Breslow's estimate

$$
\widehat{H}_{0}(T)=\sum_{t \leq T} \frac{1}{\sum_{R(t)} e^{\hat{\beta}_{X}(t) X+\hat{\beta}_{Z} Z}}
$$

- The Nelson-Aalen estimate

- A Nelson-Aalen-type estimate



## Summary

## Imputation model

$$
\begin{array}{r}
\text { logit } p(X=1 \mid T, D, Z) \approx \alpha_{0}+\alpha_{1} Z+\alpha_{2} D \beta_{X}(T)+\alpha_{3} H_{0}(T) \\
+\alpha_{5} Z H_{0}(T)+\alpha_{4} H_{0}^{(1)}(T)+\alpha_{6} Z H_{0}^{(1)}(T)
\end{array}
$$

- Breslow's estimate

$$
\widehat{H}_{0}(T)=\sum_{t \leq T} \frac{1}{\sum_{R(t)} e^{\hat{\beta}_{X}(t) X+\hat{\beta}_{Z} Z}}
$$

- The Nelson-Aalen estimate

$$
\widehat{H}(T)=\sum_{t \leq T} \frac{\text { number of events at } t}{\text { number at risk at } t}
$$

- A Nelson-Aalen-type estimate



## Summary

## Imputation model

$$
\begin{array}{r}
\text { logit } p(X=1 \mid T, D, Z) \approx \alpha_{0}+\alpha_{1} Z+\alpha_{2} D \beta_{X}(T)+\alpha_{3} H_{0}(T) \\
+\alpha_{5} Z H_{0}(T)+\alpha_{4} H_{0}^{(1)}(T)+\alpha_{6} Z H_{0}^{(1)}(T)
\end{array}
$$

- Breslow's estimate

$$
\widehat{H}_{0}(T)=\sum_{t \leq T} \frac{1}{\sum_{R(t)} e^{\hat{\beta}_{X}(t) X+\hat{\beta}_{Z} Z}}
$$

- The Nelson-Aalen estimate

$$
\widehat{H}(T)=\sum_{t \leq T} \frac{\text { number of events at } t}{\text { number at risk at } t}
$$

- A Nelson-Aalen-type estimate

$$
\widehat{H}^{(1)}(T)=\sum_{t \leq T} \frac{t \times \text { number of events at } t}{\text { number at risk at } t}
$$

## Summary

## Imputation model

$$
\begin{array}{r}
\text { logit } p(X=1 \mid T, D, Z) \approx \alpha_{0}+\alpha_{1} Z+\alpha_{2} D \beta_{X}(T)+\alpha_{3} \widehat{H}(T) \\
+\alpha_{5} Z \widehat{H}(T)+\alpha_{4} \widehat{H}^{(1)}(T)+\alpha_{6} Z \widehat{H}^{(1)}(T)
\end{array}
$$

- Breslow's estimate

$$
\widehat{H}_{0}(T)=\sum_{t \leq T} \frac{1}{\sum_{R(t)} e^{\hat{\beta}_{X}(t) X+\hat{\beta}_{Z} Z}}
$$

- The Nelson-Aalen estimate

$$
\widehat{H}(T)=\sum_{t \leq T} \frac{\text { number of events at } t}{\text { number at risk at } t}
$$

- A Nelson-Aalen-type estimate

$$
\widehat{H}^{(1)}(T)=\sum_{t \leq T} \frac{t \times \text { number of events at } t}{\text { number at risk at } t}
$$

## Summary

## Imputation model

$$
\begin{array}{r}
\text { logit } p(X=1 \mid T, D, Z) \approx \alpha_{0}+\alpha_{1} Z+\alpha_{2} D \beta_{X}(T)+\alpha_{3} \widehat{H}(T) \\
+\alpha_{5} Z \widehat{H}(T)+\alpha_{4} \widehat{H}^{(1)}(T)+\alpha_{6} Z \widehat{H}^{(1)}(T)
\end{array}
$$

mice in $R$, mi impute in Stata
In simulations we investigate..

- What happens if we ignore the time-varying effect in the imputation (White \& Royston method)?
- When are the $\widehat{H}^{(1)}$ terms needed?
- When are the interactions terms needed?
- Does the approximation required for the linear regression situation perform well?


## Summary

## Imputation model

$$
\text { logit } \begin{array}{r}
p(X=1 \mid T, D, Z) \approx \alpha_{0}+\alpha_{1} Z+\alpha_{2} D \beta_{X}(T)+\alpha_{3} \widehat{H}(T) \\
+\alpha_{5} Z \widehat{H}(T)+\alpha_{4} \widehat{H}^{(1)}(T)+\alpha_{6} Z \widehat{H}^{(1)}(T)
\end{array}
$$

$$
\text { mice in } R, \text { mi impute in Stata }
$$

In simulations we investigate...

- What happens if we ignore the time-varying effect in the imputation (White \& Royston method)?
- When are the $\widehat{H}^{(1)}$ terms needed?
- When are the interactions terms needed?
- Does the approximation required for the linear regression situation perform well?


## Specific example: log time interaction analysis

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X} X+\beta_{\chi} T \log (T) X+\beta_{Z} Z}
$$



## Imputation model

$$
\text { logit } p(X=1 \mid T, D, Z) \approx \alpha_{0}+\alpha_{1} Z+\alpha_{21} D+\alpha_{22} D \log (T)+\alpha_{3} \widehat{H}(T)
$$

$$
+\alpha_{4} \widehat{H}^{(1)}(T)+\alpha_{5} Z \widehat{H}(T)+\alpha_{6} Z \widehat{H}^{(1)}(T)
$$

## Extension to missingness in several variables

## Extended Cox model with time-varying effects

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X}(T) X+\beta_{Z} Z}
$$

- Often we will have missing data in $Z$ as well as $X$
- This can be handled using multiple imputation by chained equations (MICE), aka fully conditional specification (FCS)
- We specify models for
- $X \mid Z, T, D$
- $Z \mid X, T, D$


## Outline

1. Handling missing data on explanatory variables in Cox regression
2. Modelling time-varying effects in Cox regression
3. Derive an imputation model which handles time-varying effects
4. Simulation study
5. An application
6. An alternative approach
7. Further work

## Simulation study

- Cohort of 5000 people followed for 10 years
- Binary or normally distributed exposure $X$
- Normally distributed covariate $Z: \operatorname{corr}(X, Z)=0.5$

$$
h(T \mid X, Z)=\lambda \exp \left\{\beta_{X} X+\beta_{X T} X(\log T-\log 5)+\beta_{Z} Z\right\}
$$



- $10 \%$ have the event
- Missing data in $20 \%$ of $X$ and $20 \%$ of $Z$ (MCAR)


## Simulation study

- Cohort of 5000 people followed for 10 years
- Binary or normally distributed exposure $X$
- Normally distributed covariate $Z: \operatorname{corr}(X, Z)=0.5$


## Hazard model

$$
h(T \mid X, Z)=\lambda \exp \left\{\beta_{X} X+\beta_{X T} X(\log T-\log 5)+\beta_{Z} Z\right\}
$$



## Simulation study

- Cohort of 5000 people followed for 10 years
- Binary or normally distributed exposure $X$
- Normally distributed covariate $Z: \operatorname{corr}(X, Z)=0.5$


## Hazard model

$$
h(T \mid X, Z)=\lambda \exp \left\{\beta_{X} X+\beta_{X T} X(\log T-\log 5)+\beta_{Z} Z\right\}
$$



- $10 \%$ have the event
- Missing data in 20\% of $X$ and $20 \%$ of $Z$ (MCAR)


## Simulation study

Modelling the time-varying effect

1. Log-time analysis: $\beta_{X}(T)=\beta_{X}+\beta_{X T}\{\log T-\log 5\}$
2. Step function analysis: using 4 time periods

Complete-data analysis
2. Complete-case analysis
3. MI non-time-varying approach: White \& Royston method
4. MI time-varying approach

$$
\begin{aligned}
X= & \alpha_{0}+\alpha_{1} Z+\alpha_{21} D+\alpha_{22} D \log (T)+\alpha_{3} \widehat{H}(T) \\
& +\alpha_{4} \widehat{H}^{(1)}(T)+\alpha_{5} Z \widehat{H}(T)+\alpha_{6} Z \widehat{H}^{(1)}(T)+\varepsilon
\end{aligned}
$$

## Simulation study

## Modelling the time-varying effect

1. Log-time analysis: $\beta_{X}(T)=\beta_{X}+\beta_{X T}\{\log T-\log 5\}$
2. Step function analysis: using 4 time periods

## Analyses performed

1. Complete-data analysis
2. Complete-case analysis
3. MI non-time-varying approach: White \& Royston method
4. MI time-varying approach


## Simulation study

## Modelling the time-varying effect

1. Log-time analysis: $\beta_{X}(T)=\beta_{X}+\beta_{X T}\{\log T-\log 5\}$
2. Step function analysis: using 4 time periods

## Analyses performed

1. Complete-data analysis
2. Complete-case analysis
3. MI non-time-varying approach: White \& Royston method
4. MI time-varying approach

## Imputation model

$$
X=\alpha_{0}+\alpha_{1} Z+\alpha_{21} D+\alpha_{22} D \log (T)+\alpha_{3} \widehat{H}(T)
$$

## Simulation study

## Modelling the time-varying effect

1. Log-time analysis: $\beta_{X}(T)=\beta_{X}+\beta_{X T}\{\log T-\log 5\}$
2. Step function analysis: using 4 time periods

## Analyses performed

1. Complete-data analysis
2. Complete-case analysis
3. MI non-time-varying approach: White \& Royston method
4. MI time-varying approach

## Imputation model

$$
\begin{aligned}
X= & \alpha_{0}+\alpha_{1} Z+\alpha_{21} D+\alpha_{22} D \log (T)+\alpha_{3} \widehat{H}(T) \\
& +\alpha_{4} \widehat{H}^{(1)}(T)
\end{aligned}
$$

## Simulation study

## Modelling the time-varying effect

1. Log-time analysis: $\beta_{X}(T)=\beta_{X}+\beta_{X T}\{\log T-\log 5\}$
2. Step function analysis: using 4 time periods

## Analyses performed

1. Complete-data analysis
2. Complete-case analysis
3. MI non-time-varying approach: White \& Royston method
4. MI time-varying approach

## Imputation model

$$
\begin{aligned}
X= & \alpha_{0}+\alpha_{1} Z+\alpha_{21} D+\alpha_{22} D \log (T)+\alpha_{3} \widehat{H}(T) \\
& +\alpha_{4} \widehat{H}^{(1)}(T)+\alpha_{5} Z \widehat{H}(T)+\alpha_{6} Z \widehat{H}^{(1)}(T)+\varepsilon
\end{aligned}
$$

## Results: Log-time analysis, Normal $X$

| $\beta_{X}=0.5, \beta_{X T}=-0.5$ |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| $\beta_{Z}=0.5$ |  |  |  |  |
| Est |  |  |  |  |
| bias |  |  |  |  |
| eff |  |  |  |  |
| $\beta_{X}$ | 0.501 | 0.001 | 100 |  |
| $\beta_{X T}$ | -0.502 | -0.002 | 100 |  |
| $\beta_{Z}$ | 0.498 | -0.002 | 100 |  |
| Complete case |  |  |  |  |
| $\beta_{X}$ | 0.493 | -0.007 | 63 |  |
| $\beta_{X T}$ | -0.505 | -0.005 | 67 |  |
| $\beta_{Z}$ | 0.502 | 0.002 | 63 |  |
| Time-varying MI |  |  |  |  |
| $\beta_{X}$ | 0.497 | -0.003 | 74 |  |
| $\beta_{X T}$ | -0.506 | -0.006 | 87 |  |
| $\beta_{Z}$ | 0.500 | -0.000 | 76 |  |
| Non-time-varying MI |  |  |  |  |
| $\beta_{X}$ | 0.492 | -0.008 | 75 |  |
| $\beta_{X T}$ | -0.425 | 0.075 | 123 |  |
| $\beta_{Z}$ | 0.500 | 0.000 | 77 |  |



## Results: Log-time analysis, Normal $X$

| $\beta_{X}=0.5, \beta_{X T}=-0.5$ |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| $\beta_{Z}=0.5$ |  |  |  |  |
| Est |  |  |  |  |
| bias |  |  |  |  |
| $\beta_{X}$ | 0.501 | eff |  |  |
| $\beta_{X T}$ | -0.502 | -0.001 | 100 |  |
| $\beta_{Z}$ | 0.498 | -0.002 | 100 |  |
| Complete case |  |  |  |  |
| $\beta_{X}$ | 0.493 | -0.007 | 63 |  |
| $\beta_{X T}$ | -0.505 | -0.005 | 67 |  |
| $\beta_{Z}$ | 0.502 | 0.002 | 63 |  |
| Time-varying MI |  |  |  |  |
| $\beta_{X}$ | 0.497 | -0.003 | 74 |  |
| $\beta_{X T}$ | -0.506 | -0.006 | 87 |  |
| $\beta_{Z}$ | 0.500 | -0.000 | 76 |  |
| Non-time-varying MI |  |  |  |  |
| $\beta_{X}$ | 0.492 | -0.008 | 75 |  |
| $\beta_{X T}$ | -0.425 | 0.075 | 123 |  |
| $\beta_{Z}$ | 0.500 | 0.000 | 77 |  |



## Results: Log-time analysis, Normal $X$

| $\beta_{X}=0.5, \beta_{X T}=-0.5$ |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| $\beta_{Z}=0.5$ |  |  |  |  |
| Est |  |  |  |  |
| Complete data | eff |  |  |  |
| $\beta_{X}$ | 0.501 | 0.001 | 100 |  |
| $\beta_{X T}$ | -0.502 | -0.002 | 100 |  |
| $\beta_{Z}$ | 0.498 | -0.002 | 100 |  |
| Complete case |  |  |  |  |
| $\beta_{X}$ | 0.493 | -0.007 | 63 |  |
| $\beta_{X T}$ | -0.505 | -0.005 | 67 |  |
| $\beta_{Z}$ | 0.502 | 0.002 | 63 |  |
| Time-varying MI |  |  |  |  |
| $\beta_{X}$ | 0.497 | -0.003 | 74 |  |
| $\beta_{X T}$ | -0.506 | -0.006 | 87 |  |
| $\beta_{Z}$ | 0.500 | -0.000 | 76 |  |
| Non-time-varying MI |  |  |  |  |
| $\beta_{X}$ | 0.492 | -0.008 | 75 |  |
| $\beta_{X T}$ | -0.425 | 0.075 | 123 |  |
| $\beta_{Z}$ | 0.500 | 0.000 | 77 |  |



## Results: Log-time analysis, Normal $X$

| $\beta_{X}=0.5, \beta_{X T}=-0.5$ |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| $\beta_{Z}=0.5$ |  |  |  |  |
| Est |  |  |  |  |
| Complete data | eff |  |  |  |
| $\beta_{X}$ | 0.501 | 0.001 | 100 |  |
| $\beta_{X T}$ | -0.502 | -0.002 | 100 |  |
| $\beta_{Z}$ | 0.498 | -0.002 | 100 |  |
| Complete case |  |  |  |  |
| $\beta_{X}$ | 0.493 | -0.007 | 63 |  |
| $\beta_{X T}$ | -0.505 | -0.005 | 67 |  |
| $\beta_{Z}$ | 0.502 | 0.002 | 63 |  |
| Time-varying MI |  |  |  |  |
| $\beta_{X}$ | 0.497 | -0.003 | 74 |  |
| $\beta_{X T}$ | -0.506 | -0.006 | 87 |  |
| $\beta_{Z}$ | 0.500 | -0.000 | 76 |  |
| Non-time-varying MI |  |  |  |  |
| $\beta_{X}$ | 0.492 | -0.008 | 75 |  |
| $\beta_{X T}$ | -0.425 | 0.075 | 123 |  |
| $\beta_{Z}$ | 0.500 | 0.000 | 77 |  |



## Results: Log-time analysis, Normal $X$

| $\beta_{X}=0.5, \beta_{X T}=-0.5$ |  |  |  |  |  |
| :---: | :---: | :---: | ---: | :---: | :---: |
| $\beta_{Z}=0.5$ |  |  |  |  |  |
| Est |  |  |  |  |  |
| bime-varying MI |  |  |  |  | eff |
| $\beta_{X}$ | 0.497 | -0.003 | 74 |  |  |
| $\beta_{X T}$ | -0.506 | -0.006 | 87 |  |  |
| $\beta_{Z}$ | 0.500 | -0.000 | 76 |  |  |
| Time-varying MI: + $\widehat{H}^{(1)}(T) "$ |  |  |  |  |  |
| $\beta_{X}$ | 0.497 | -0.003 | 75 |  |  |
| $\beta_{X T}$ | -0.508 | -0.008 | 86 |  |  |
| $\beta_{Z}$ | 0.499 | -0.001 | 75 |  |  |
| Time-varying MI: + interactions |  |  |  |  |  |
| $\beta_{X}$ | 0.497 | -0.003 | 74 |  |  |
| $\beta_{X T}$ | -0.507 | -0.007 | 86 |  |  |
| $\beta_{Z}$ | 0.500 | 0.000 | 75 |  |  |

## Results: Log-time analysis, Normal $X$

|  | $\begin{gathered} \beta_{X}=0.5, \beta_{X T}=-0.5 \\ \beta_{Z}=0.5 \end{gathered}$ |  |  | $\begin{gathered} \beta_{X}=1.5, \beta_{X T}=-0.5 \\ \beta_{Z}=0.5 \end{gathered}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Est | bias | eff | Est | bias | eff |
| Time-varying MI |  |  |  |  |  |  |
| $\beta_{X}$ | 0.497 | -0.003 | 74 | 1.485 | -0.0 | 75 |
| $\beta_{X T}$ | -0.506 | -0.006 | 87 | -0.506 | -0.006 | 89 |
| $\beta_{Z}$ | 0.500 | -0.000 | 76 | 0.498 | -0.002 | 78 |
| Time-varying MI: + interactions |  |  |  |  |  |  |
| $\beta_{X}$ | 0.497 | -0.003 | 74 | 1.488 | -0.012 | 75 |
| $\beta_{X T}$ | -0.507 | -0.007 | 86 | -0.501 | -0.001 | 88 |
| $\beta_{Z}$ | 0.500 | 0.000 | 75 | 0.500 | 0.000 | 78 |

## Results: Log-time analysis, Normal $X$

|  | 10\% have event |  |  | 30\% have event |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Est | bias | eff | Est | bias | eff |
| Time-varying MI |  |  |  |  |  |  |
| $\beta_{X}$ | 0.497 | -0.003 | 74 | 0.494 | -0.006 | 78 |
| $\beta_{X T}$ | -0.506 | -0.006 | 87 | -0.500 | -0.000 | 87 |
| $\beta_{Z}$ | 0.500 | -0.000 | 76 | 0.502 | 0.002 | 75 |
| Time-varying MI: + interactions |  |  |  |  |  |  |
| $\beta_{X}$ | 0.497 | -0.003 | 74 | 0.496 | -0.004 | 79 |
| $\beta_{X T}$ | -0.507 | -0.007 | 86 | -0.498 | 0.002 | 87 |
| $\beta_{Z}$ | 0.500 | 0.000 | 75 | 0.503 | 0.003 | 76 |

## Results: step function analysis



## Results: step function analysis



## Results: step function analysis



## Results: step function analysis

| Parameter | Est | \% Bias | cov | eff |
| :--- | ---: | ---: | ---: | ---: |
| Complete case |  |  |  |  |
| $\beta_{X 1}$ | 1.116 | -0.005 | 62 |  |
| $\beta_{X 2}$ | 0.650 | -0.005 | 64 |  |
| $\beta_{X 3}$ | 0.376 | -0.009 | 65 |  |
| $\beta_{X 4}$ | 0.214 | -0.010 | 61 |  |
| $\beta_{Z}$ | 0.502 | 0.002 | 63 |  |
| MI: time-varying method |  |  |  |  |
| $\beta_{X 1}$ | 1.121 | -0.001 | 85 |  |
| $\beta_{X 2}$ | 0.648 | -0.007 | 80 |  |
| $\beta_{X 3}$ | 0.379 | -0.006 | 79 |  |
| $\beta_{X 4}$ | 0.218 | -0.006 | 78 |  |
| $\beta_{Z}$ | 0.500 | -0.000 | 76 |  |
| MI: non-time-varying method |  |  |  |  |
| $\beta_{X 1}$ | 1.019 | -0.103 | 110 |  |
| $\beta_{X 2}$ | 0.619 | -0.036 | 102 |  |
| $\beta_{X 3}$ | 0.394 | 0.009 | 98 |  |
| $\beta_{X 4}$ | 0.256 | 0.033 | 95 |  |
| $\beta_{Z}$ | 0.500 | 0.000 | 76 |  |



## Testing the proportional hazards assumption

## Hazard model

Data generated using the hazard model

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X} X+\beta_{X T}(\log T-\log 5) X+\beta_{Z} Z}
$$

with $\beta_{X T}=0$
Percentage of simulations in which the null hypothesis $\beta_{X T}=0$ was rejected:

| Complete data | $5.0 \%$ |
| :--- | :--- |
| Complete case | $5.3 \%$ |
| $\mathrm{MI}:$ time-varying method | $5.3 \%$ |
| $\mathrm{MI}:$ non-timevarying method | $2.2 \%$ |

## Outline

1. Handling missing data on explanatory variables in Cox regression
2. Modelling time-varying effects in Cox regression
3. Derive an imputation model which handles time-varying effects
4. Simulation study
5. An application
6. An alternative approach
7. Further work

## Illustration: Rotterdam breast Cancer Study

- 2982 individuals with primary breast cancer from the Rotterdam tumour bank
- Individuals followed-up for death/disease recurrence (51\%)
- Sauerbrei et al (2007), Royston \& Sauerbrei (2008): time-varying effects of two variables
- tumour size: $\log (T)$
- number of progesterone receptors $(\log (p g r+1)): \log (T)$
- I generated missing data for $20 \%$ of individuals in both variables


## Illustration: Rotterdam breast Cancer Study

- 2982 individuals with primary breast cancer from the Rotterdam tumour bank
- Individuals followed-up for death/disease recurrence (51\%)
- Sauerbrei et al (2007), Royston \& Sauerbrei (2008): time-varying effects of two variables
- tumour size: $\log (T)$
- number of progesterone receptors $(\log (p g r+1)): \log (T)$


## Illustration: Rotterdam breast Cancer Study

- 2982 individuals with primary breast cancer from the Rotterdam tumour bank
- Individuals followed-up for death/disease recurrence (51\%)
- Sauerbrei et al (2007), Royston \& Sauerbrei (2008): time-varying effects of two variables
- tumour size: $\log (T)$
- number of progesterone receptors $(\log (p g r+1)): \log (T)$
- I generated missing data for $20 \%$ of individuals in both variables


## Illustration: Rotterdam Breast Cancer Study



## Illustration: Rotterdam Breast Cancer Study



## Illustration: Rotterdam Breast Cancer Study



## Illustration: Rotterdam Breast Cancer Study




## Another example: Arrest after release from prison

- 432 inmates released from state prison followed up for 1 year (Allison et al (2010))
- Factors associated with re-arrest:
- Age: time-varying effect (linear with time since release)
- Financial aid: step function, with a step 20-30 weeks after release
- Prior arrests: no time-varying effect
- $20 \%$ missingness introduced in age and financial aid


## Another example: Arrest after release from prison




## Another example: Arrest after release from prison




## Another example: Arrest after release from prison




## Another example: Arrest after release from prison




## Another example: Arrest after release from prison




## Outline

1. Handling missing data on explanatory variables in Cox regression
2. Modelling time-varying effects in Cox regression
3. Derive an imputation model which handles time-varying effects
4. Simulation study
5. An application
6. An alternative approach
7. Further work

## Another approach for imputation under the Cox model

- We have focused on an approximate imputation model for $p(X \mid T, D, Z)$
- This does not extend to allowing non-linear terms (e.g. $X^{2}$ ) or interaction terms

| Artic | SMMR |
| :---: | :---: |
|  |  |
| Multiple imputation of covariates |  |
| by fully conditional specificatio | 50:10.1717 |
| Accommodating the substantive model | ©SAGE |

Jonathan W Bartlett, ${ }^{1}$ Shaun R Seaman, ${ }^{2}$
lan R White ${ }^{2}$ and James R Carpenter ${ }^{1,3}$ for the Alzheimer's
Disease Neuroimaging Initiative*

## Another approach for imputation under the Cox model

- We have focused on an approximate imputation model for $p(X \mid T, D, Z)$
- This does not extend to allowing non-linear terms (e.g. $X^{2}$ ) or interaction terms

| Artic | SMMR |
| :---: | :---: |
|  |  |
| Multiple imputation of covariates |  |
| by fully conditional specificatio | 50:10.1717 |
| Accommodating the substantive model | ©SAGE |

Jonathan W Bartlett, ${ }^{1}$ Shaun R Seaman, ${ }^{2}$
lan R White ${ }^{2}$ and James R Carpenter ${ }^{1,3}$ for the Alzheimer's
Disease Neuroimaging Initiative*

## The Bartlett et al. approach

## Aim

- For variable $X$ with missing data and fully-observed variable $Z$
- To impute missing values of $X$ by drawing from the true distribution $p(X \mid T, D, Z)$
- Draw potential values of $X$ from a proposal distribution $p(X \mid Z)$
- Use a reiection rule to decide whether or not to accent the potential imputed values of $X$ as imputed values from the desired distribution $p(X \mid T, D, Z)$


## The Bartlett et al. approach

## Aim

- For variable $X$ with missing data and fully-observed variable $Z$
- To impute missing values of $X$ by drawing from the true distribution $p(X \mid T, D, Z)$

The basic idea...

- Draw potential values of $X$ from a proposal distribution $p(X \mid Z)$
- Use a rejection rule to decide whether or not to accept the potential imputed values of $X$ as imputed values from the desired distribution $p(X \mid T, D, Z)$


## The Bartlett et al. approach

## Aim

- For variable $X$ with missing data and fully-observed variable $Z$
- To impute missing values of $X$ by drawing from the true distribution $p(X \mid T, D, Z)$

The basic idea...

- Draw potential values of $X$ from a proposal distribution $p(X \mid Z)$
- Use a rejection rule to decide whether or not to accept the potential imputed values of $X$ as imputed values from the desired distribution $p(X \mid T, D, Z)$

The method does not currently accommodate time-varying effects of exposures

## Extending the Bartlett et al. approach

Cox proportional hazards model

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X} X+\beta_{Z} Z}
$$

1. Obtain initial estimates for $\beta_{X}, \beta_{Z}$ and their covariance
2. Draw values $\beta_{X}^{(m)}, \beta_{Z}^{(m)}$ from their estimated distribution
3. Fit the proposal distribution $p(X \mid Z)$ and draw parameter values from their estimated joint distribution
4. Draw a value $X^{*}$ from the proposal distribution
5. Draw a value $U \sim \operatorname{Uniform}(0,1)$. Accept the value $X^{*}$ if.


## Extending the Bartlett et al. approach

## Cox proportional hazards model

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X} X+\beta_{Z} Z}
$$

1. Obtain initial estimates for $\beta_{X}, \beta_{Z}$ and their covariance
2. Draw values $\beta_{X}^{(m)}, \beta_{Z}^{(m)}$ from their estimated distribution
3. Fit the proposal distribution $p(X \mid Z)$ and draw parameter values from their estimated joint distribution
4. Draw a value $X^{*}$ from the proposal distr bution
5. Draw a value $U \sim \operatorname{Uniform}(0,1)$. Accept the value $X^{*}$ if


## Extending the Bartlett et al. approach

## Cox proportional hazards model

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X} X+\beta_{Z} Z}
$$

1. Obtain initial estimates for $\beta_{X}, \beta_{Z}$ and their covariance
2. Draw values $\beta_{X}^{(m)}, \beta_{Z}^{(m)}$ from their estimated distribution
3. Fit the proposal distribution $p(X \mid Z)$ and draw parameter values from their estimated joint distribution

## Extending the Bartlett et al. approach

## Cox proportional hazards model

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X} X+\beta_{Z} Z}
$$

1. Obtain initial estimates for $\beta_{X}, \beta_{Z}$ and their covariance
2. Draw values $\beta_{X}^{(m)}, \beta_{Z}^{(m)}$ from their estimated distribution
3. Fit the proposal distribution $p(X \mid Z)$ and draw parameter values from their estimated joint distribution
4. Draw a value $X^{*}$ from the proposal distribution
5. Draw a value $U \sim \operatorname{Uniform}(0,1)$

## Extending the Bartlett et al. approach

## Cox proportional hazards model

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X} X+\beta_{Z} Z}
$$

1. Obtain initial estimates for $\beta_{X}, \beta_{Z}$ and their covariance
2. Draw values $\beta_{X}^{(m)}, \beta_{Z}^{(m)}$ from their estimated distribution
3. Fit the proposal distribution $p(X \mid Z)$ and draw parameter values from their estimated joint distribution
4. Draw a value $X^{*}$ from the proposal distribution
5. Draw a value $U \sim \operatorname{Uniform}(0,1)$. Accept the value $X^{*}$ if...

$$
\begin{cases}U \leq \exp \left\{-H_{0}^{(m)}(T) e^{\left.\beta_{X}^{(m)} X^{*}+\beta_{Z}^{(m)} z\right\}}\right. & \text { if } D=0 \\ U \leq H_{0}^{(m)}(T) \exp \left\{1+\beta_{X}^{(m)} X^{*}+\beta_{Z}^{(m)} Z-H_{0}^{(m)}(T) e^{\beta_{X}^{(m)} X^{*}+\beta_{Z}^{(m)} z}\right\} & \text { if } D=1\end{cases}
$$

## Extending the Bartlett et al. approach

## Cox proportional hazards model

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X} X+\beta_{Z} Z}
$$

$$
\begin{array}{ll}
U \leq \exp \left\{-H_{0}^{(m)}(T) e^{\left.\beta_{X}^{(m)} X^{*}+\beta_{Z}^{(m)} z\right\}}\right. & \text { if } D=0 \\
U \leq H_{0}^{(m)}(T) \exp \left\{1+\beta_{X}^{(m)} X^{*}+\beta_{Z}^{(m)} Z-H_{0}^{(m)}(T) e^{\left.\beta_{X}^{(m)} X^{*}+\beta_{Z}^{(m)} z\right\}}\right. & \text { if } D=1
\end{array}
$$

## Extended Cox model with time-varying effects

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X}(T) X+\beta_{Z} Z}
$$

$$
\begin{aligned}
& U \leq \exp \left\{-\int_{0}^{T} h_{0}(u) e^{\left.\beta_{X}^{(m)} X^{*}+\beta_{Z}^{(m)} Z+\beta_{X T}^{(m)}(u) X^{*} \mathrm{~d} u\right\}}\right. \\
& U \leq h_{0}^{(m)}(T) \exp \left\{1+\beta_{X}^{(m)} X^{*}+\beta_{Z}^{(m)} Z+\beta_{X T}^{(m)}(T) X^{*}-\int_{0}^{T} h_{0}(u) e^{\beta_{X}^{(m)} X^{*}+\beta_{Z}^{(m)} Z+\beta_{X T}^{(m)}(u) X^{*}} \mathrm{~d} u\right\}
\end{aligned}
$$

- The standard approach can be applied in R and Stata using Jonathan Bartlett's package smcfcs


## Extending the Bartlett et al. approach

## Cox proportional hazards model

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X} X+\beta_{Z} Z}
$$

$$
\begin{array}{ll}
U \leq \exp \left\{-H_{0}^{(m)}(T) e^{\left.\beta_{X}^{(m)} X^{*}+\beta_{Z}^{(m)} z\right\}}\right. & \text { if } D=0 \\
U \leq H_{0}^{(m)}(T) \exp \left\{1+\beta_{X}^{(m)} X^{*}+\beta_{Z}^{(m)} Z-H_{0}^{(m)}(T) e^{\beta_{X}^{(m)} X^{*}+\beta_{Z}^{(m)} z}\right\} & \text { if } D=1
\end{array}
$$

## Extended Cox model with time-varying effects

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X}(T) X+\beta_{Z} Z}
$$

$$
\begin{aligned}
& U \leq \exp \left\{-\int_{0}^{T} h_{0}(u) e^{\beta_{X}^{(m)} X^{*}+\beta_{Z}^{(m)} Z+\beta_{X T}^{(m)}(u) X^{*}} \mathrm{~d} u\right\} \\
& U \leq h_{0}^{(m)}(T) \exp \left\{1+\beta_{X}^{(m)} X^{*}+\beta_{Z}^{(m)} Z+\beta_{X T}^{(m)}(T) X^{*}-\int_{0}^{T} h_{0}(u) e^{\beta_{X}^{(m)} X^{*}+\beta_{Z}^{(m)} Z+\beta_{X T}^{(m)}(u) X^{*}} \mathrm{~d} u\right\}
\end{aligned}
$$

- The standard approach can be applied in R and Stata using Jonathan Bartlett's package smcfcs


## Extending the Bartlett et al. approach: Some results

## Extended Cox model with time-varying effects

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X} X+\beta_{X T} \log (T) X+\beta_{Z} Z}
$$

- I simulated data for binary $X$ and continuous $Z$
- Missing data on $X$ were generated for $20 \%$ of individuals

|  | $\beta_{X}$ | $\beta_{X T}$ | $\beta_{Z}$ |
| :--- | :--- | :--- | :--- |
| Complete data | $0.47(0.32)$ | $-0.53(0.18)$ | $0.51(0.30)$ |
| Complete case | $0.46(0.36)$ | $-0.55(0.22)$ | $0.44(0.34)$ |
| MI: non-time-varying | $0.57(0.34)$ | $-0.42(0.15)$ | $0.51(0.31)$ |
| MI: Approx method | $0.46(0.36)$ | $-0.54(0.21)$ | $0.51(0.31)$ |
| MI: Extended Bartlett | $0.47(0.31)$ | $-0.53(0.18)$ | $0.51(0.30)$ |

## Outline

1. Handling missing data on explanatory variables in Cox regression
2. Modelling time-varying effects in Cox regression
3. Derive an imputation model which handles time-varying effects
4. Simulation study
5. An application
6. An alternative approach
7. Further work

## Allowing a flexible functional form

- Everything so far requires us to specify the functional form for the time-varying effects $\beta_{X}(T)$
- An alternative is to somehow select a 'best' functional form
- Sauerbrei et al. (2007), Royston \& Sauerbrei (2008): Using fractional polynomials to model time-varying effects



## Allowing a flexible functional form

## Extended Cox model with time-varying effects

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X}(T) X+\beta_{Z} Z}
$$

Using a fractional polynomial of degree 1

$$
\beta_{X}(T)=\beta_{X 0}+\beta_{X 1} T^{p}
$$

The best power $p$ is selected from set $\{-2,-1,-0.5,0,0.5,1,2,3\}$
Aim

- Incorporate MI within this approach
- By allowing accommodating a flexible functional form for $\beta_{X}(T)$ in the imputation model
- By selecting the best fitting FP using the imputed data sets


## Allowing a flexible functional form

## Extended Cox model with time-varying effects

$$
h(T \mid X, Z)=h_{0}(T) e^{\beta_{X}(T) X+\beta_{Z} Z}
$$

Using a fractional polynomial of degree 1

$$
\beta_{X}(T)=\beta_{X 0}+\beta_{X 1} T^{p}
$$

The best power $p$ is selected from set $\{-2,-1,-0.5,0,0.5,1,2,3\}$
Aim

- Incorporate MI within this approach
- By allowing accommodating a flexible functional form for $\beta_{X}(T)$ in the imputation model
- By selecting the best fitting FP using the imputed data sets


## Allowing a flexible functional form

Statistics<br>Research Article

# Combining fractional polynomial model building with multiple imputation 

Tim P. Morris, ${ }^{\text {a,b* }}{ }^{\dagger}$ Ian R. White, ${ }^{\text {c }}$ James R. Carpenter, ${ }^{\text {a,b }}$ Simon J. Stanworth ${ }^{\text {d }}$ and Patrick Royston ${ }^{\text {a }}$

## Summary comments

- We should incorporate time-varying effects into the imputation model to get unbiased estimates of time-varying effects
- ... and correct tests for proportional hazards
- The approximate approach can be easily applied in standard software and works well in many circumstances
- The extended Bartlett et al. approach has advantages in some situations
- ...it also allows for nonlinear terms e.g. $X^{2}$
- We aim to show how these methods can be used in conjunction with model selection and fractional polynomials


## Summary comments

- We should incorporate time-varying effects into the imputation model to get unbiased estimates of time-varying effects
- ... and correct tests for proportional hazards
- The approximate approach can be easily applied in standard software and works well in many circumstances
- The extended Bartlett et al. approach has advantages in some situations
- ...it also allows for nonlinear terms e.g. $X^{2}$
- We aim to show how these methods can be used in conjunction with model selection and fractional polynomials


## Summary comments

- We should incorporate time-varying effects into the imputation model to get unbiased estimates of time-varying effects
- ... and correct tests for proportional hazards
- The approximate approach can be easily applied in standard software and works well in many circumstances
- The extended Bartlett et al. approach has advantages in some situations
- ...it also allows for nonlinear terms e.g. $X^{2}$
- We aim to show how these methods can be used in conjunction with model selection and fractional polynomials


## Summary comments

- We should incorporate time-varying effects into the imputation model to get unbiased estimates of time-varying effects
- ... and correct tests for proportional hazards
- The approximate approach can be easily applied in standard software and works well in many circumstances
- The extended Bartlett et al. approach has advantages in some situations
- ...it also allows for nonlinear terms e.g. $X^{2}$
- We aim to show how these methods can be used in conjunction with model selection and fractional polynomials


## Thanks

For comments on this work
Ian White, Mike Kenward, Tim Morris, Jonathan Bartlett

Funding
MRC Methodology Fellowship

